

Fig. 1

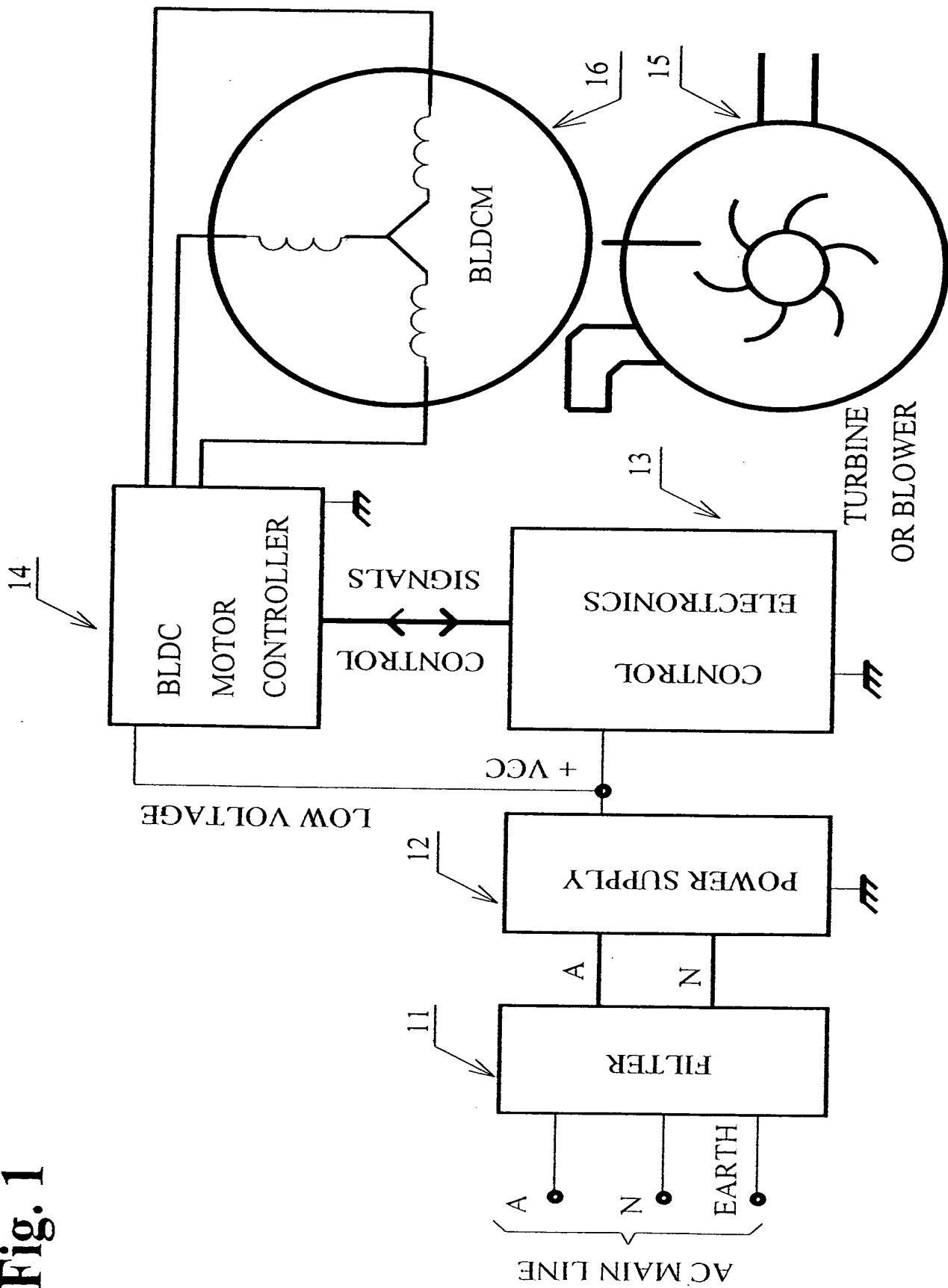


Fig. 2

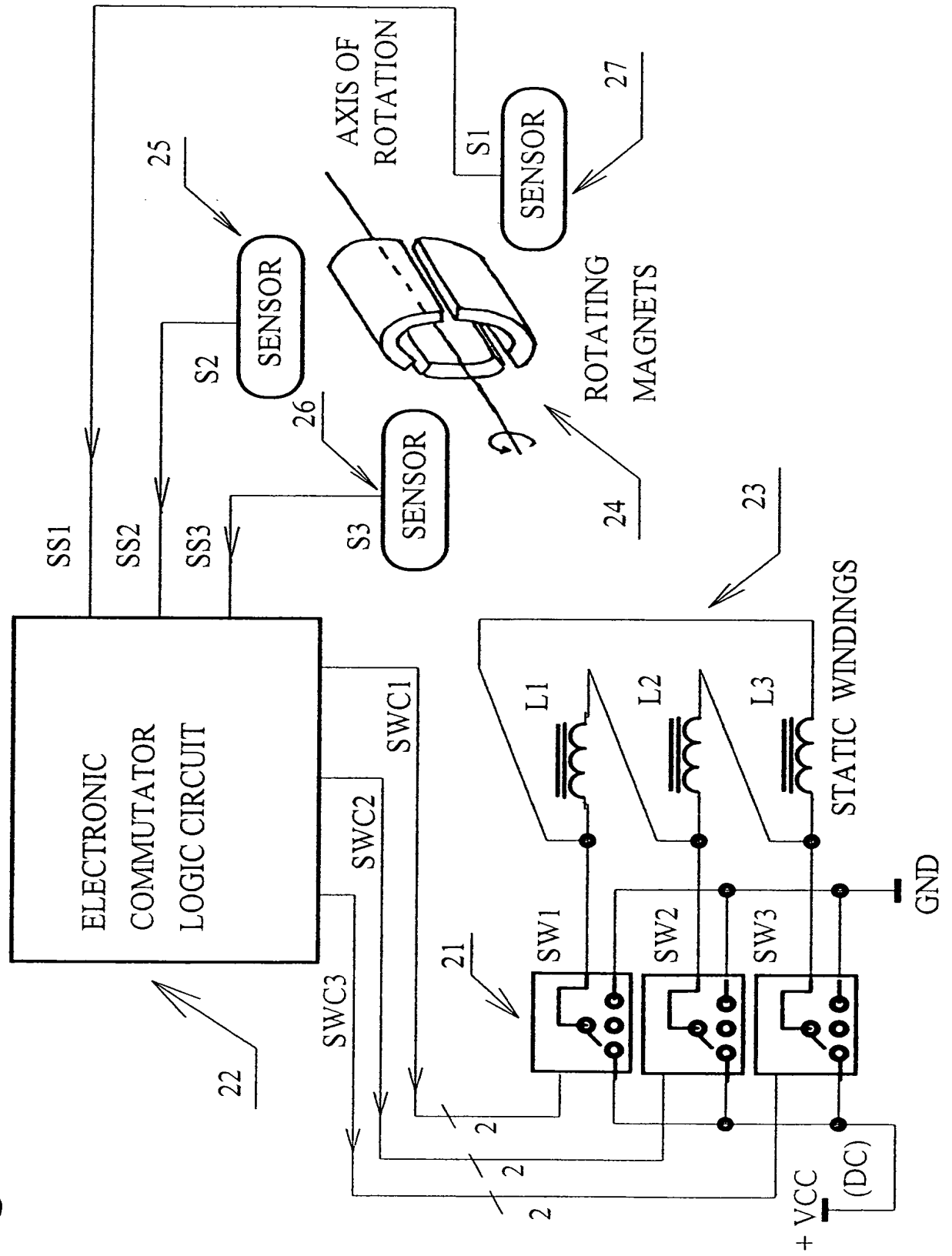
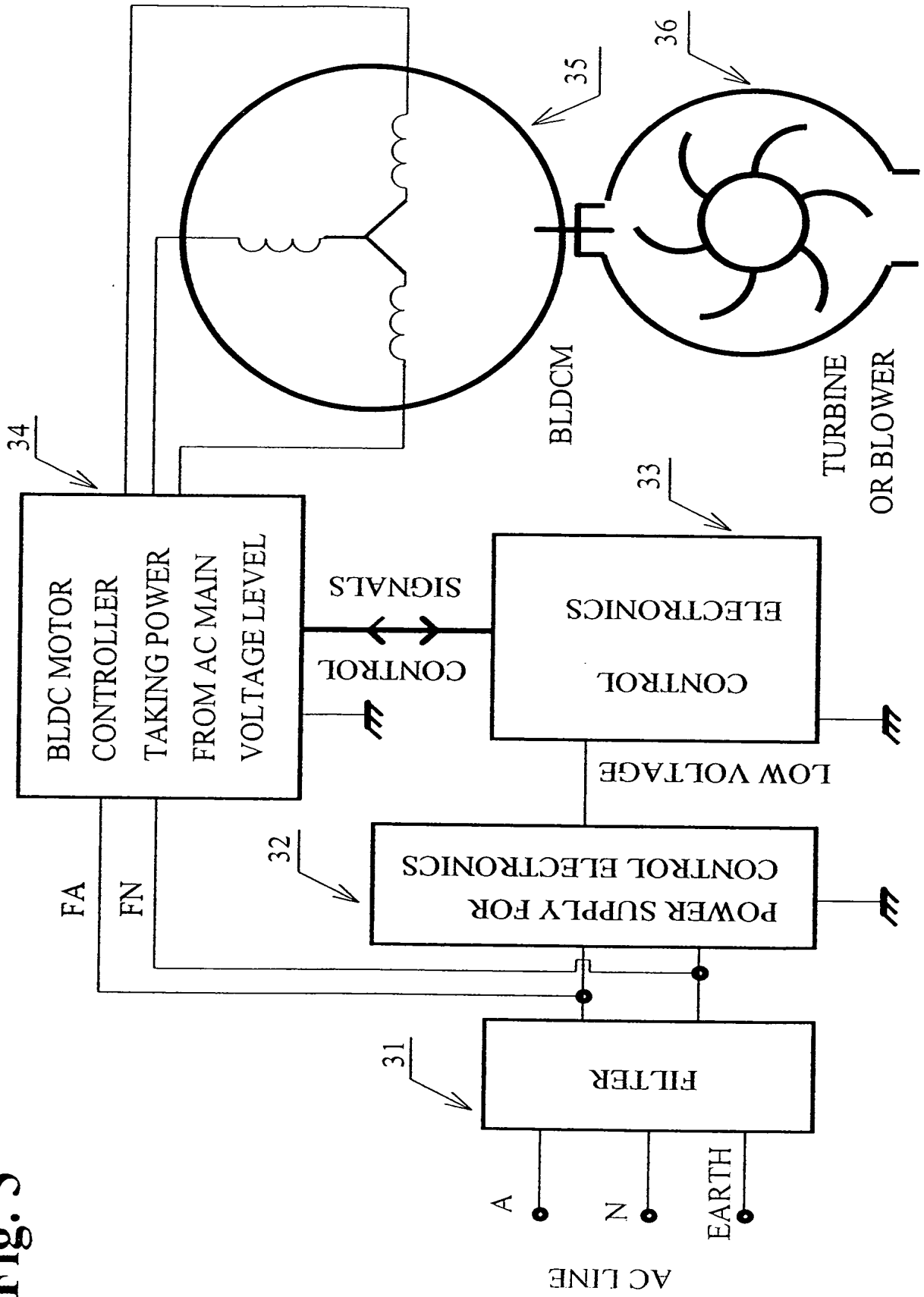
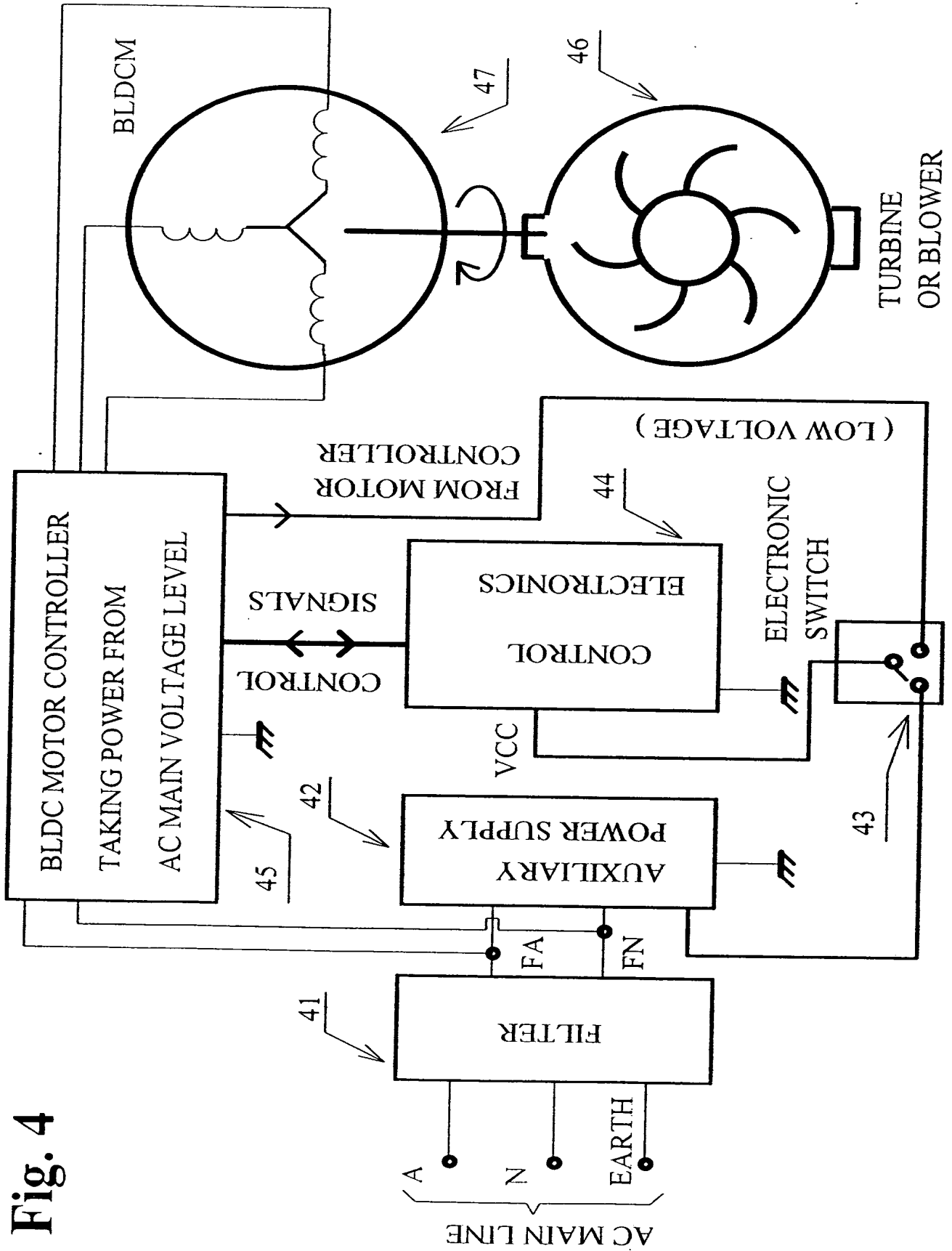


Fig. 3





**Fig. 5**

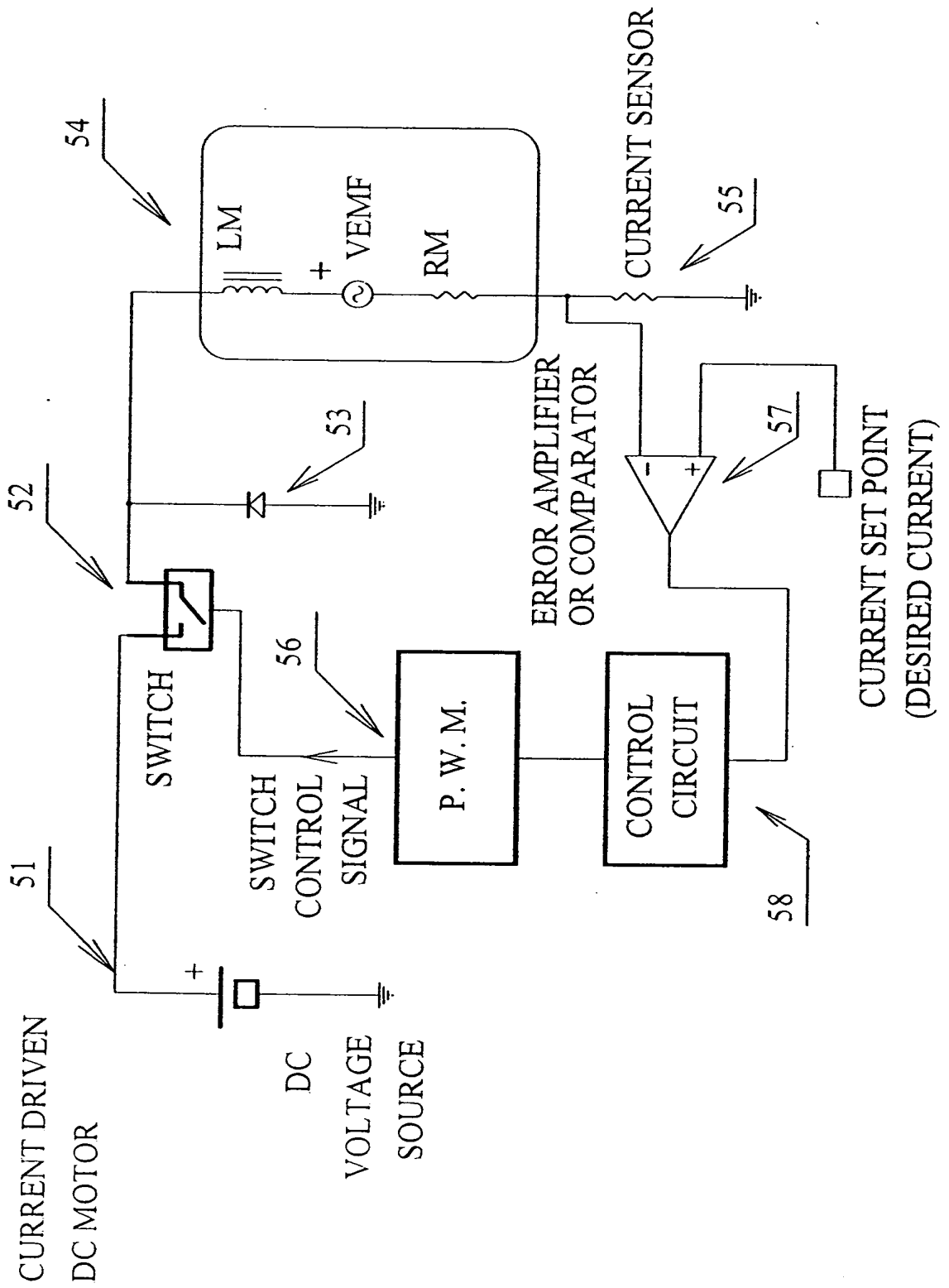


Fig. 6

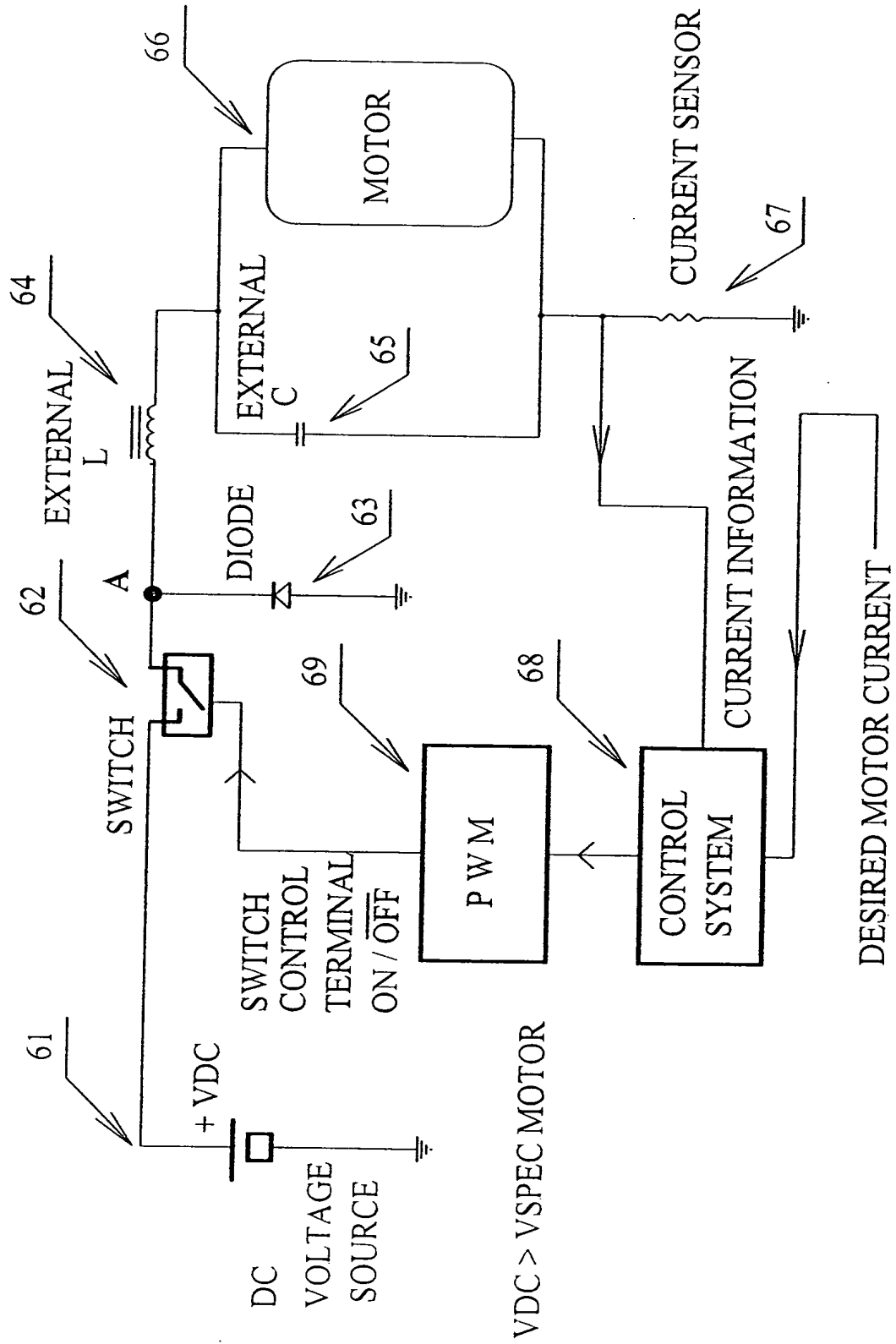
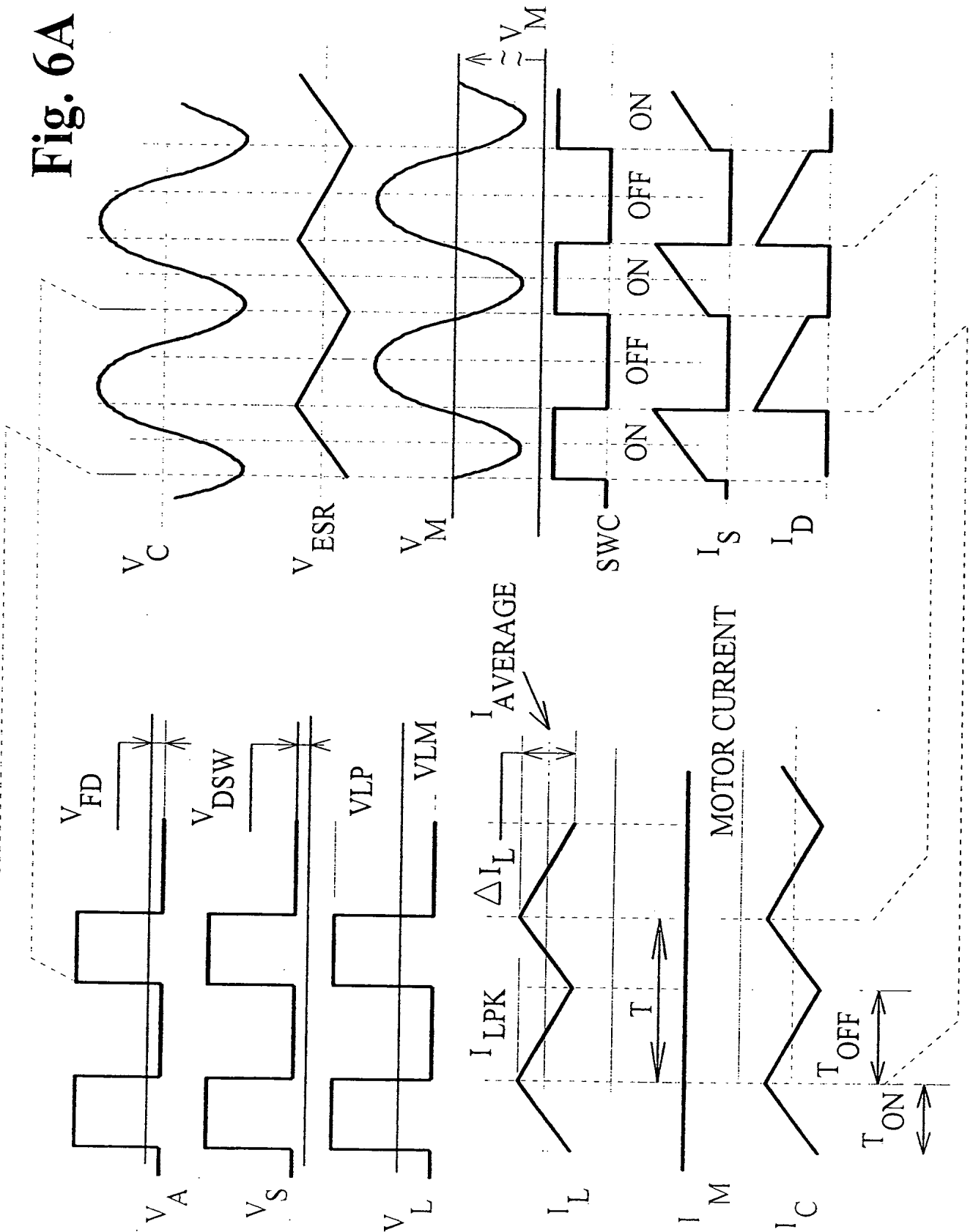


Fig. 6A



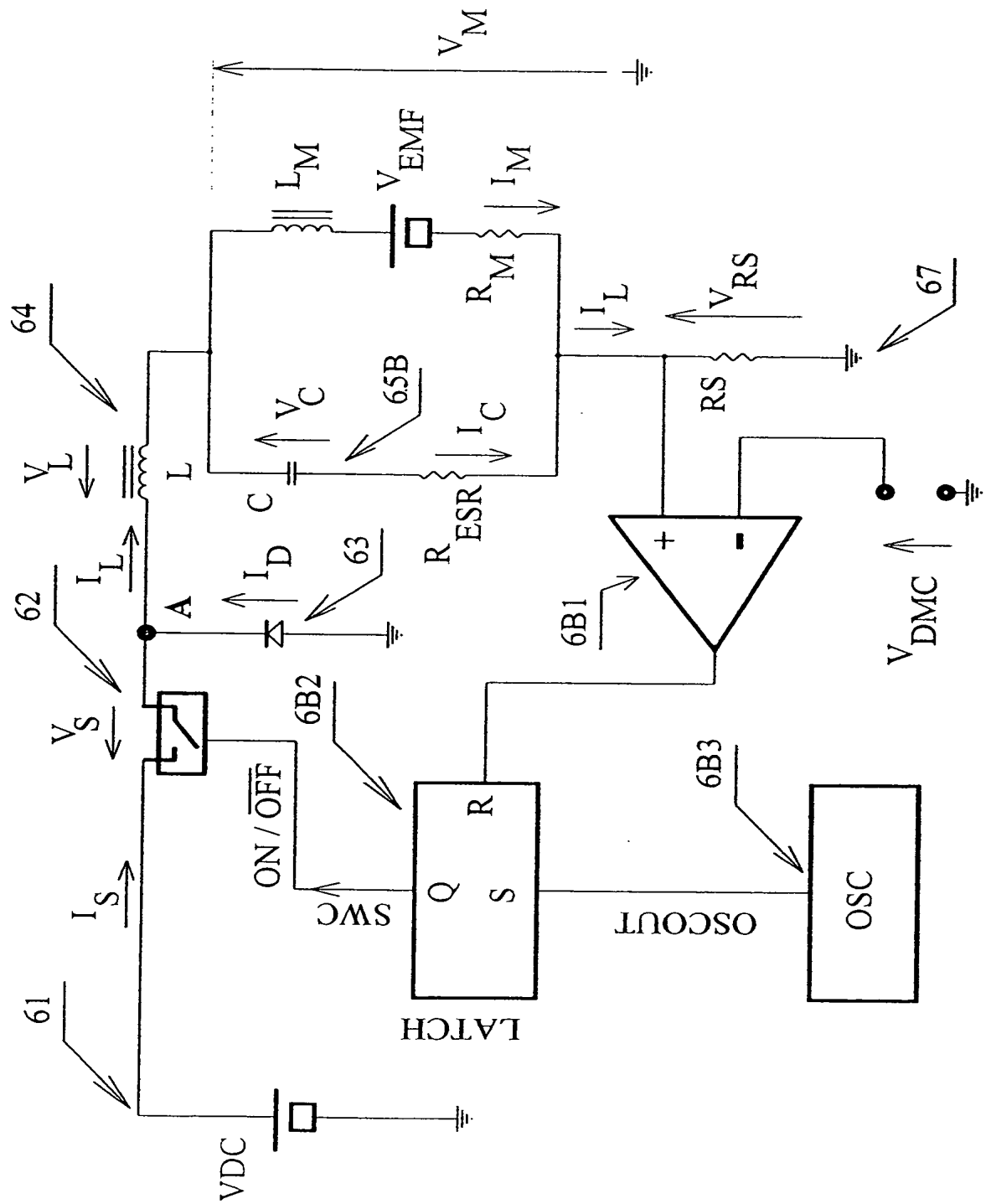
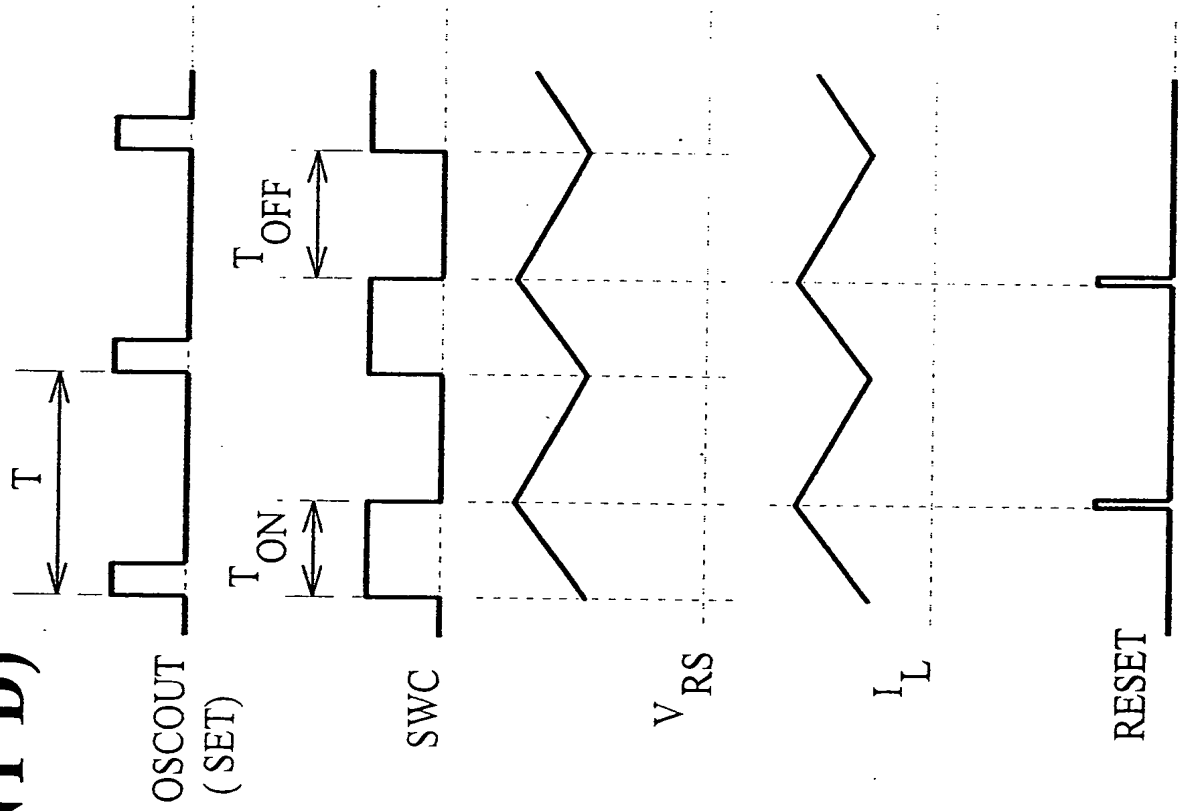




Fig. 6B (CONT'D)



- 1)  $V_S = V_{DC} - V_A$
- 2)  $V_L = V_A - V_M$
- 3)  $V_M \cong I_M \cdot R_M + V_{emf}$
- 4)  $V_{emf} = K_v \cdot \omega_M$
- 5)  $I_S = I_L$
- 6)  $I_L = I_C + I_M$
- 7)  $I_L = V_{RS} / R_S$
- 8)  $V_M = V_C + I_C \cdot R_{ESR}$
- 9)  $T = T_{ON} + T_{OFF}$
- 10)  $I_L = I_{AVERAGE} + I_L(t)$
- 11)  $I_{LPK} = I_{AVERAGE} + ( \Delta I_L / 2 )$
- 12)  $I_{LMIN} = I_{AVERAGE} - ( \Delta I_L / 2 )$
- 13)  $I_M = I_{AVERAGE}$
- 14)  $I_C = I_L(t)$
- 15) 
$$I_L(t) = \frac{1}{L} \int V_L(t) dt$$
- 16) 
$$I_L = \frac{V_L}{L} t = \frac{V_A - V_M}{L} t$$
- 17) 
$$I_L = \frac{V_{DC} - V_S - V_M}{L} t$$

**FIG. 6C-1**

$$18) \quad \Delta I_L = \frac{V_{DC} - V_S - V_M}{L} T_{ON}$$

$$19) \quad |\Delta I_L| = \frac{V_M + V_{FD}}{L} T_{OFF}$$

$$20) \quad T_{ON} \frac{V_{DC} - V_S - V_M}{L} = \frac{V_M + V_{FD}}{L} T_{OFF}$$

$$21) \quad T_{ON} (V_{DC} - V_M) \cong V_M T_{OFF}$$

$$22) \quad V_M \cong V_{DC} \frac{T_{ON}}{T_{ON} + T_{OFF}} = V_{DC} \frac{T_{ON}}{T}$$

$$23) \quad \Delta Q = \frac{1}{2} \frac{T}{2} \frac{\Delta I_L}{2}$$

$$24) \quad \Delta V_{CC} = \frac{\Delta Q}{C} = \frac{\Delta I_L}{f \cdot 8 \cdot C}$$

$$25) \quad \Delta V_C = \Delta V_{CC} + \Delta I_L R_{ESR}$$

$$26) \quad \Delta V_C \ll V_M$$

**FIG. 6C-2**

Fig. 6C-2 (CONT'D)

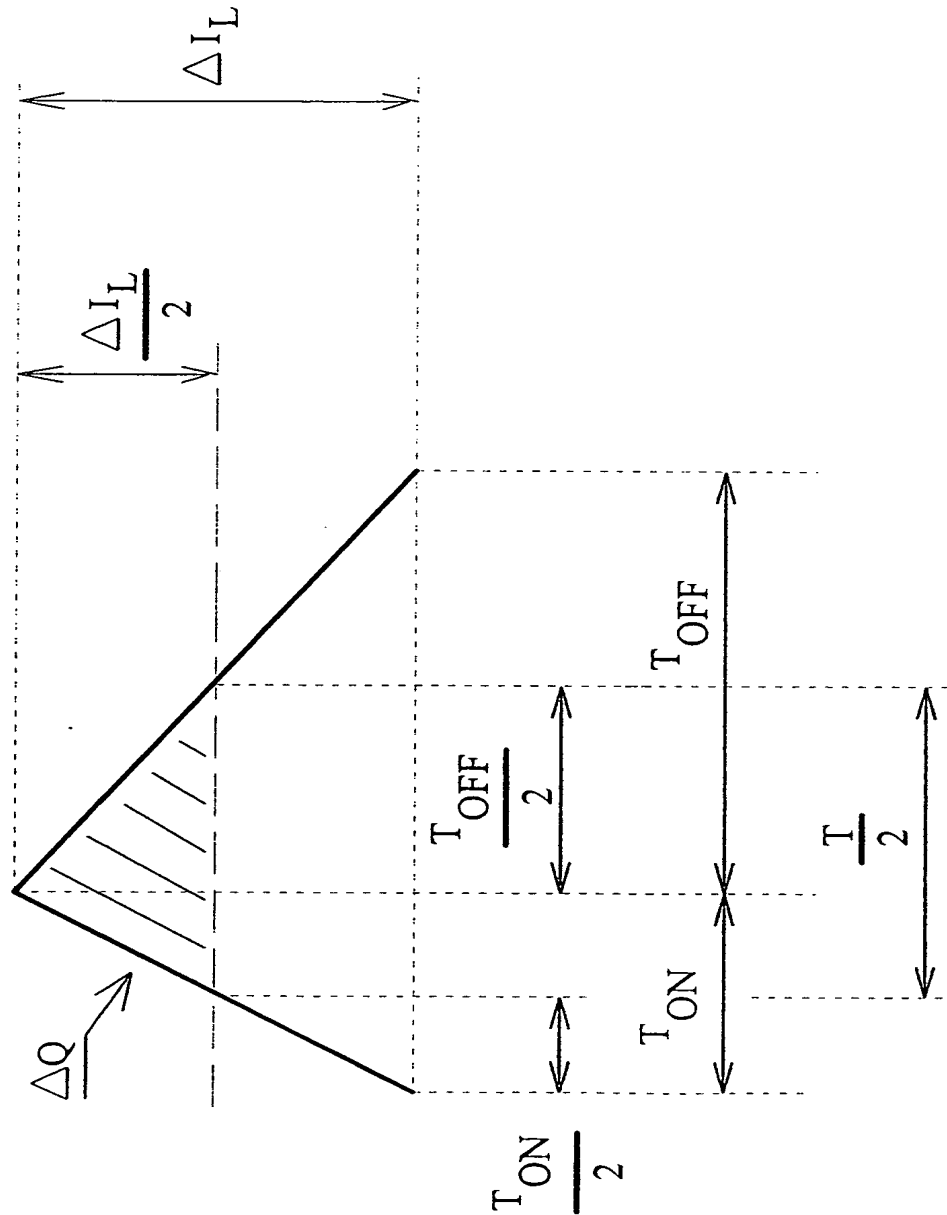
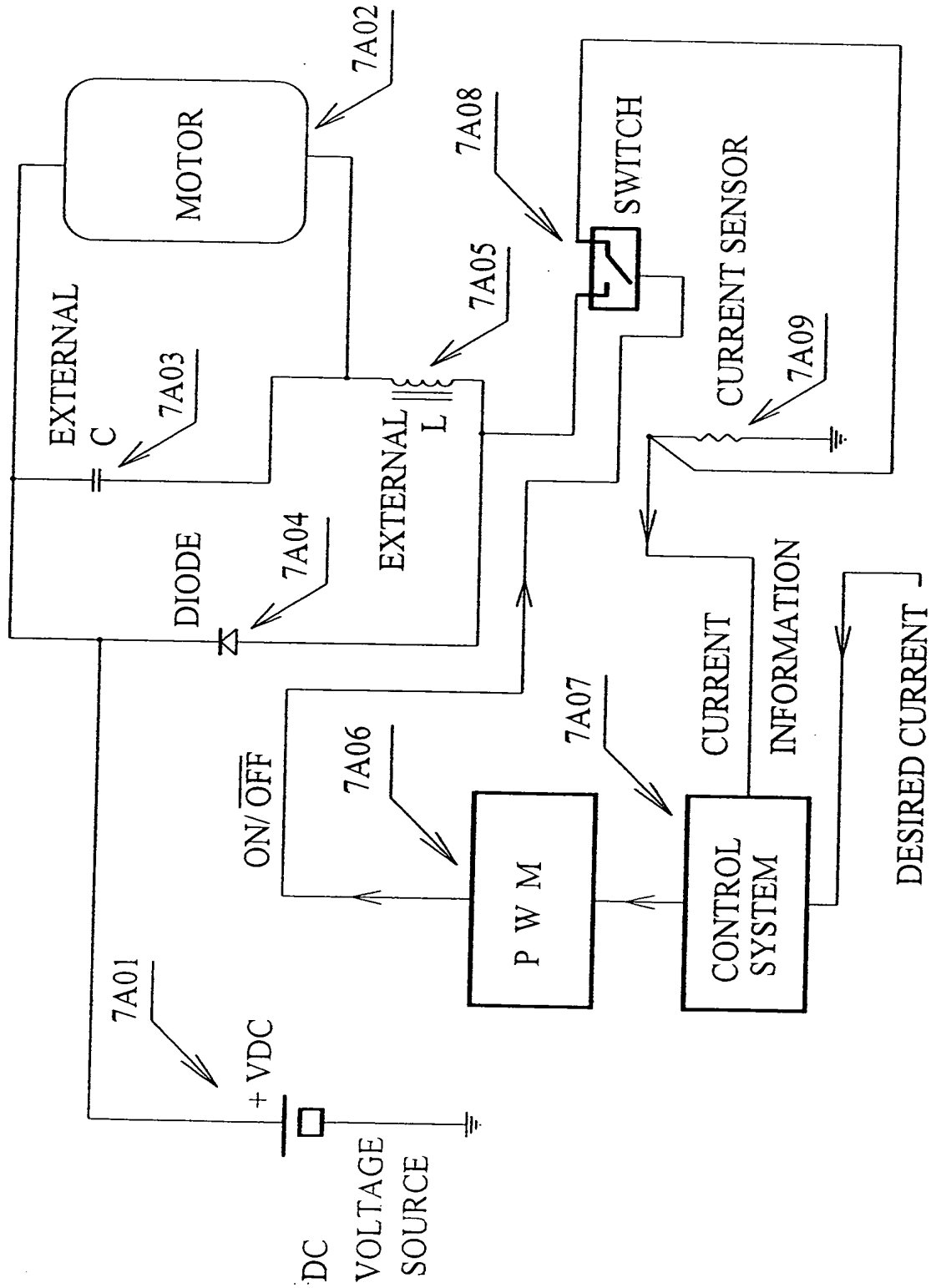
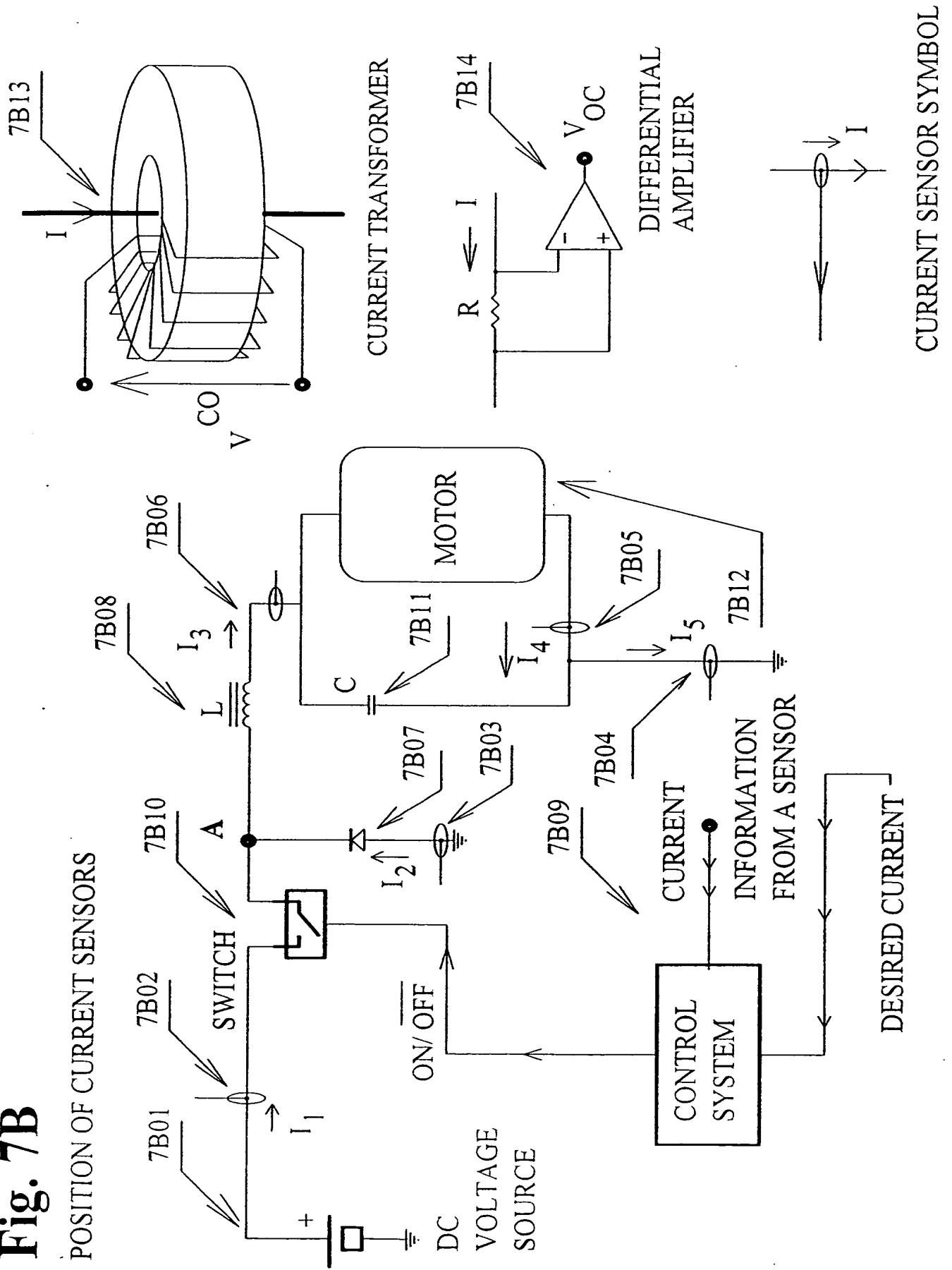


Fig. 7A



**Fig. 7B**

POSITION OF CURRENT SENSORS



**Fig. 7C**

WITH SYNCHRONOUS RECTIFICATION

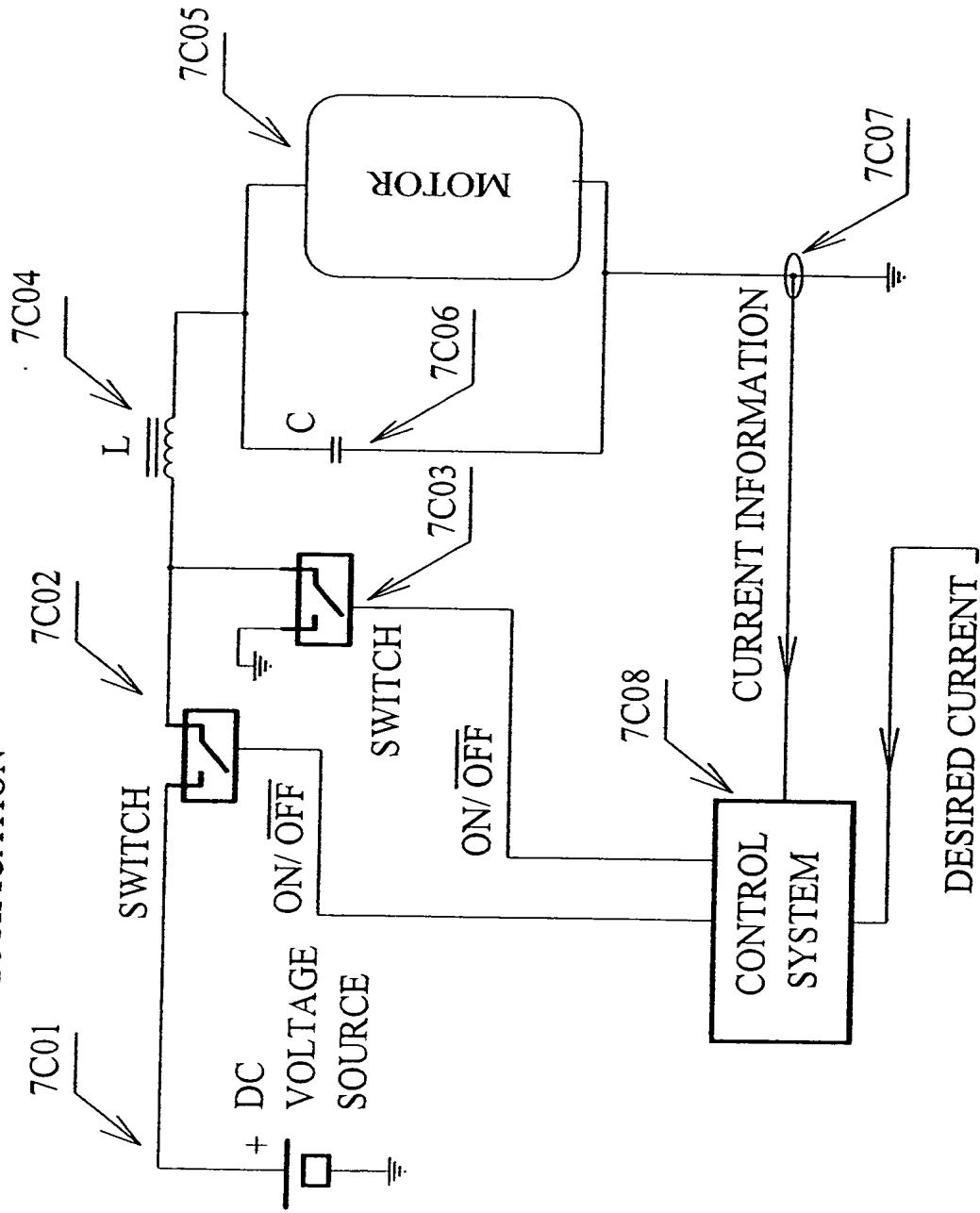


Fig. 7D

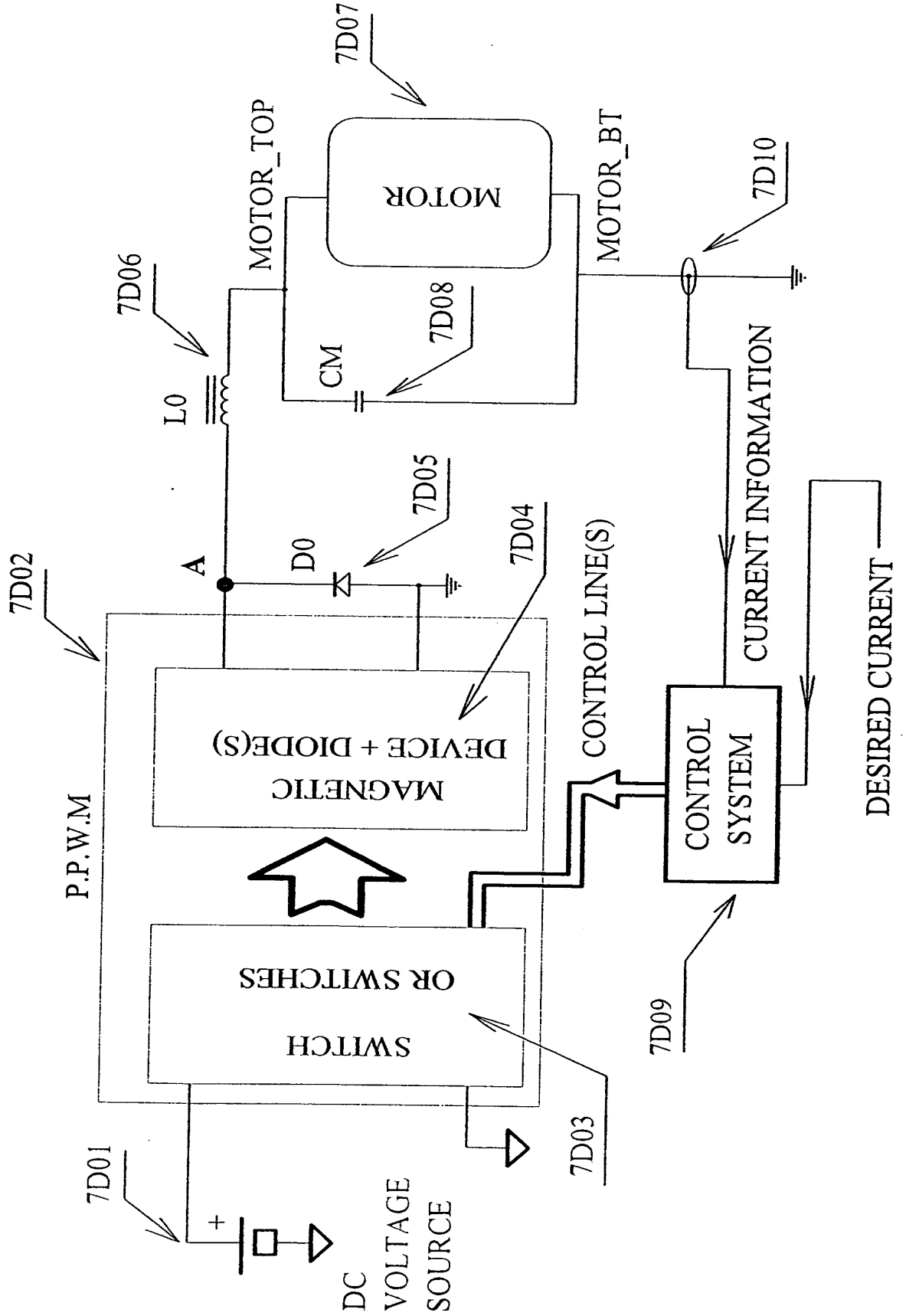
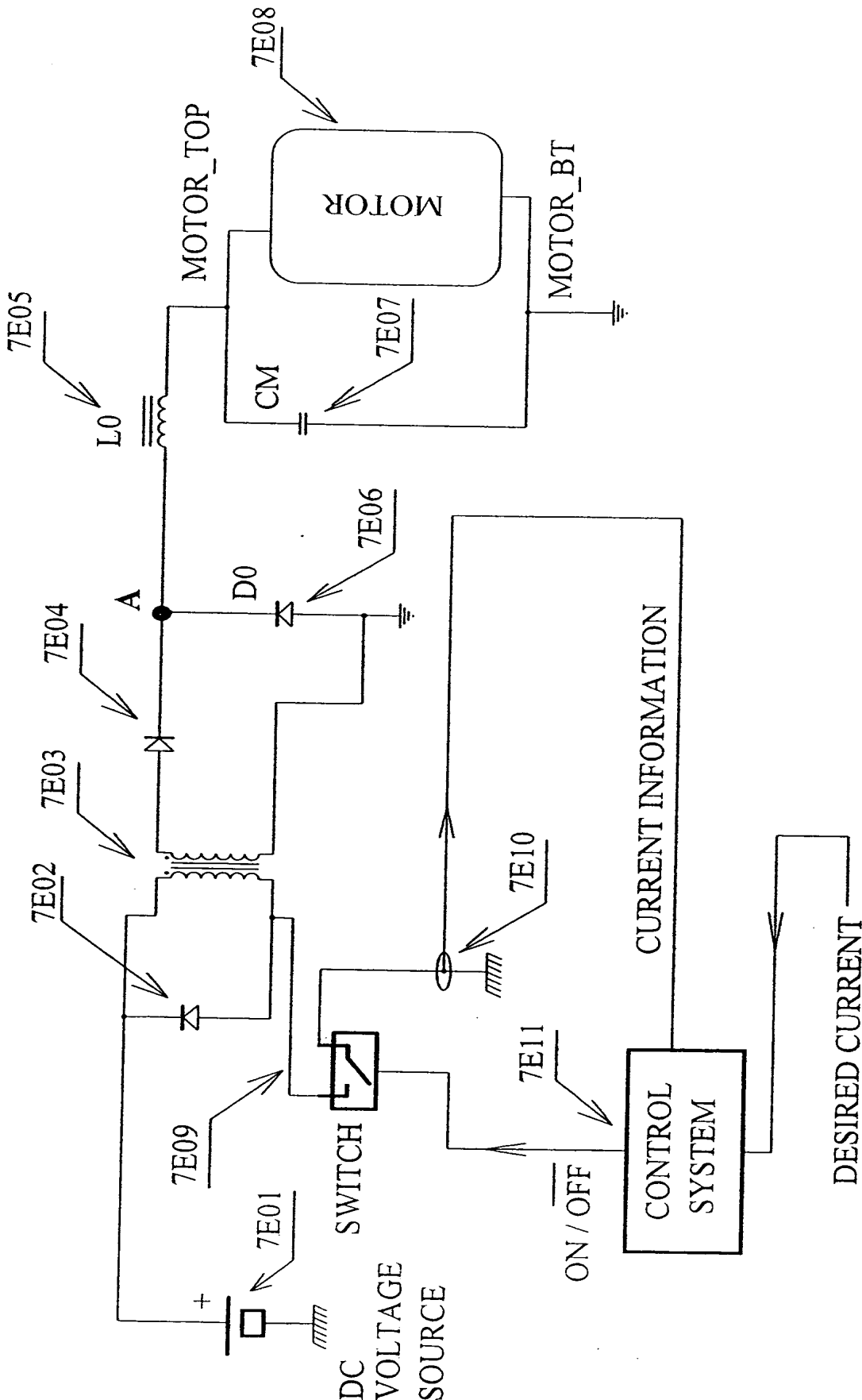
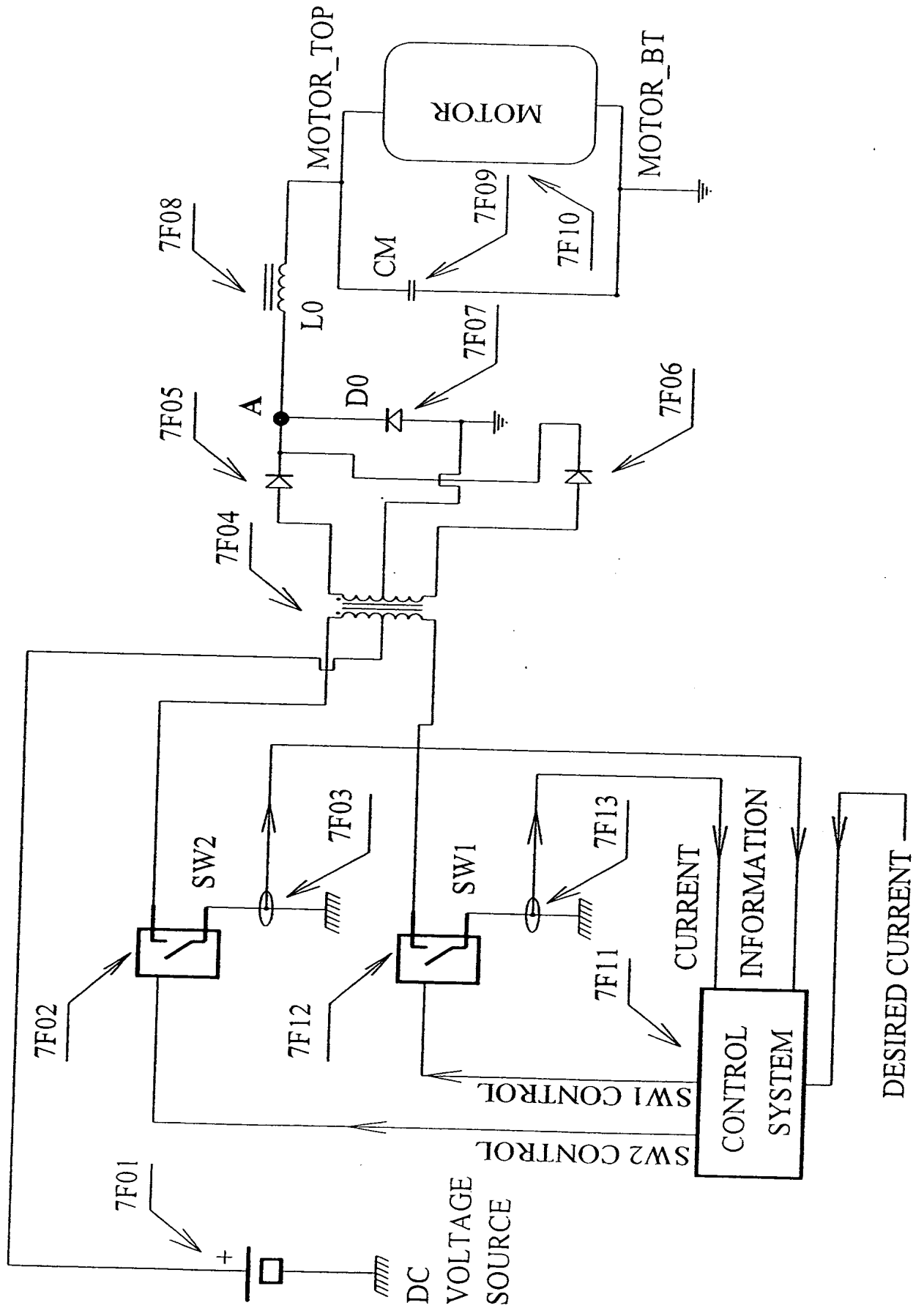




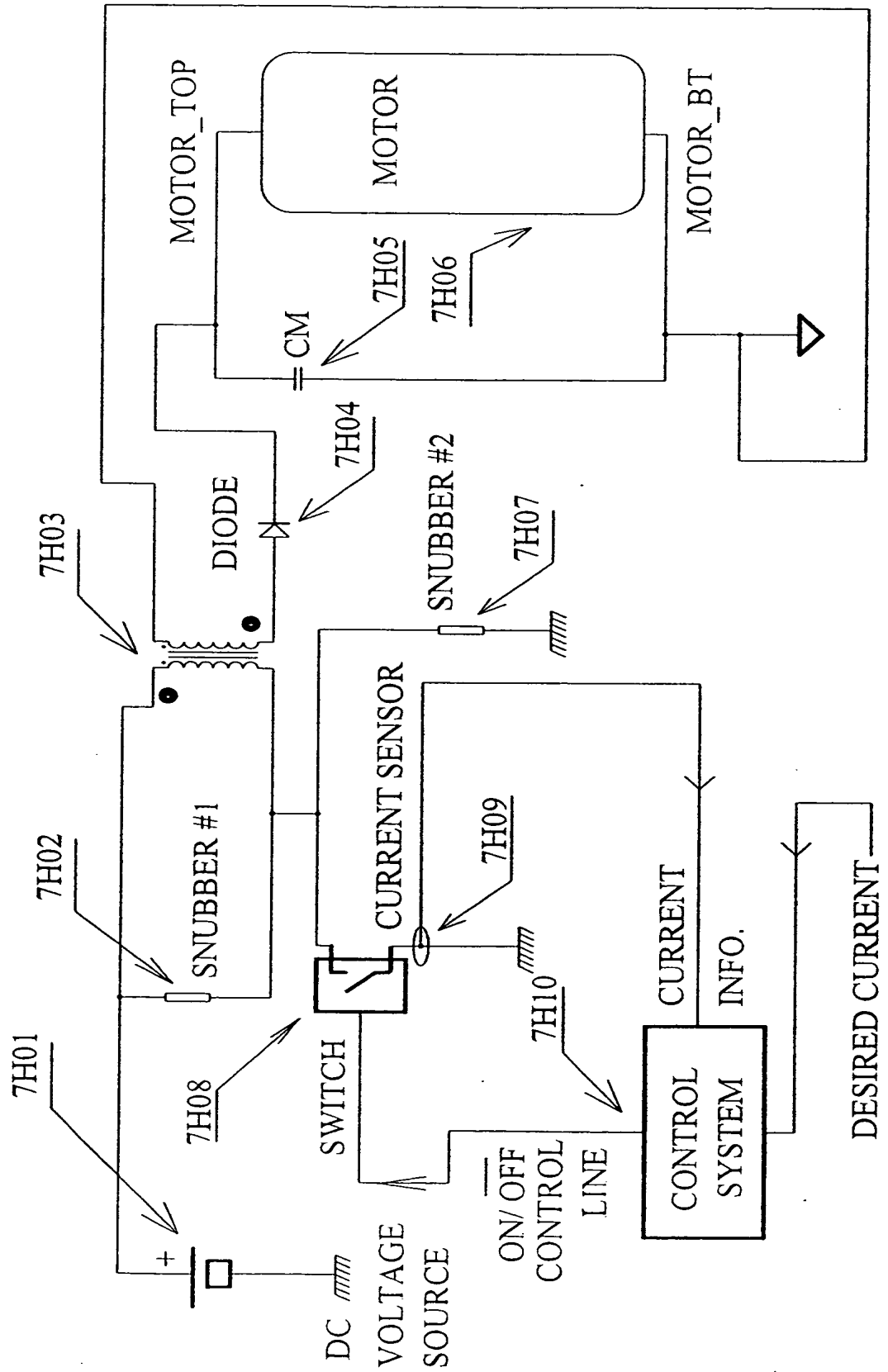
Fig. 7E

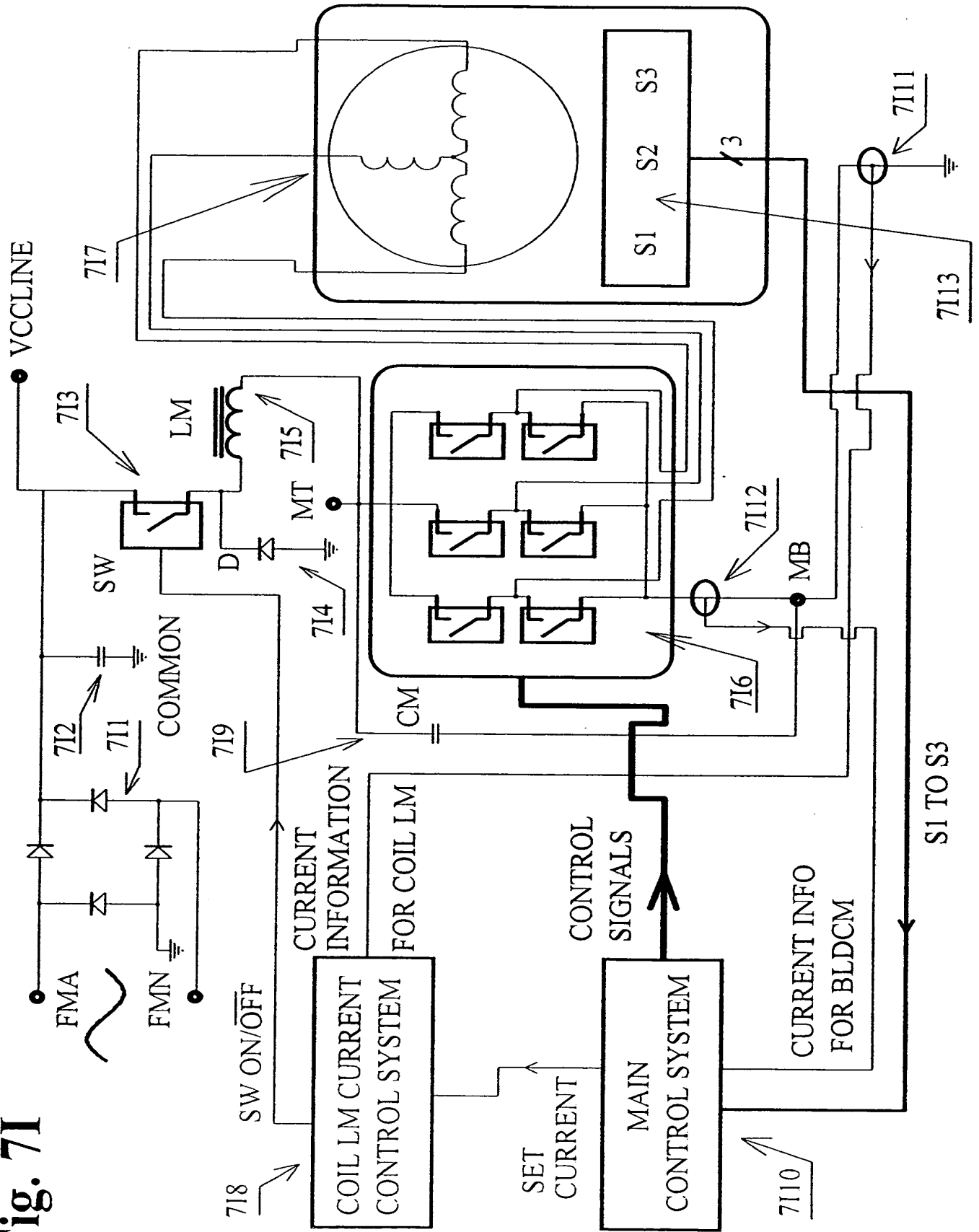




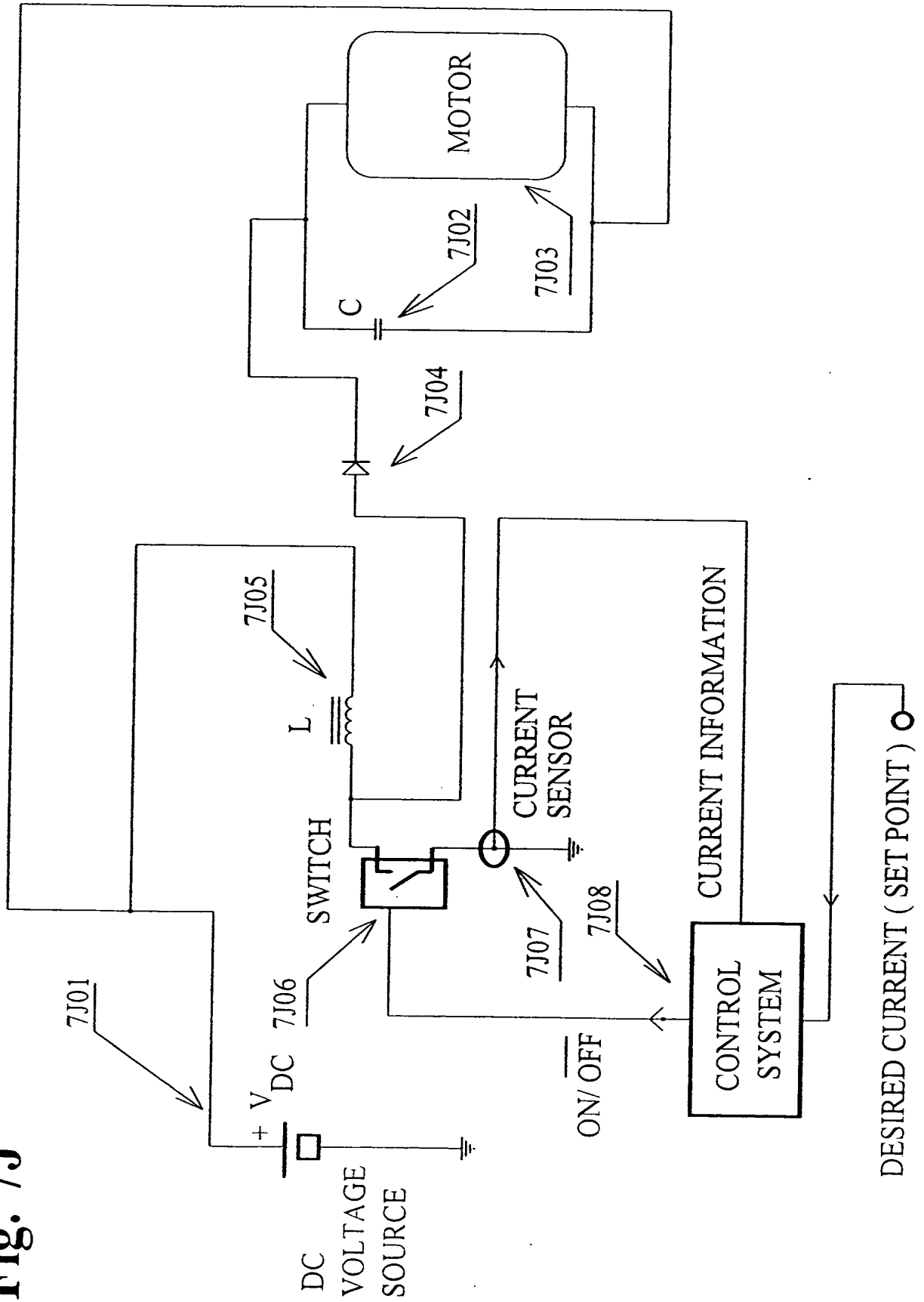


**Fig. 7H**





**Fig. 7J**



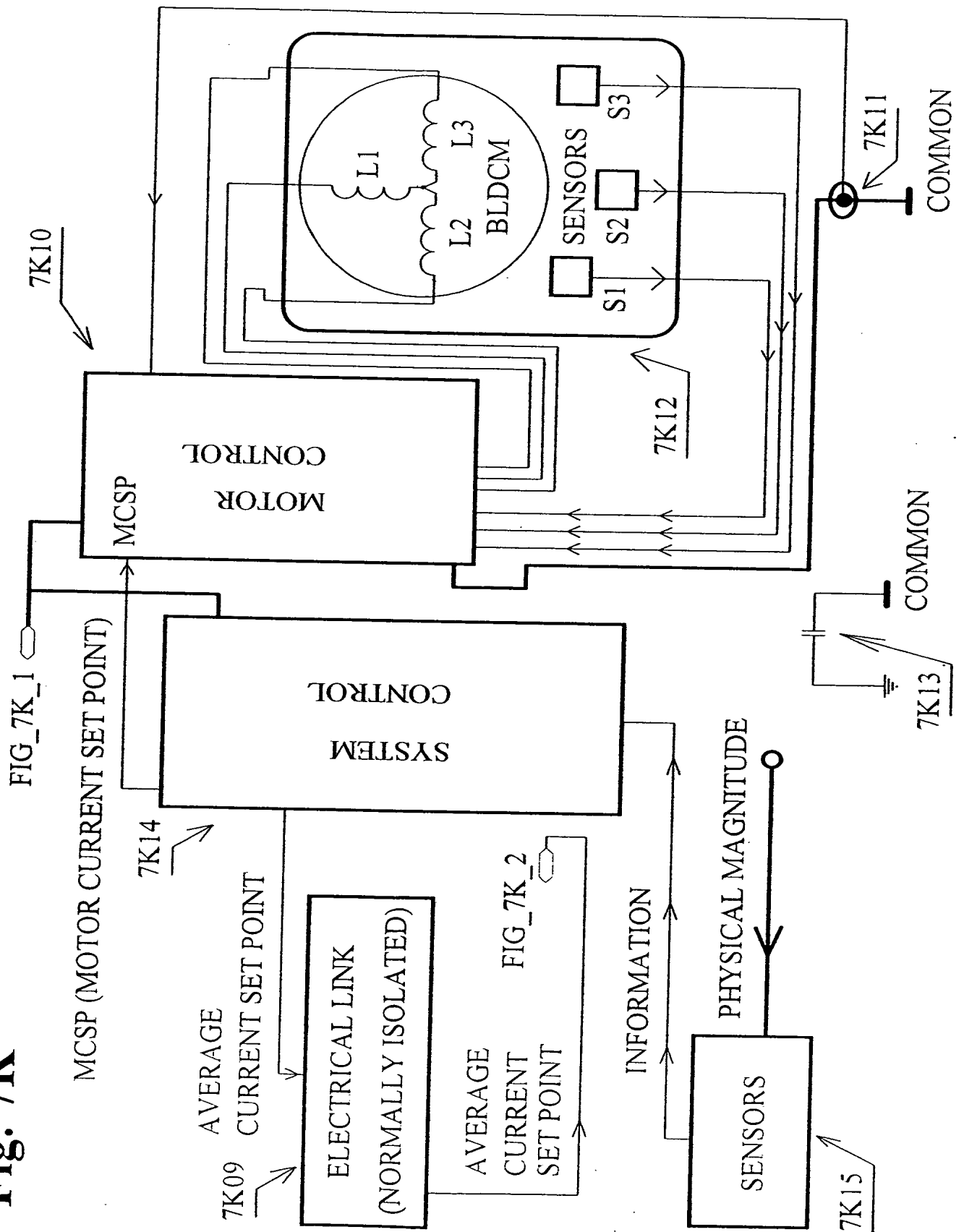


Fig. 7K (CONT'D)

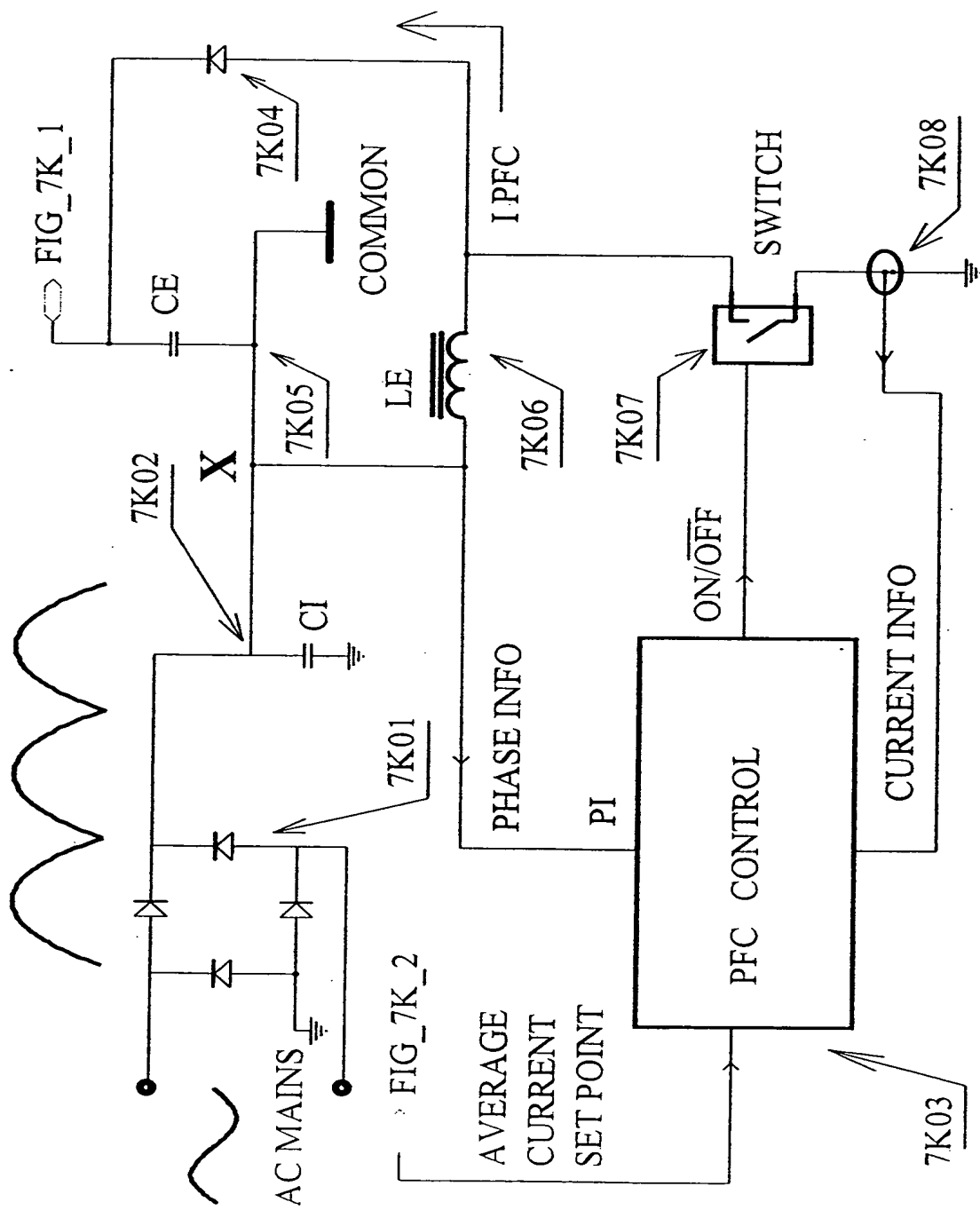
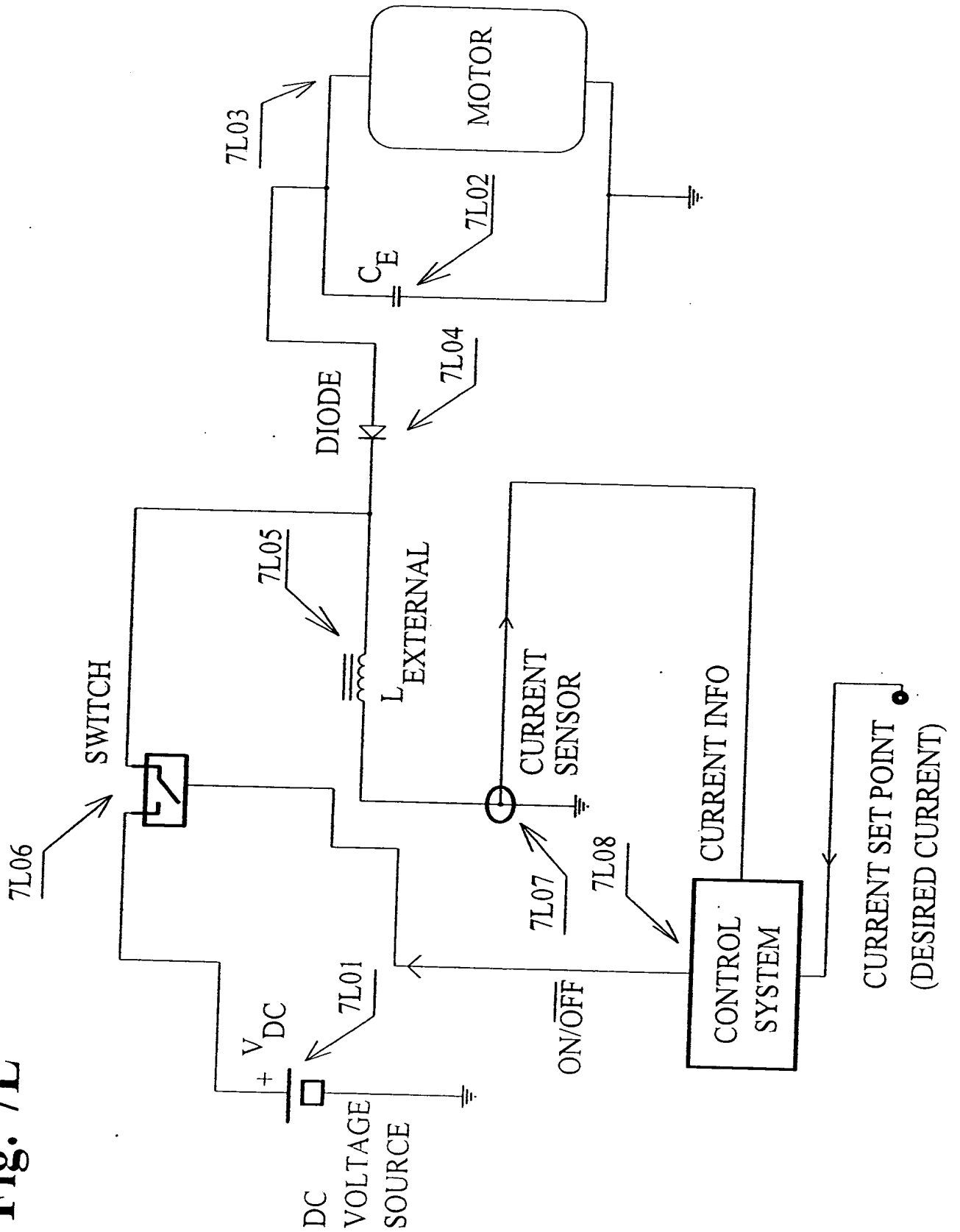




Fig. 7L



**Fig. 8A**

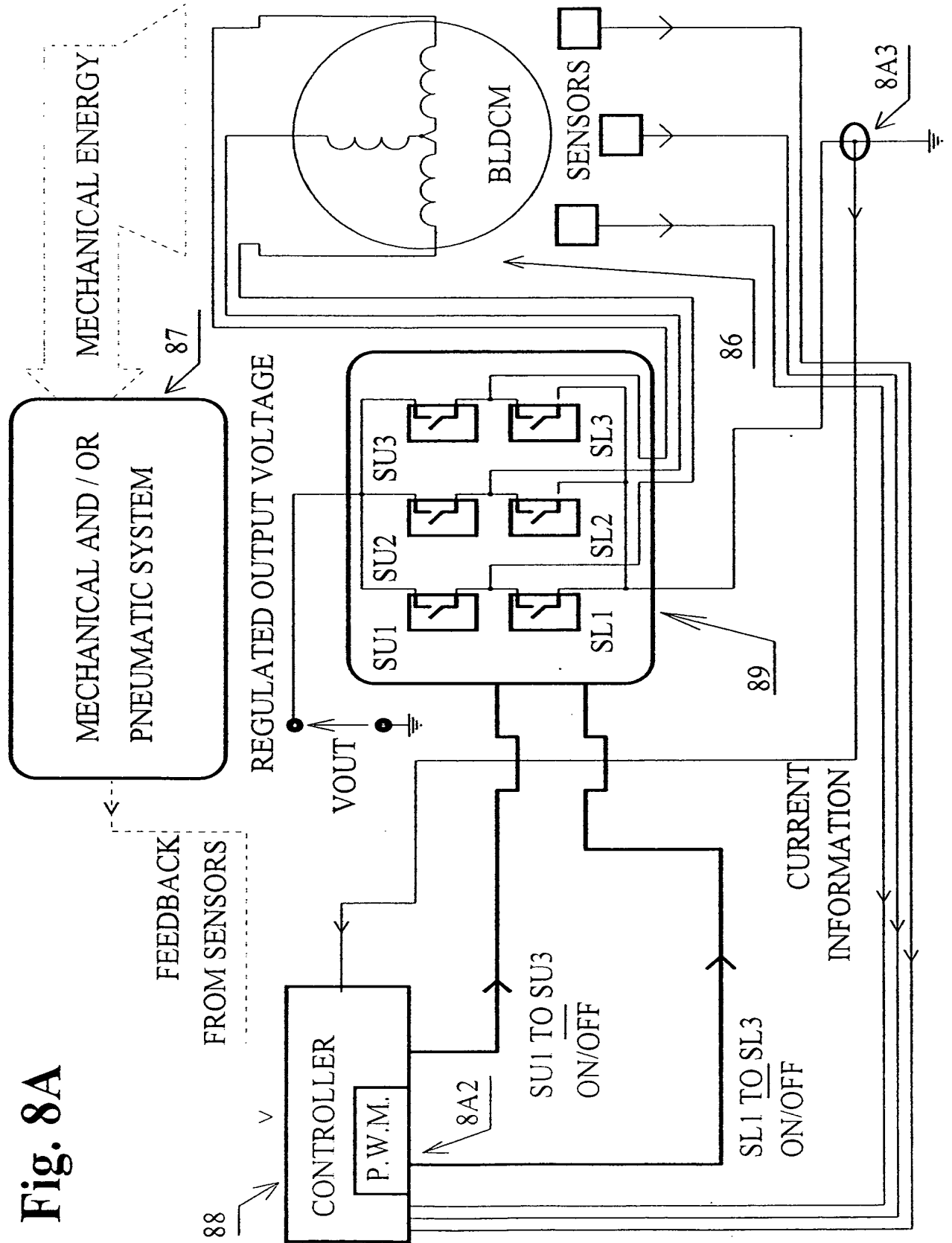


Fig. 8A (CONT'D)

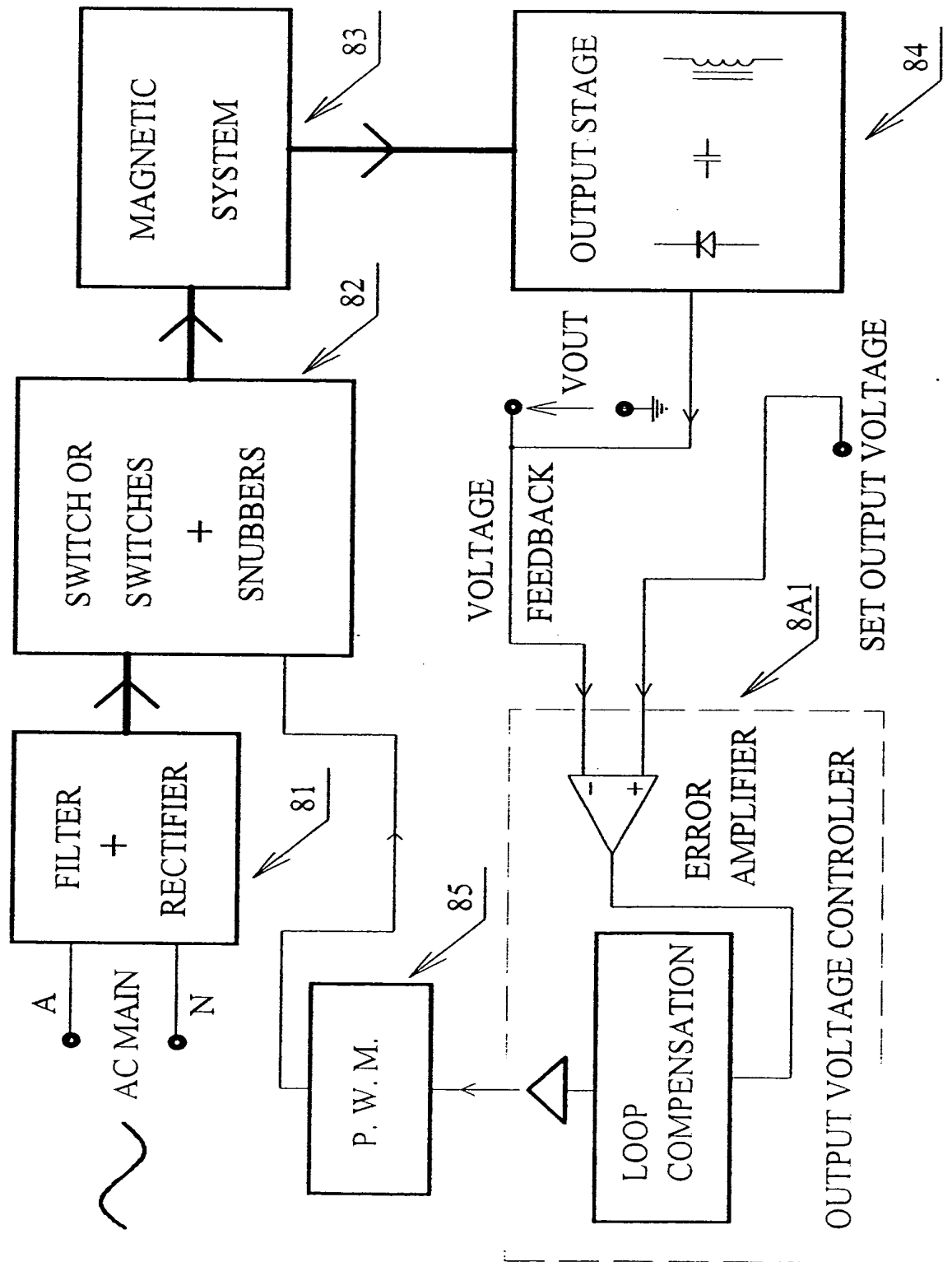


Fig. 8B

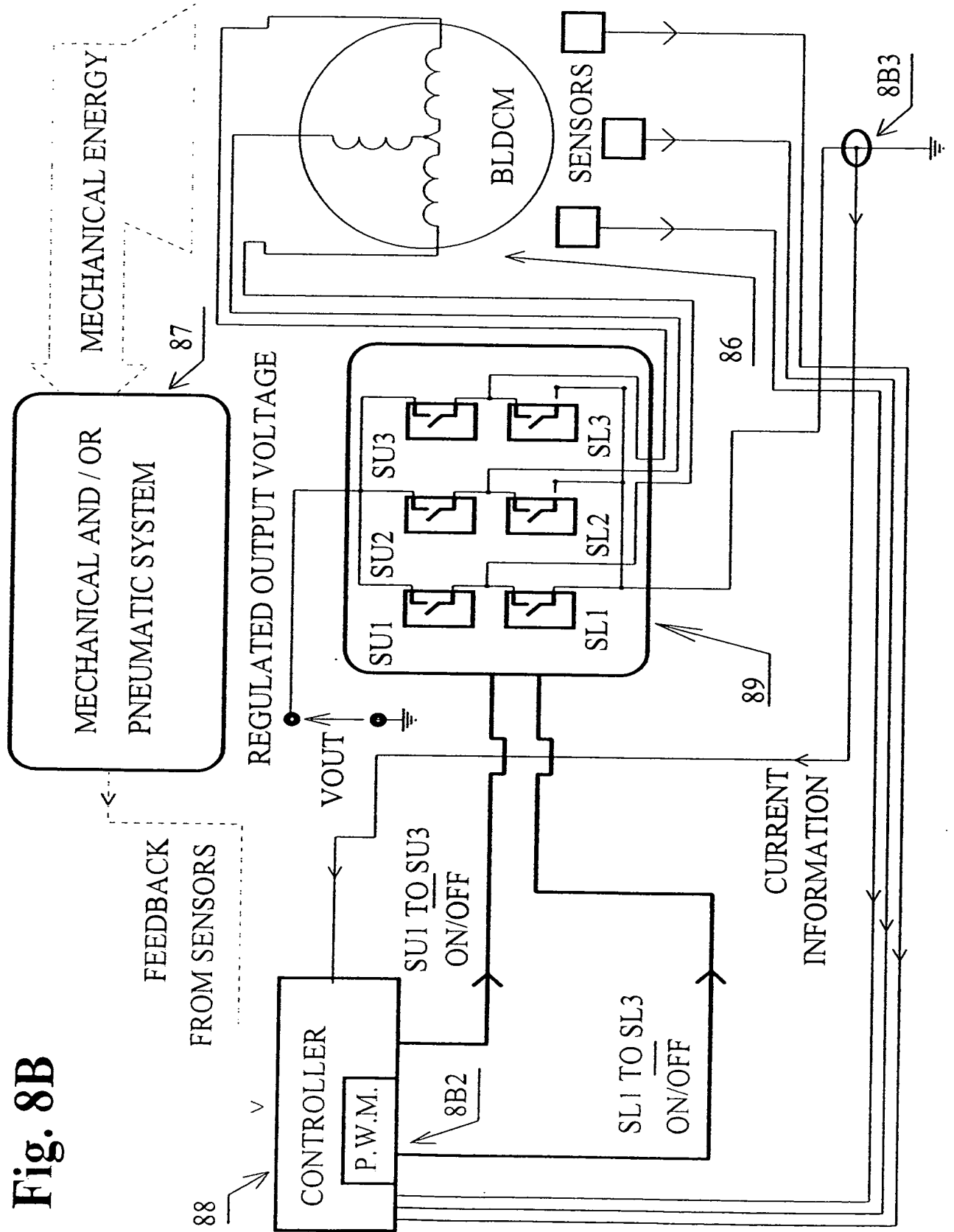


Fig. 8B (CONT'D)

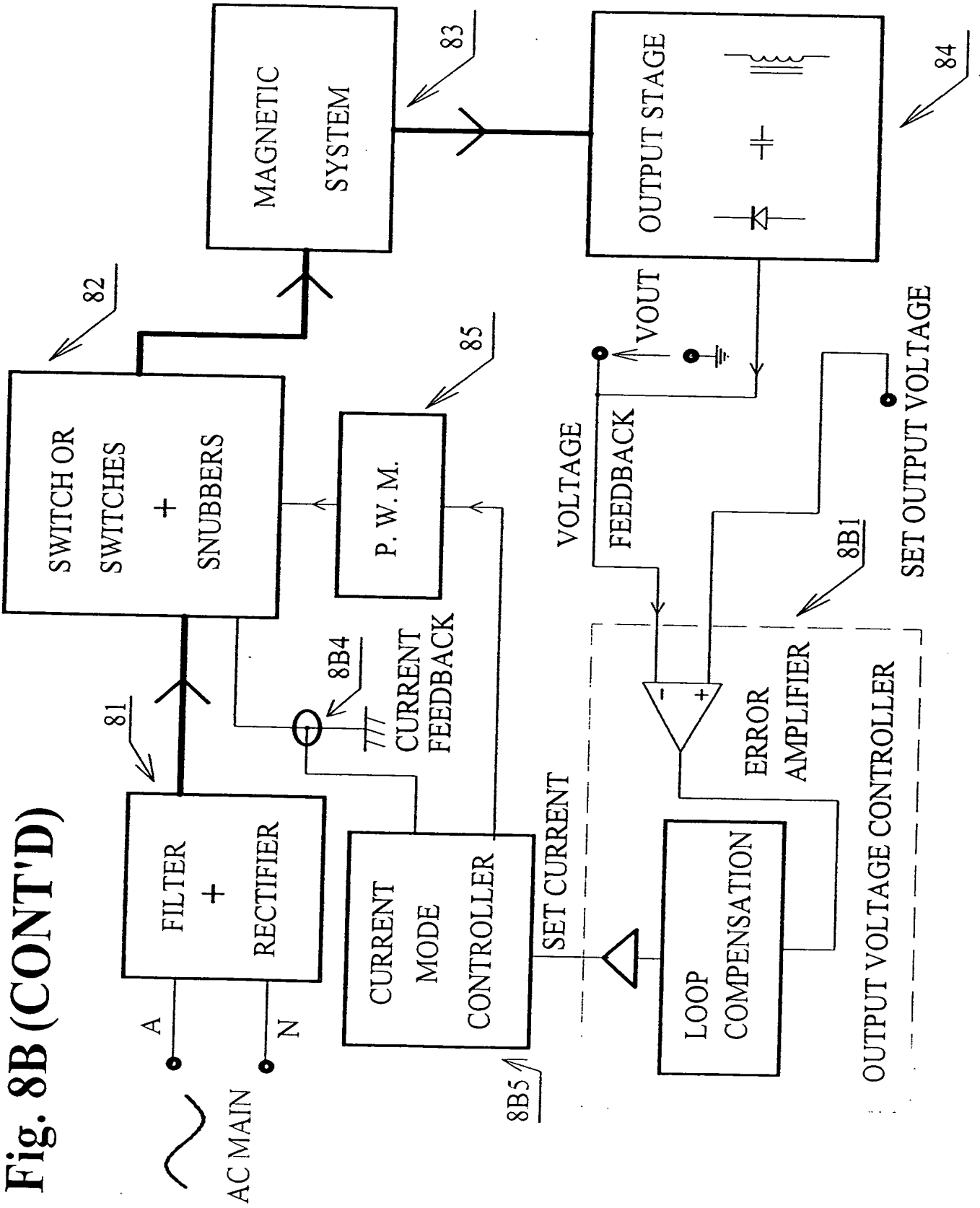


Fig. 8C

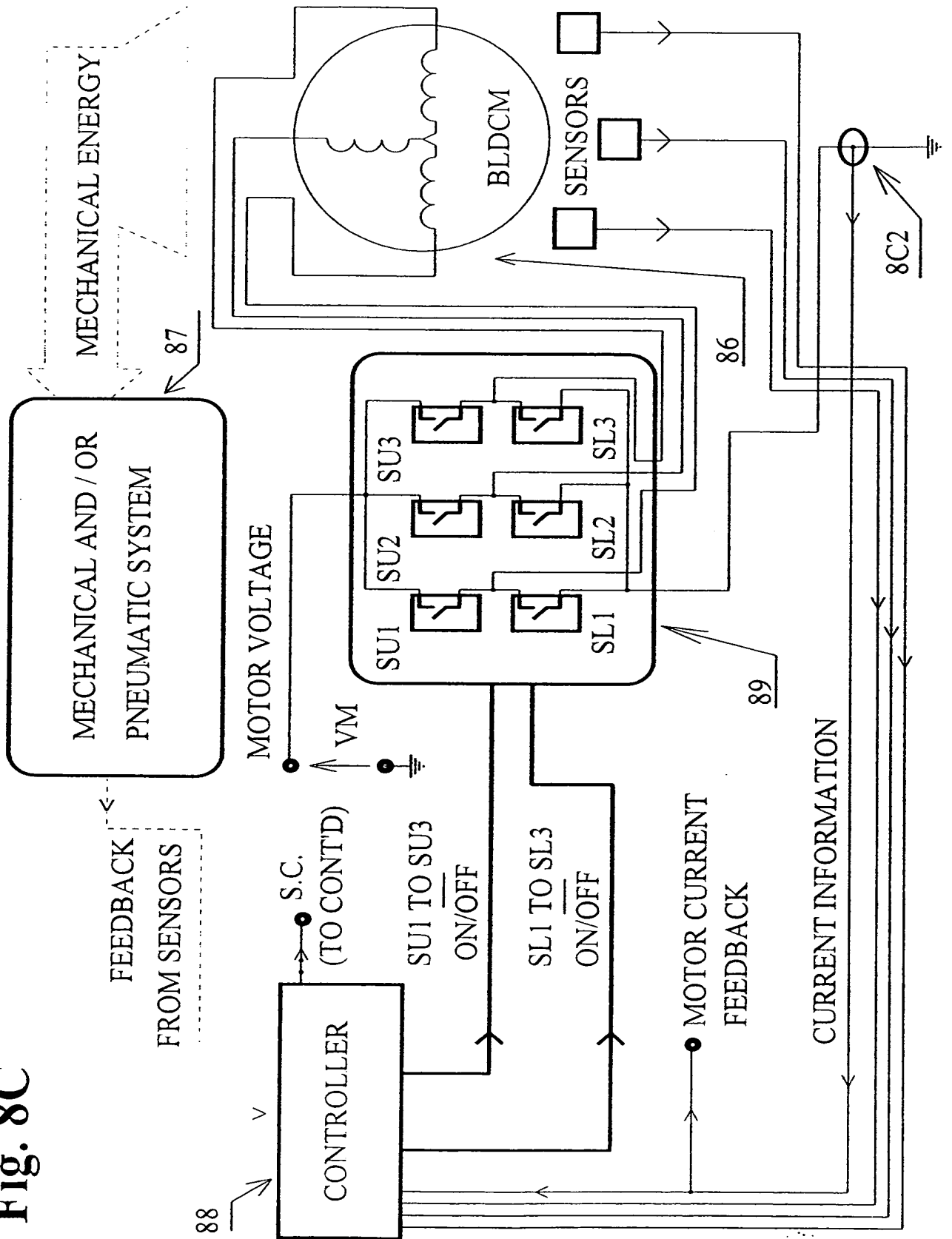


Fig. 8C (CONT'D)

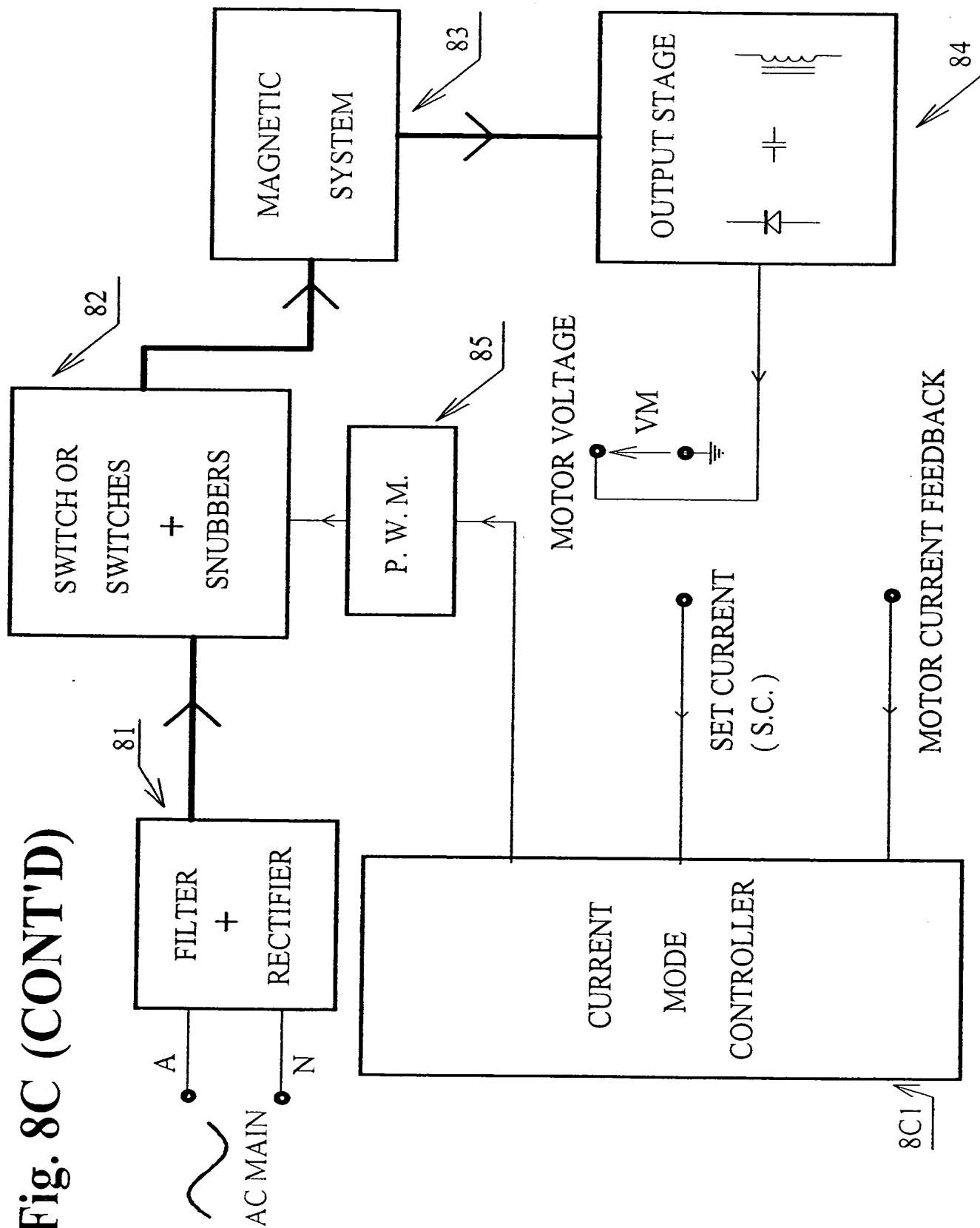


Fig. 9A

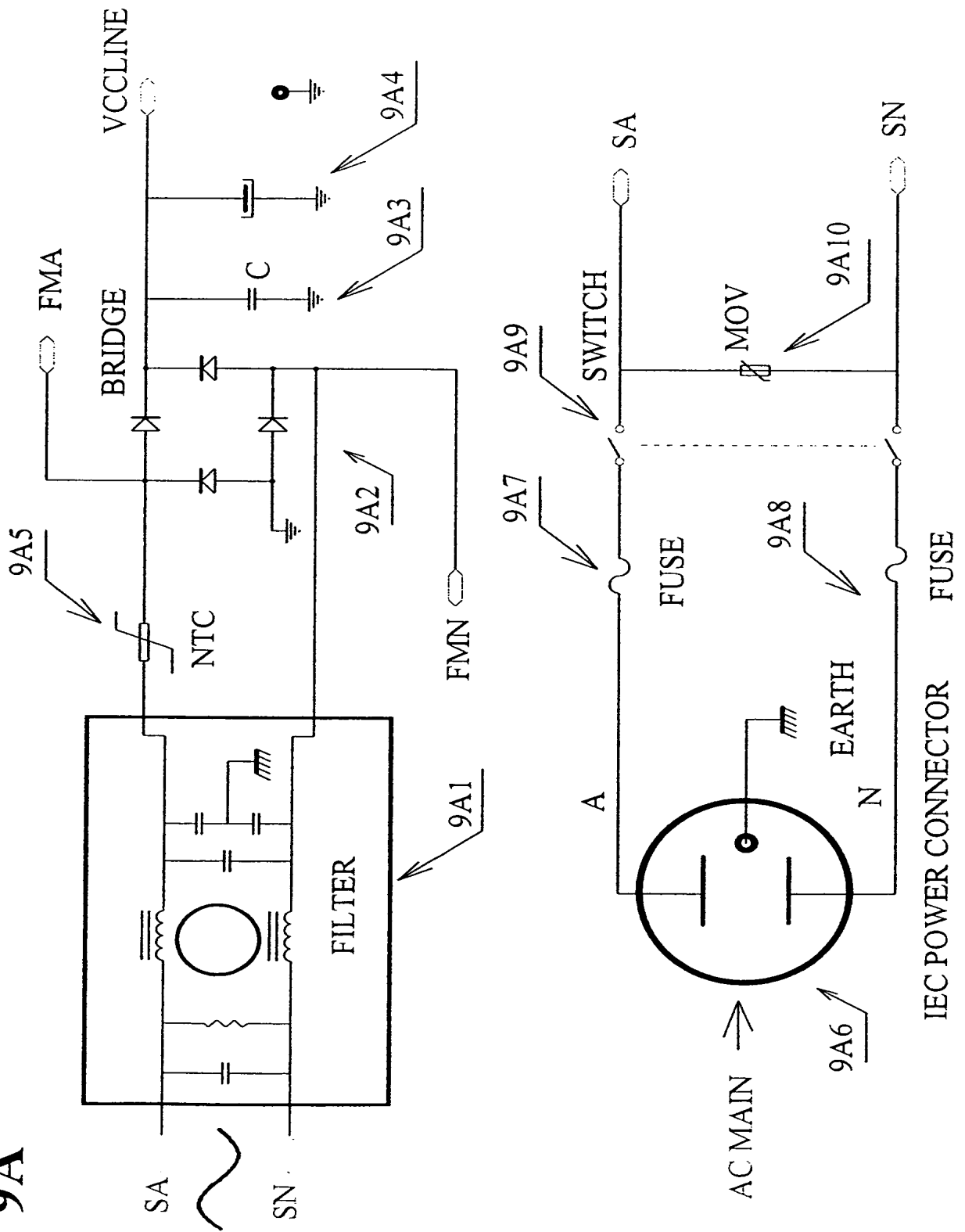
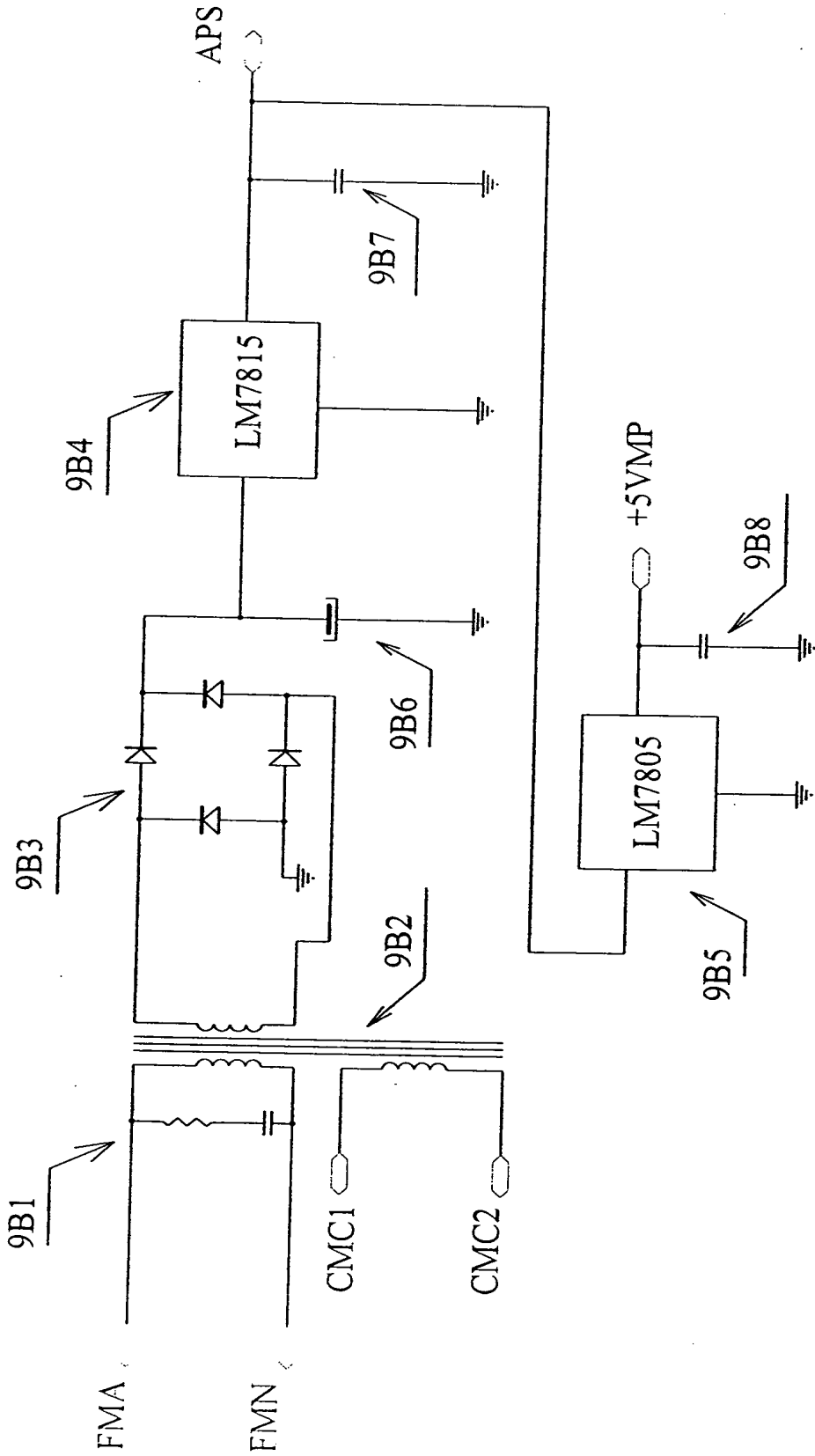




Fig. 9B



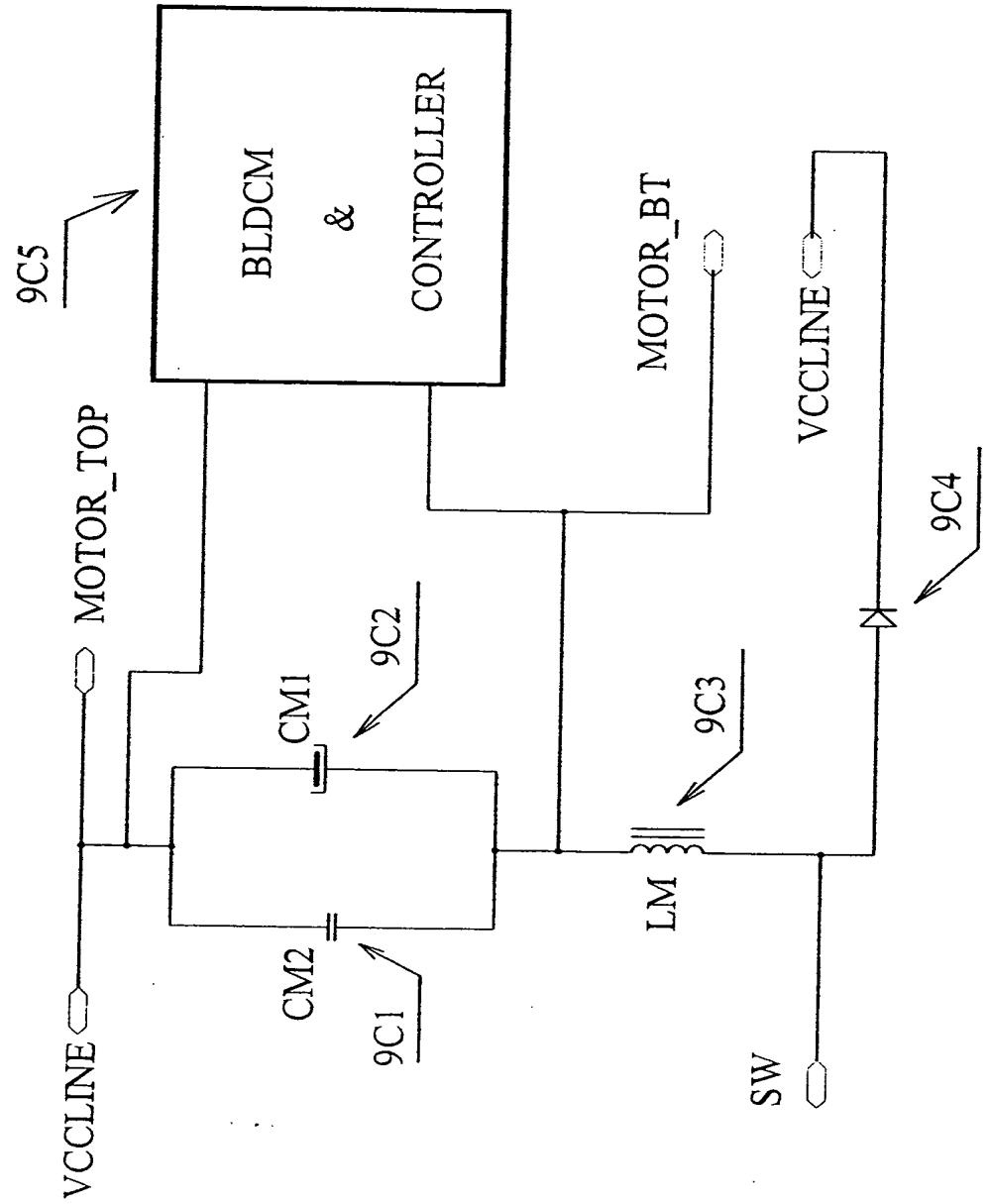
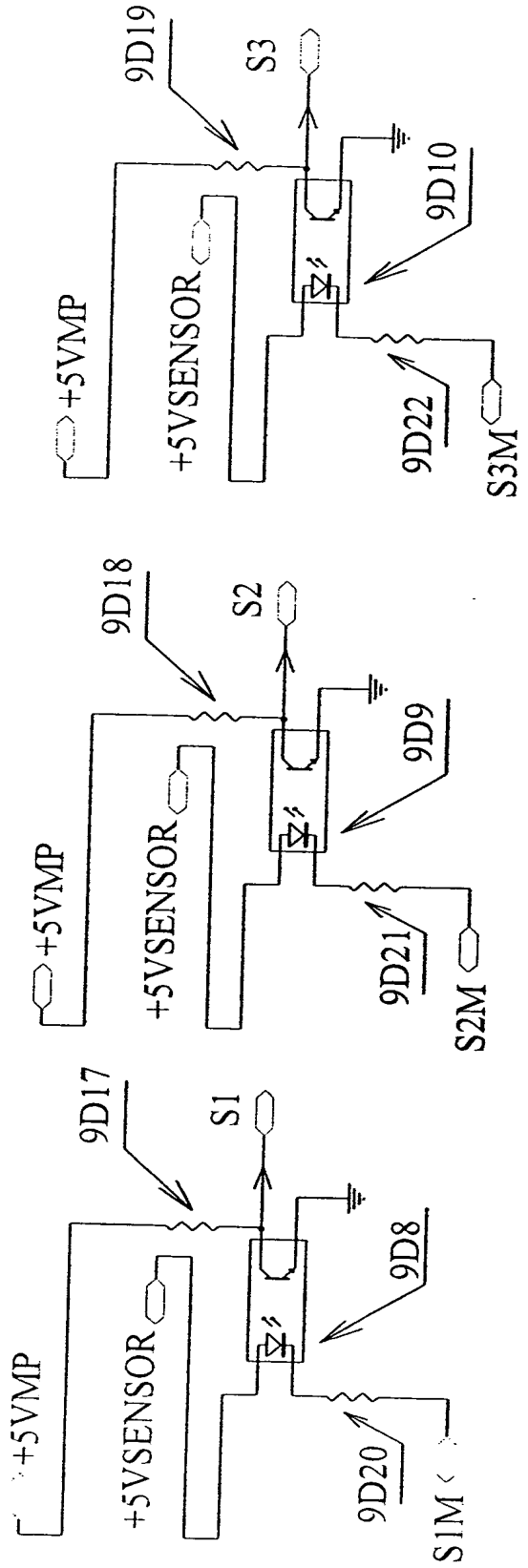
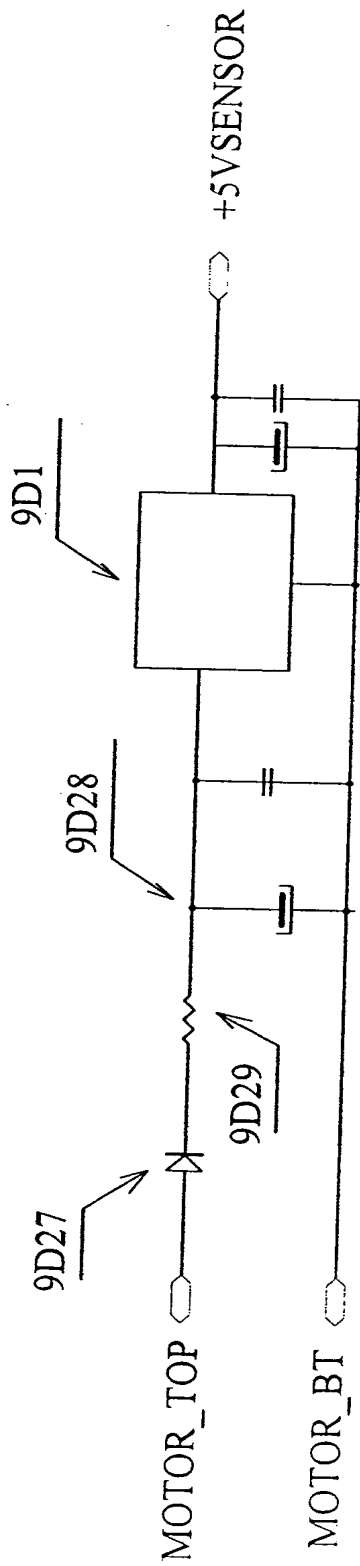
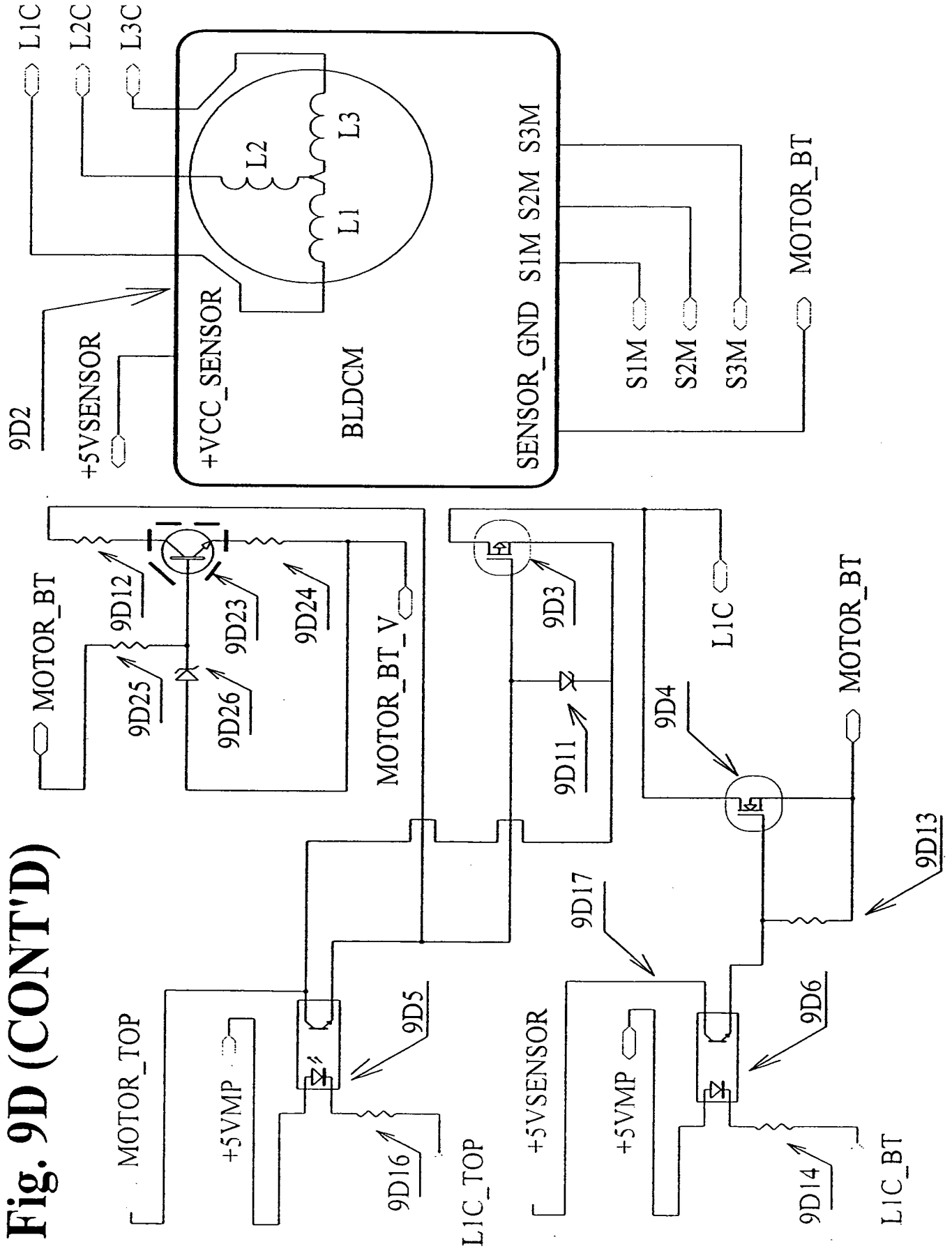
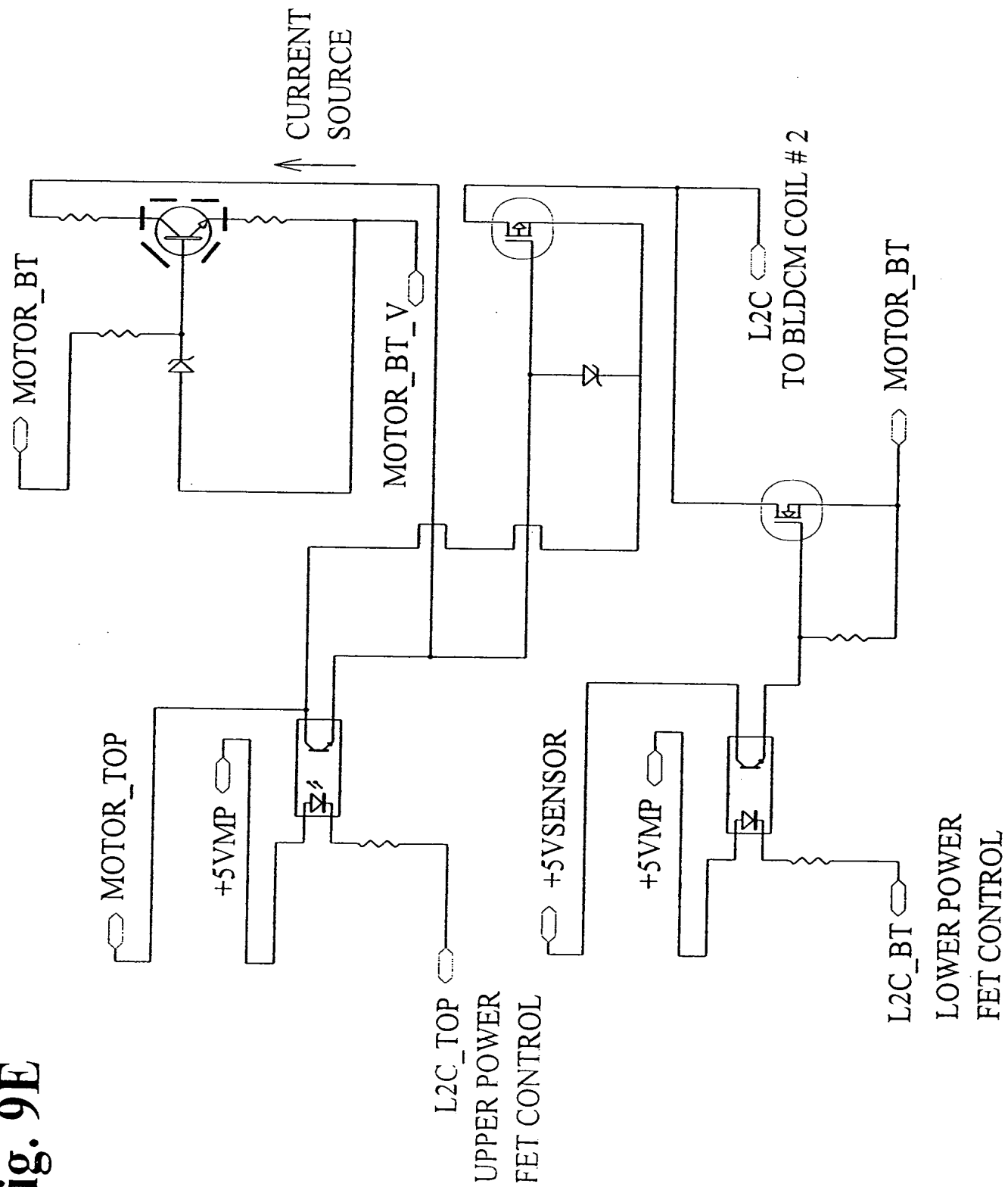


Fig. 9D



**Fig. 9D (CONT'D)**





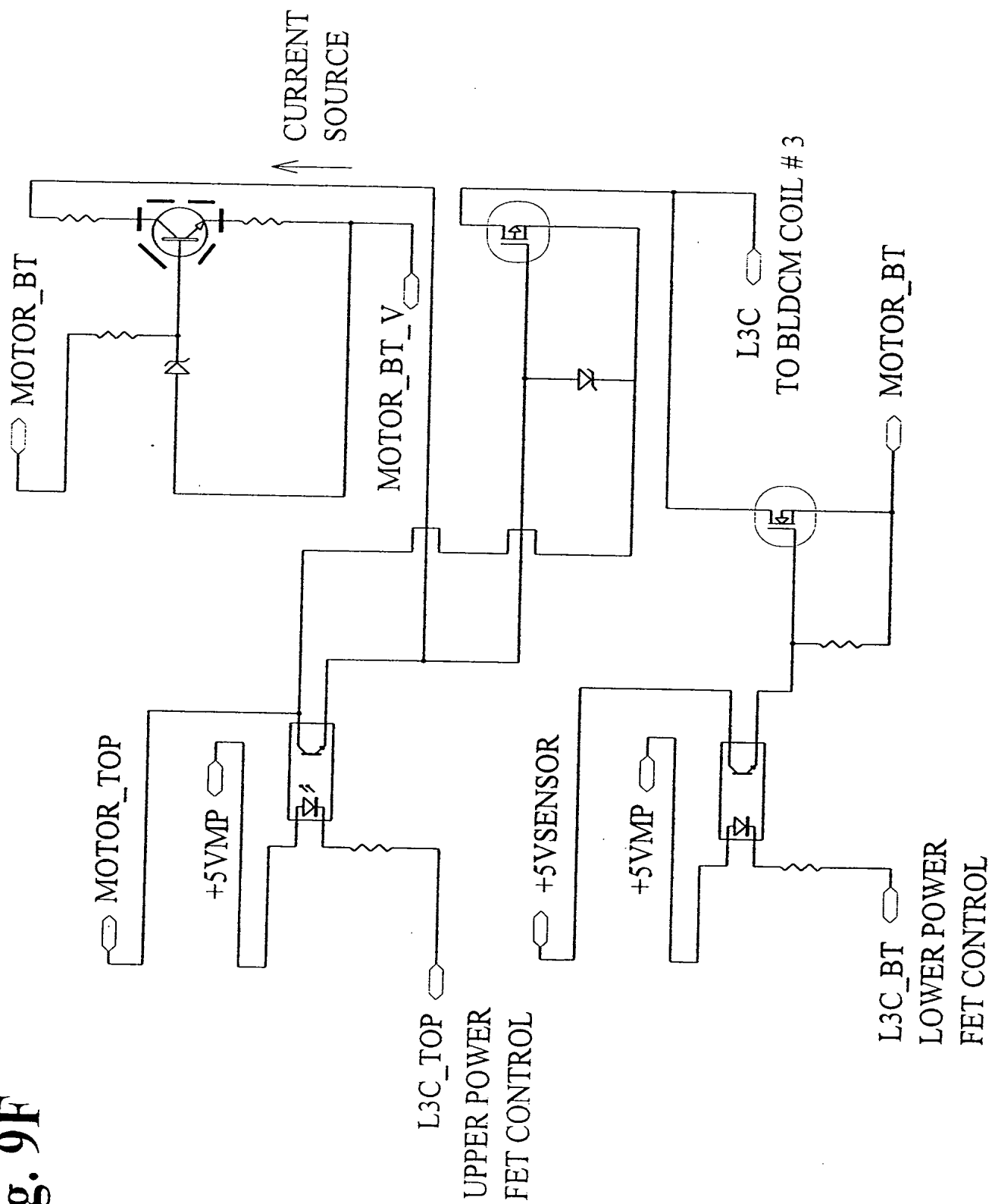


Fig. 9G

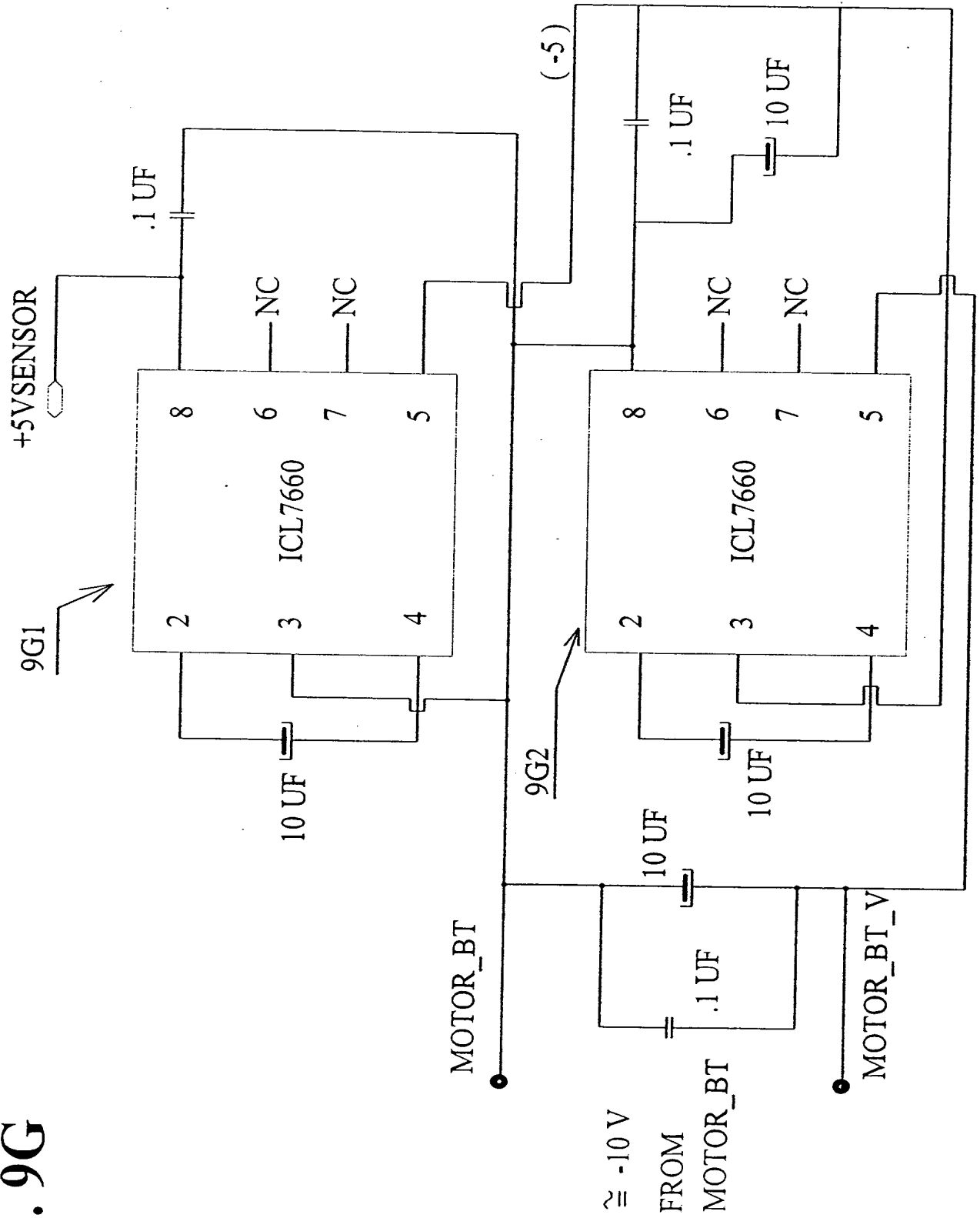


Fig. 9H

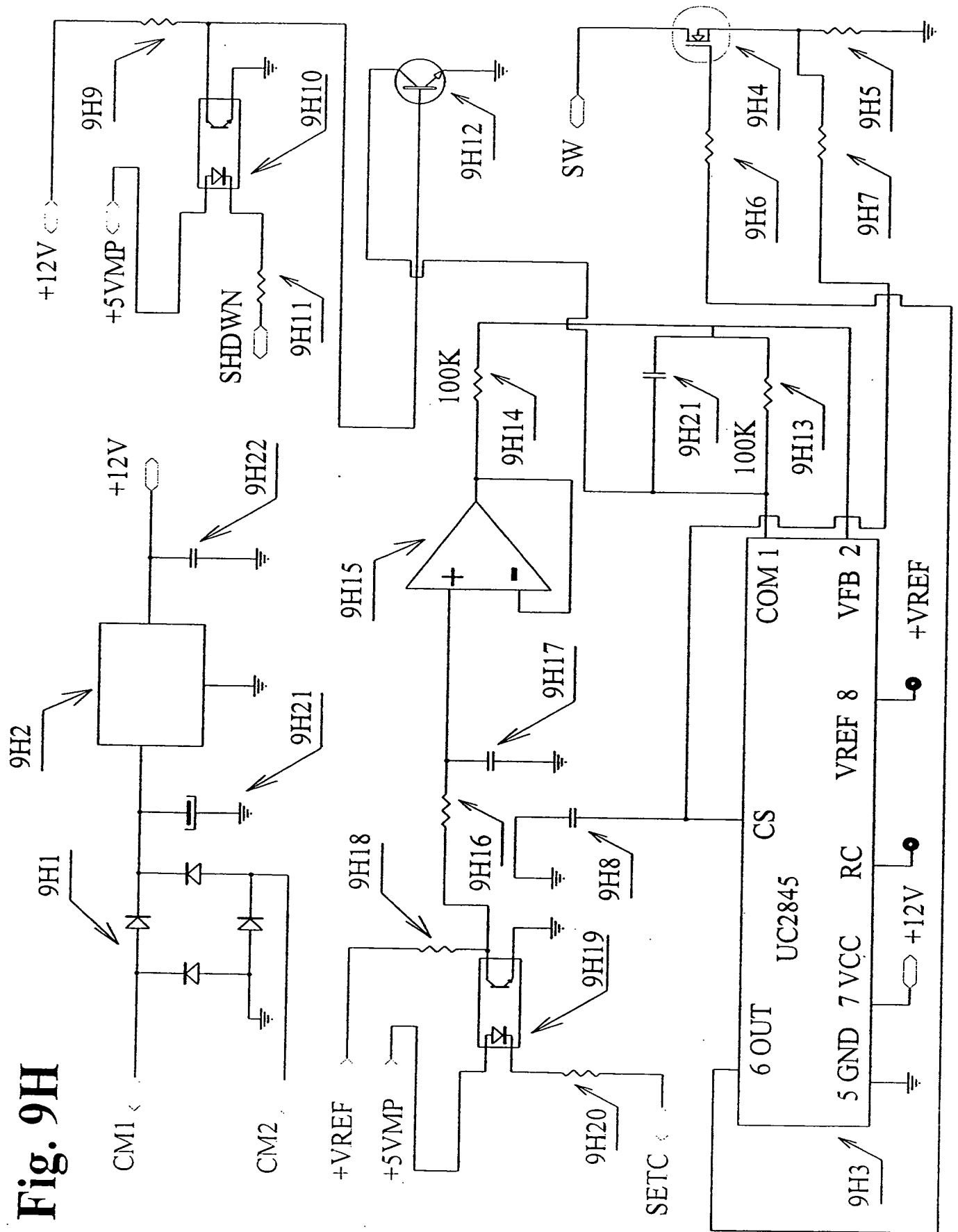




Fig. 9I

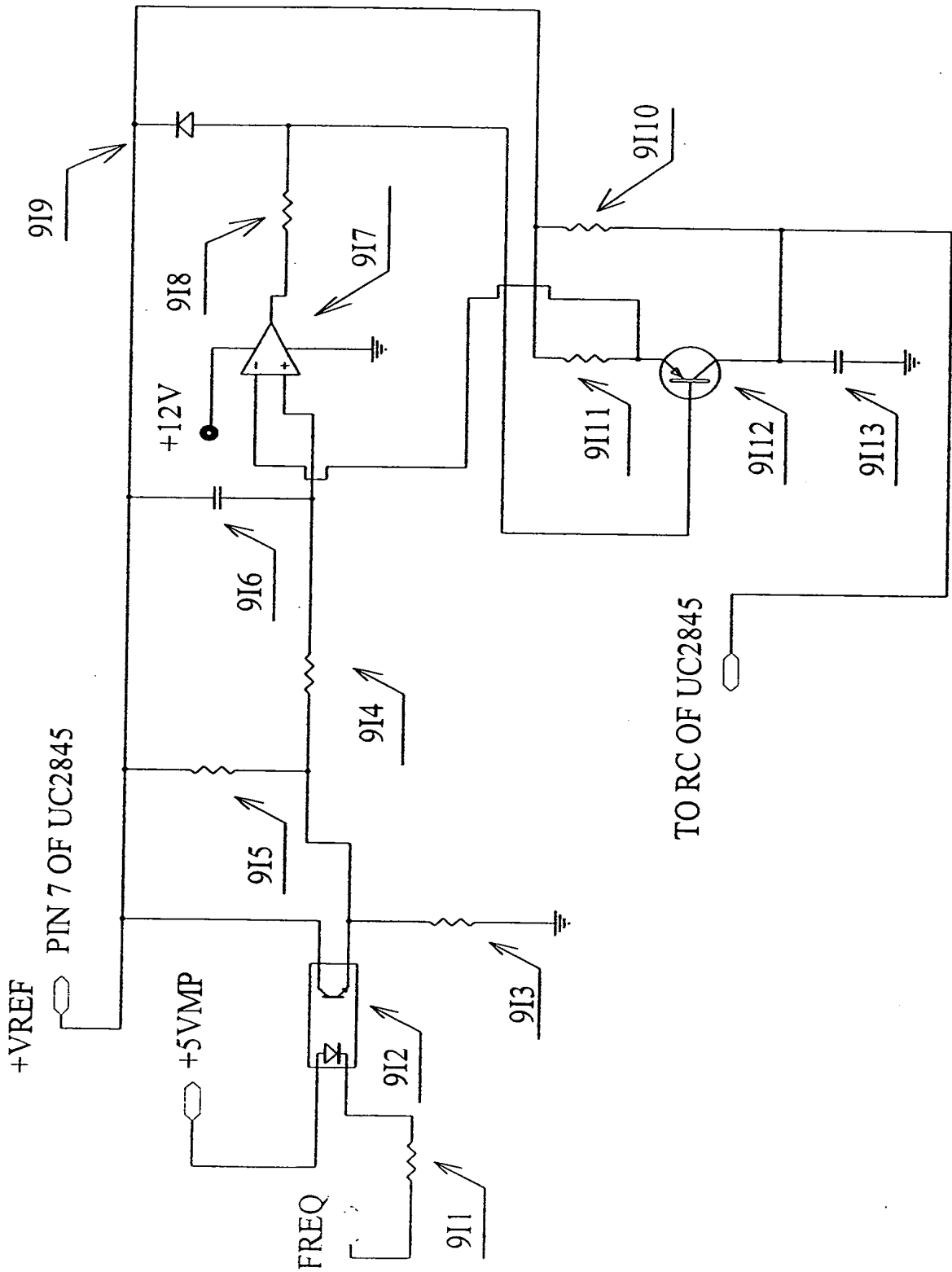
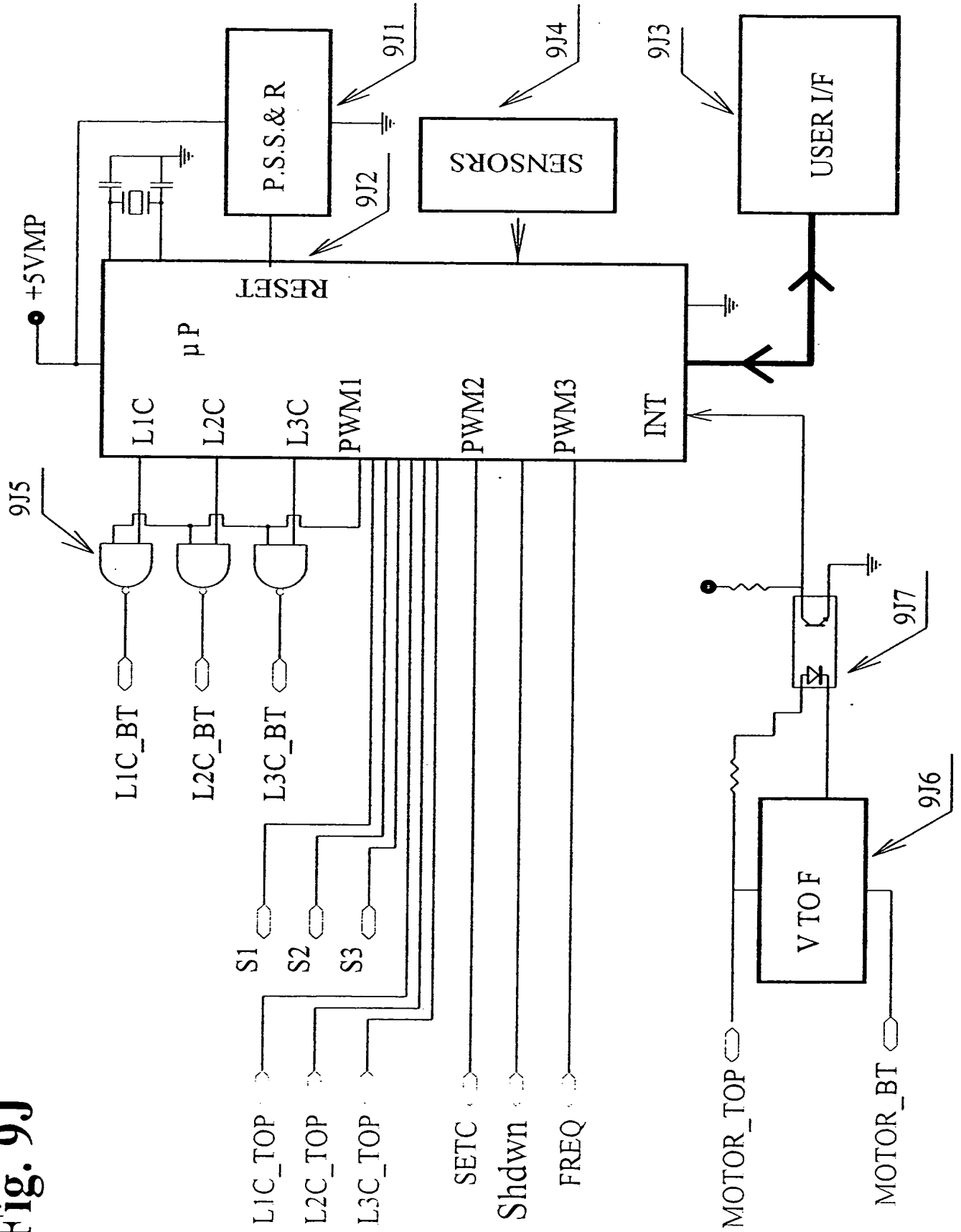
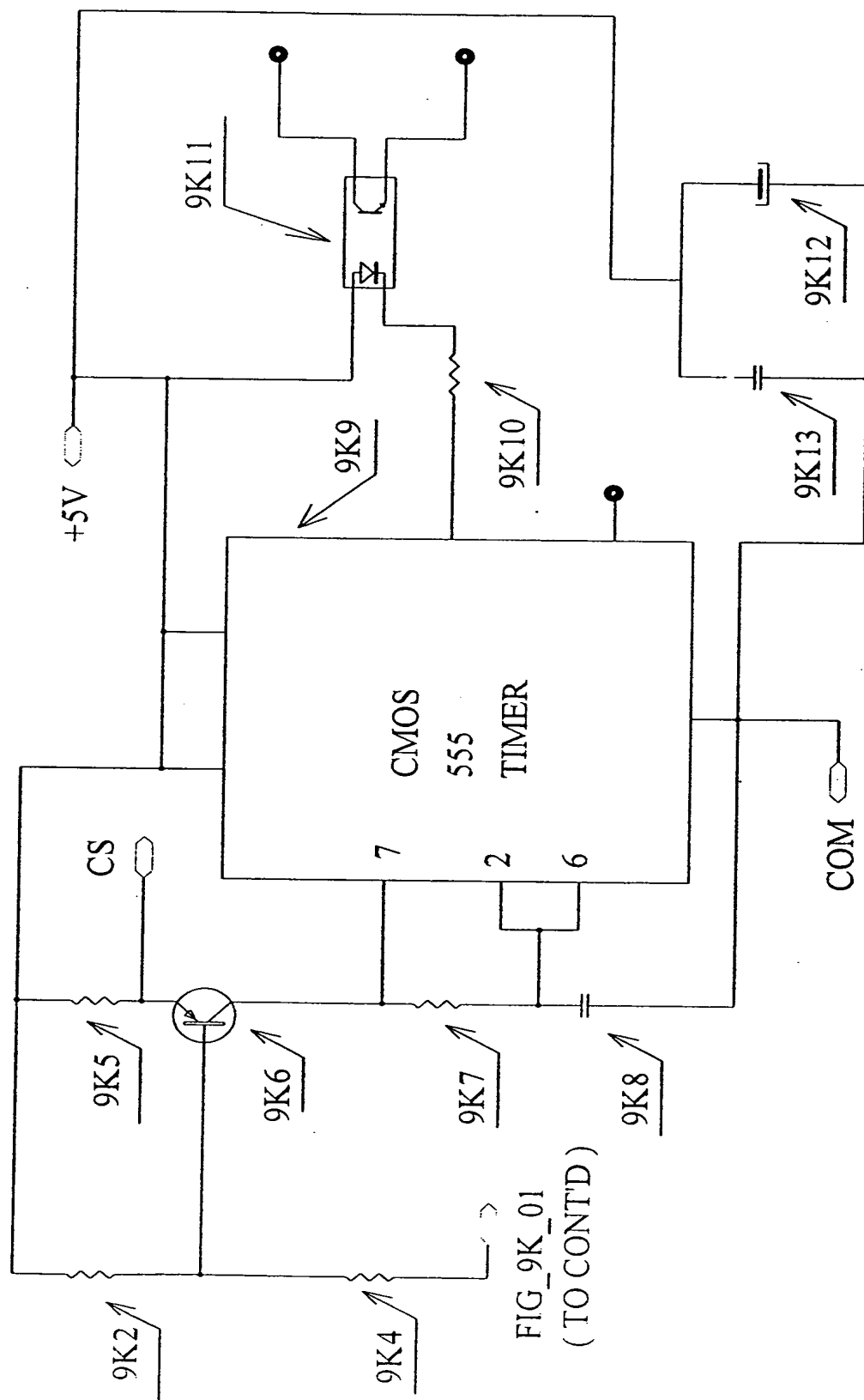


Fig. 9J





**Fig. 9K (CONT'D)**

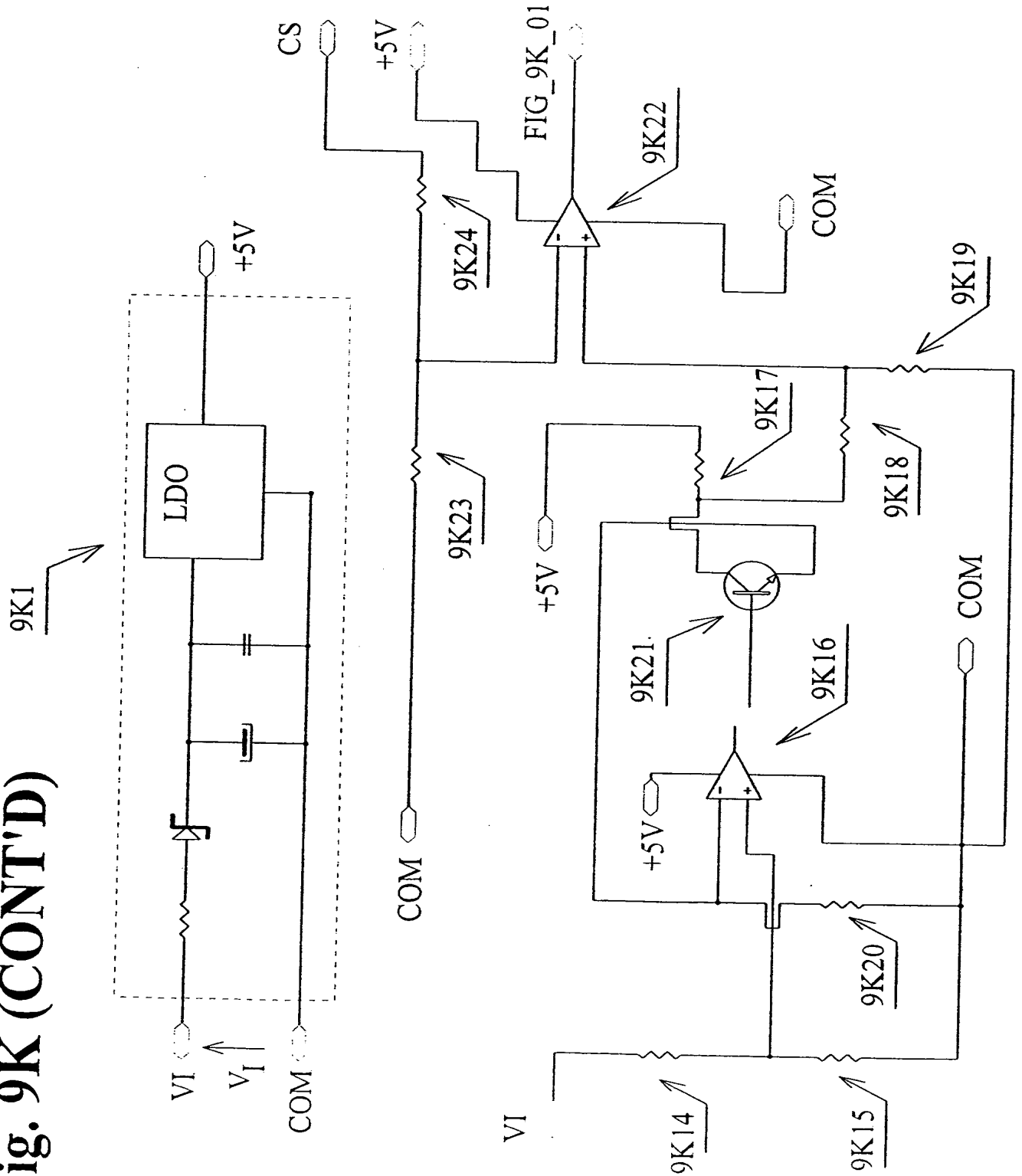


Fig. 9L

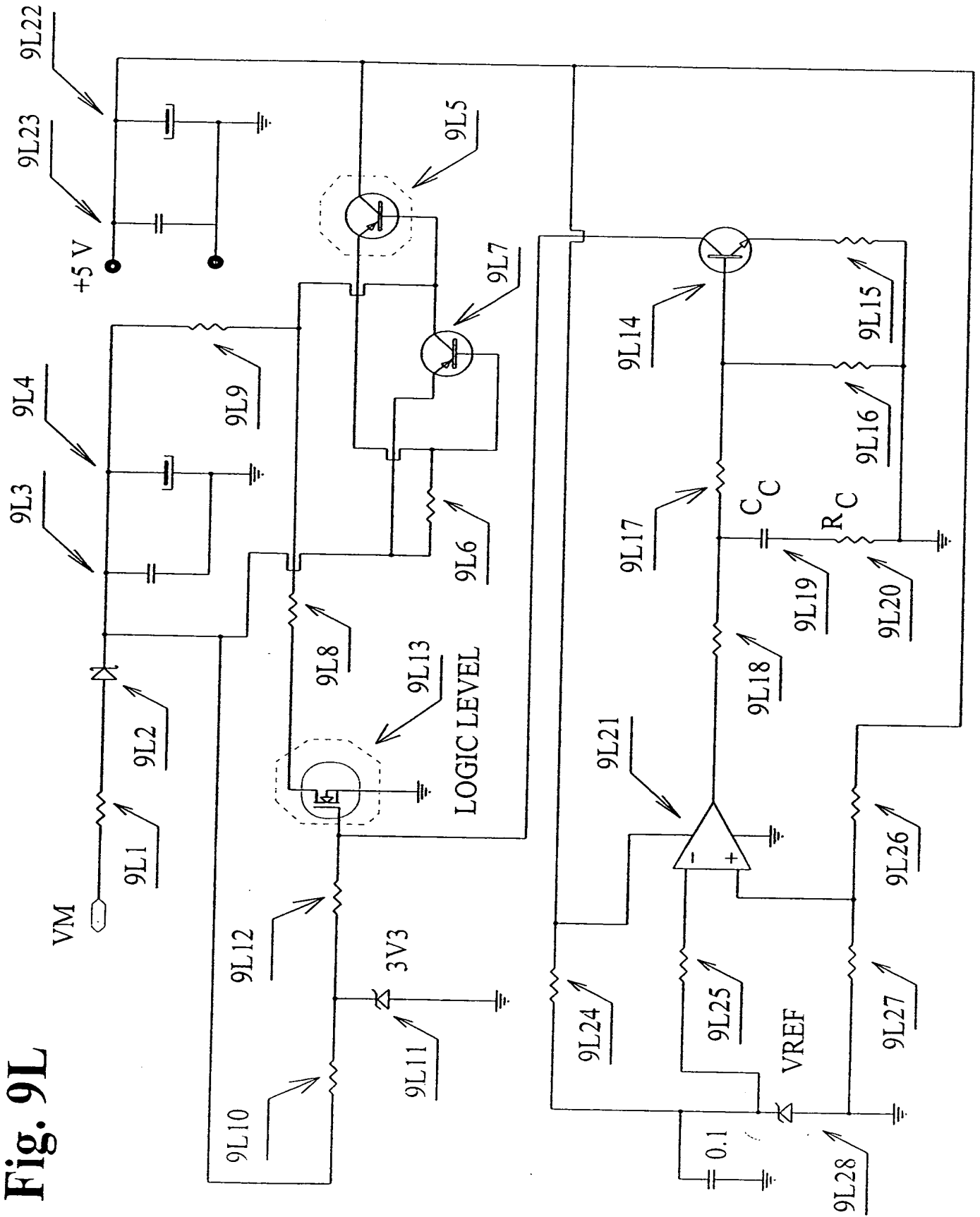
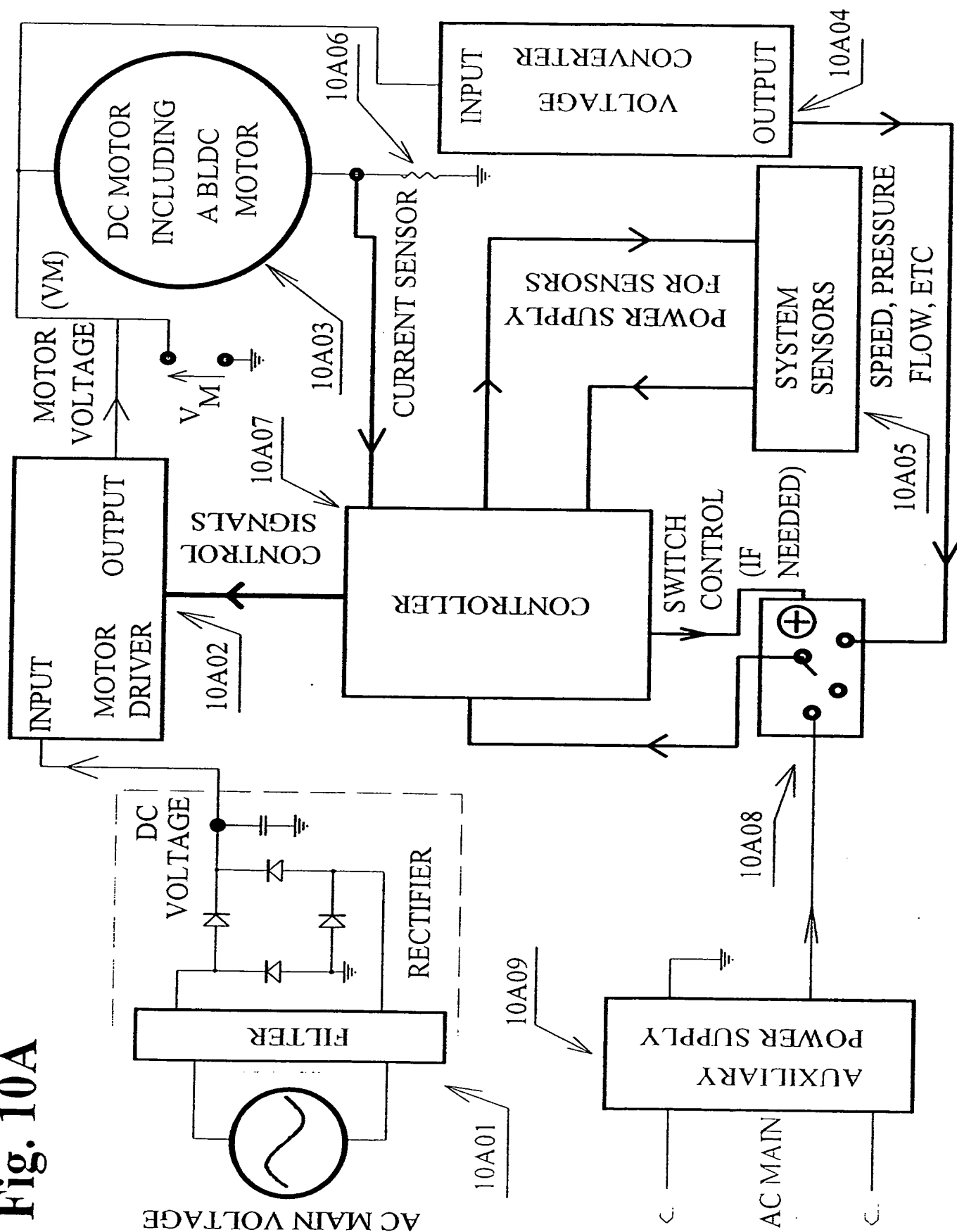
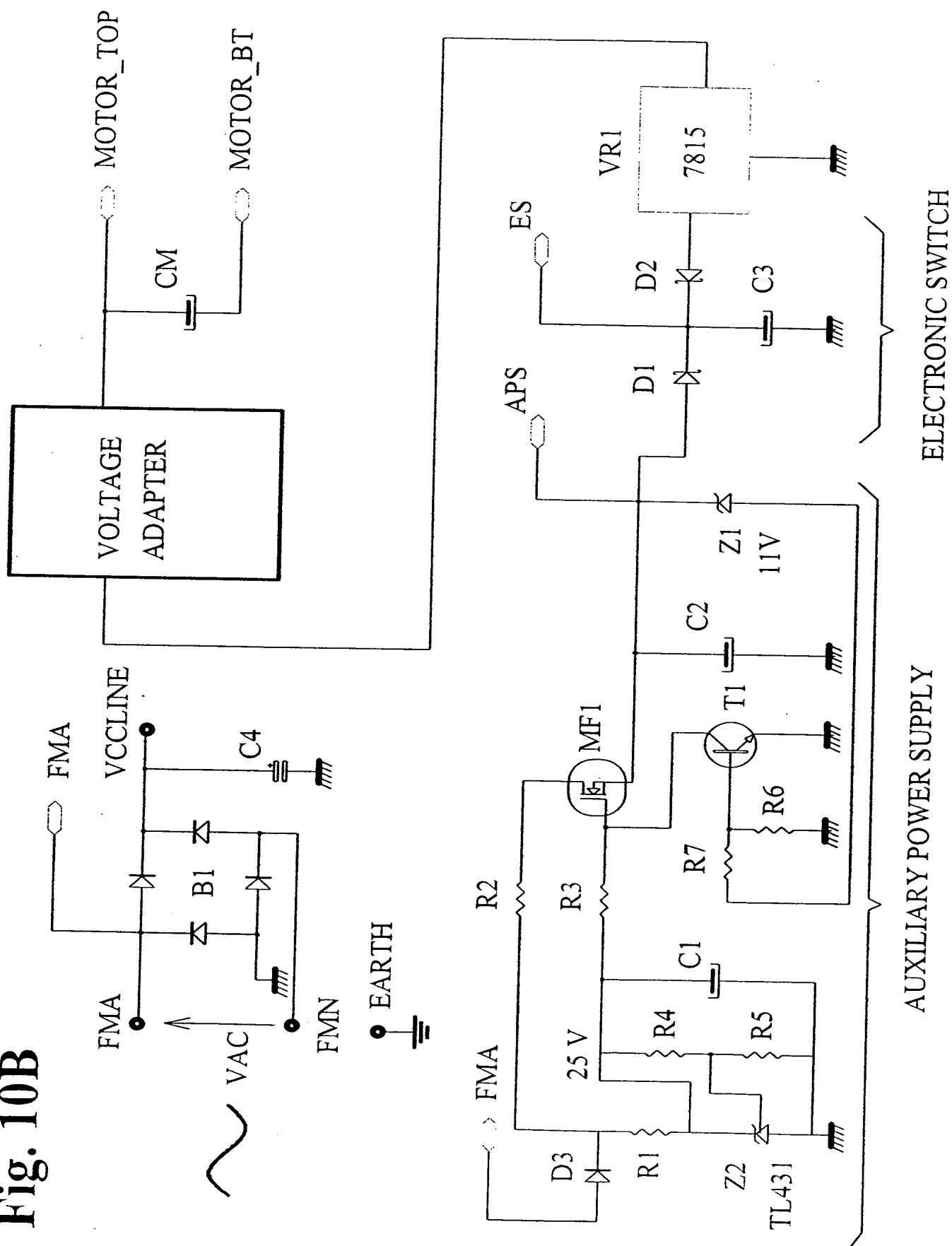


Fig. 10A





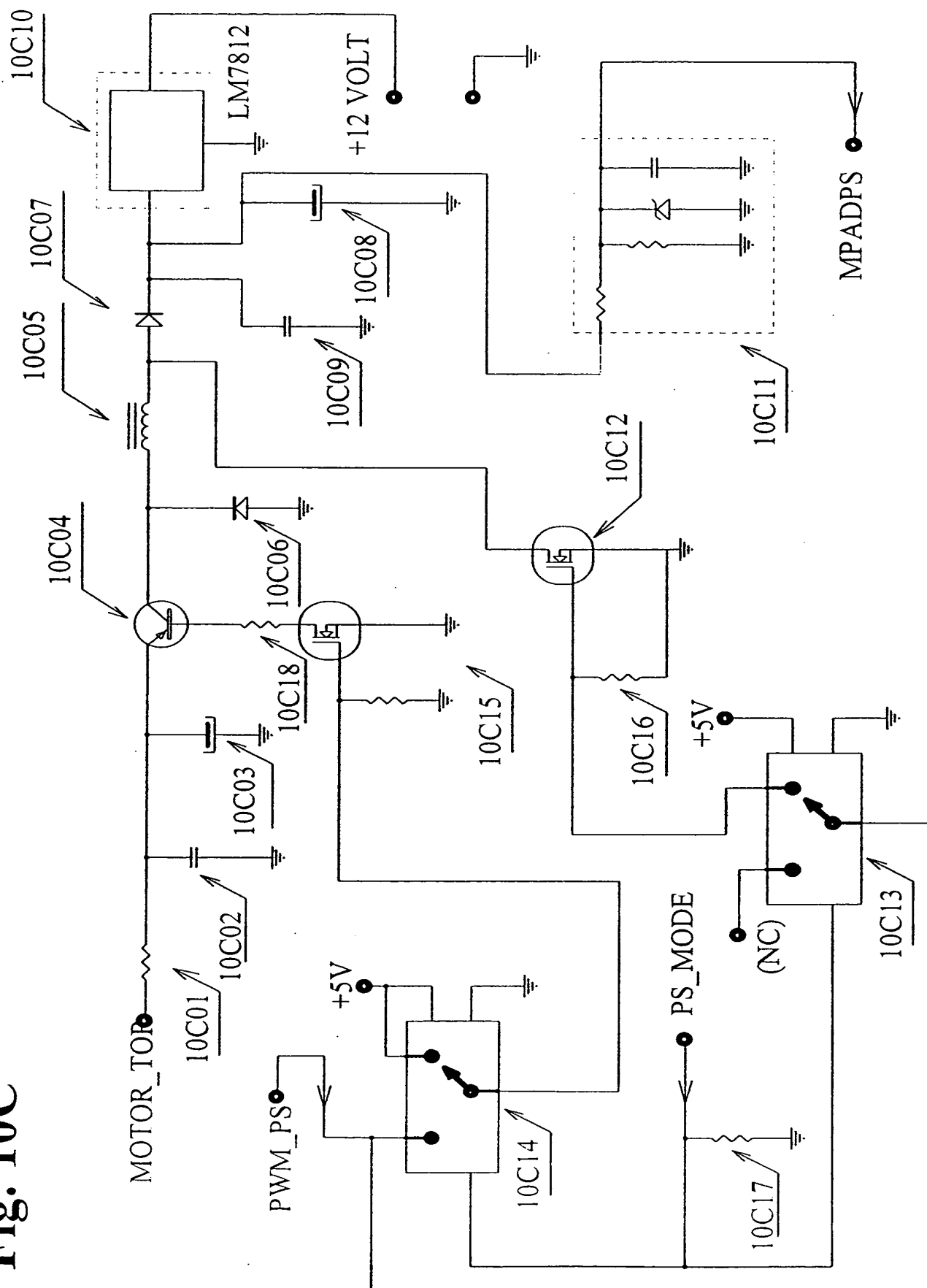




Fig. 10D

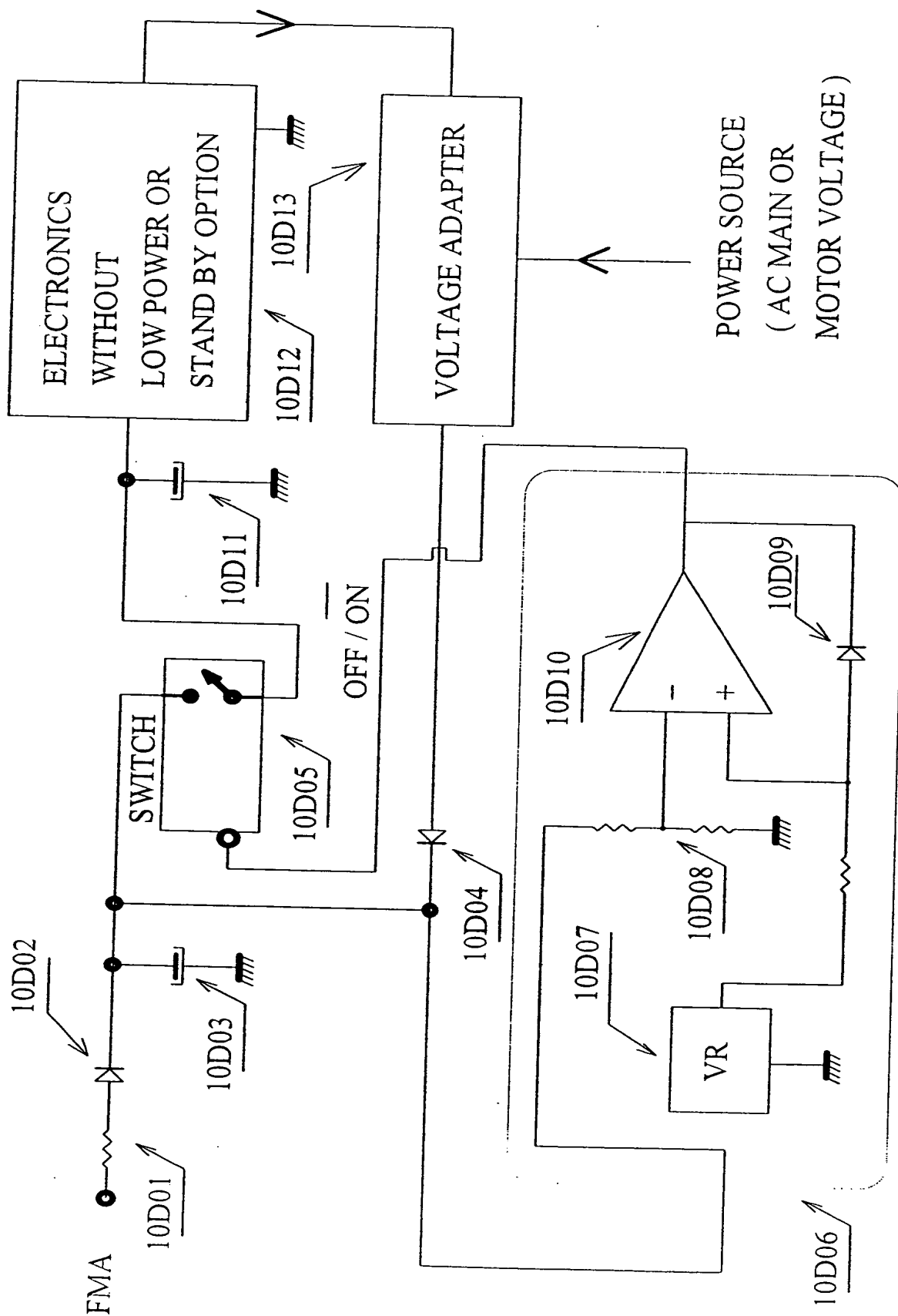
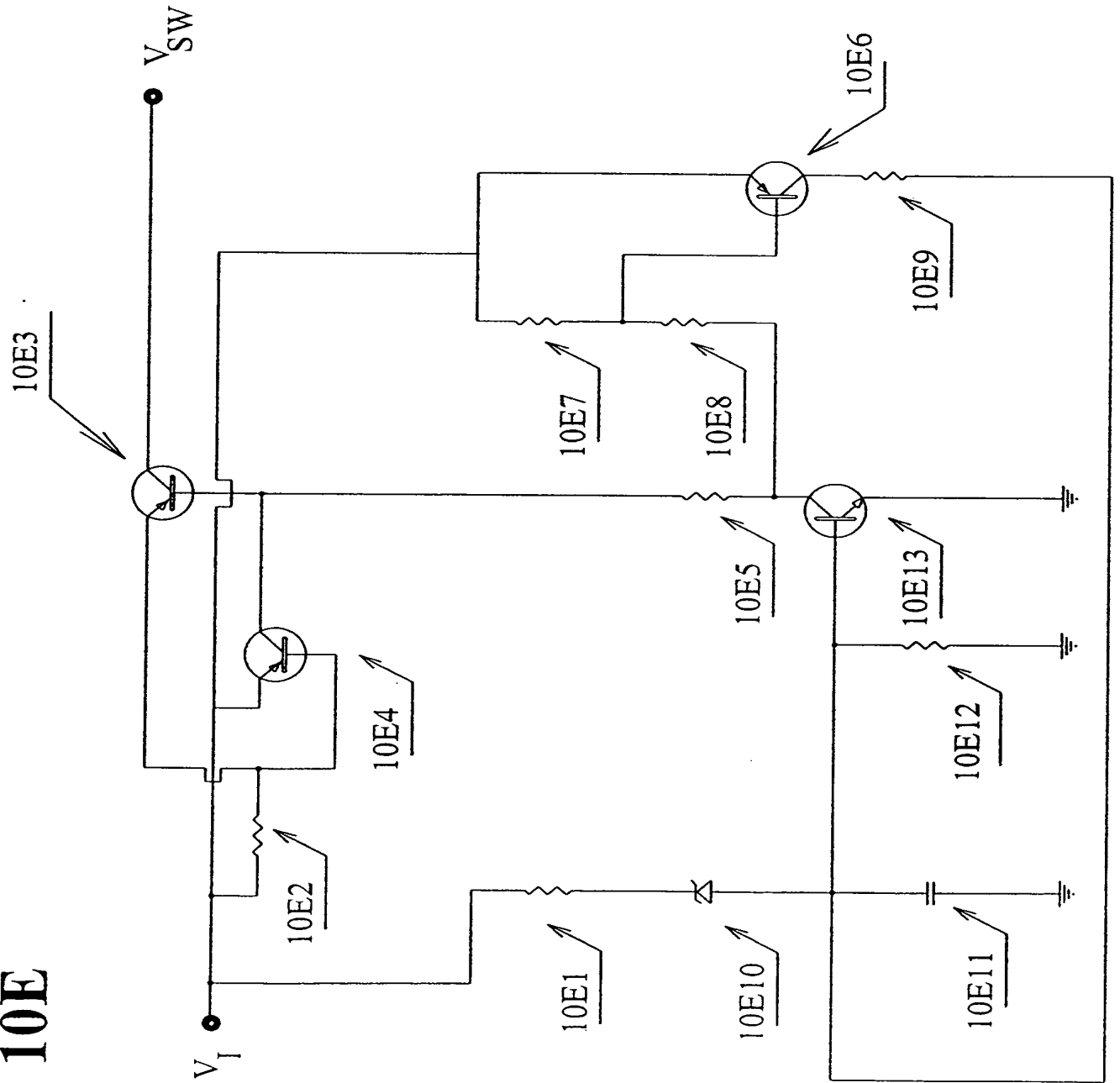
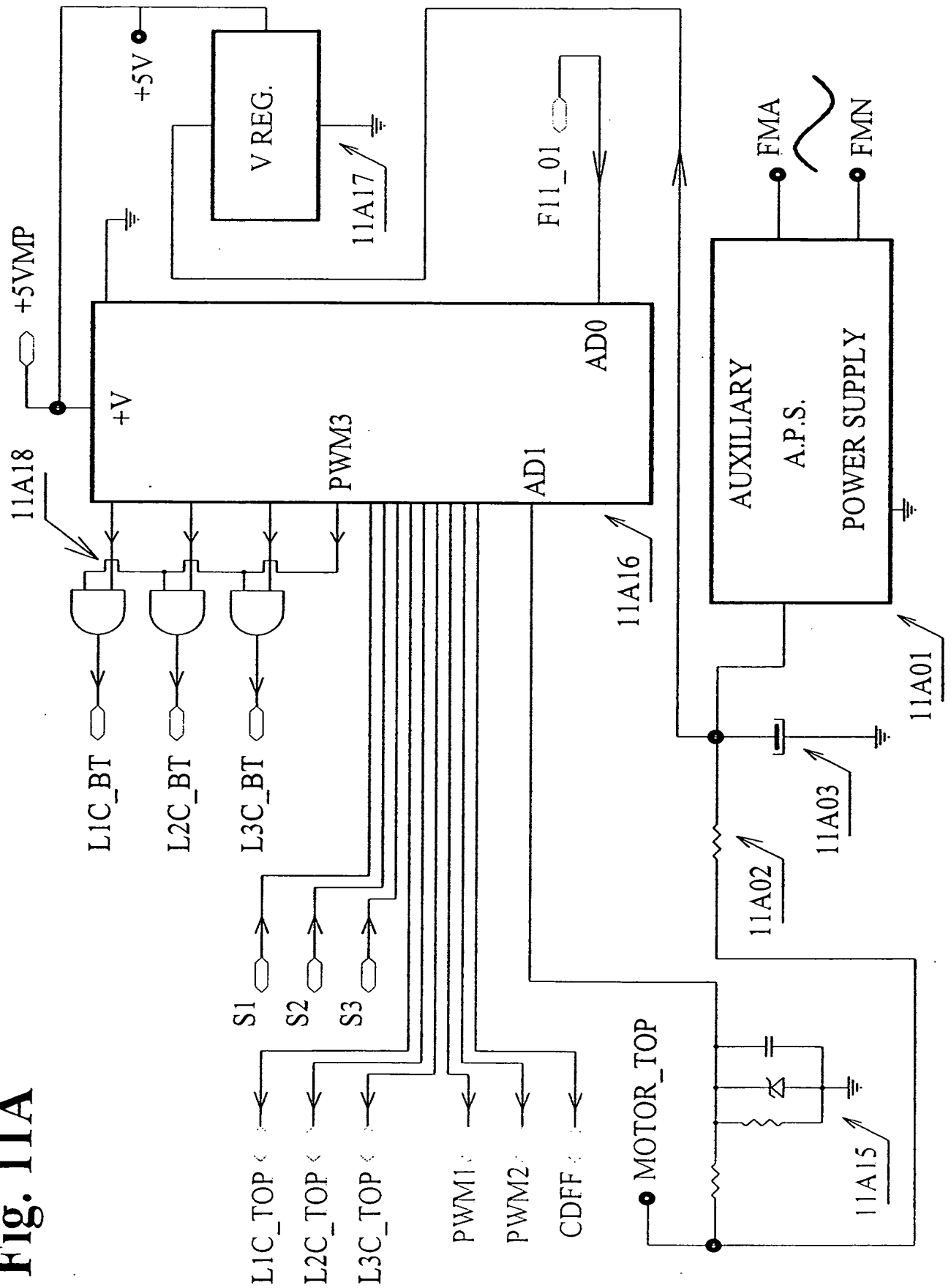
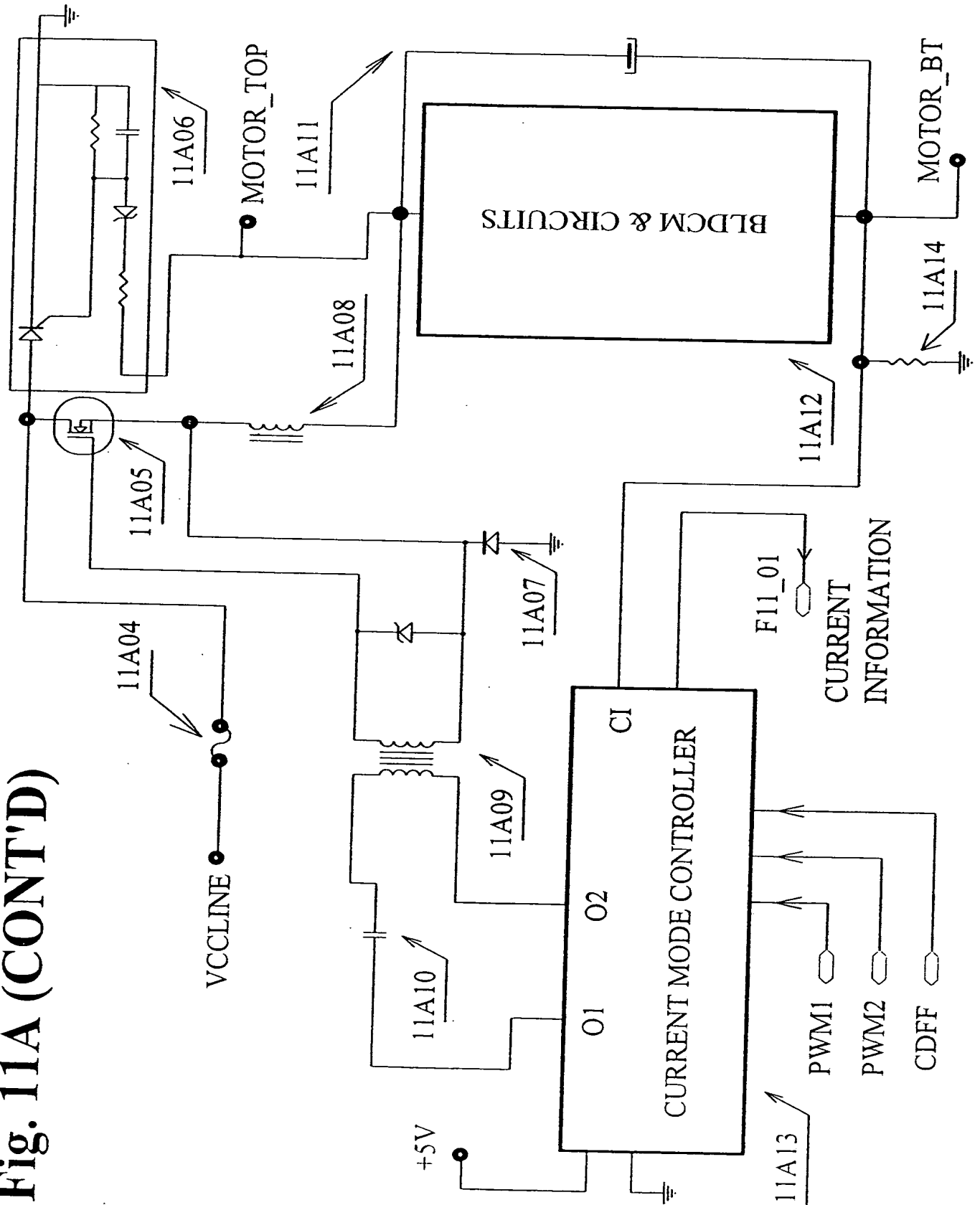


Fig. 10E







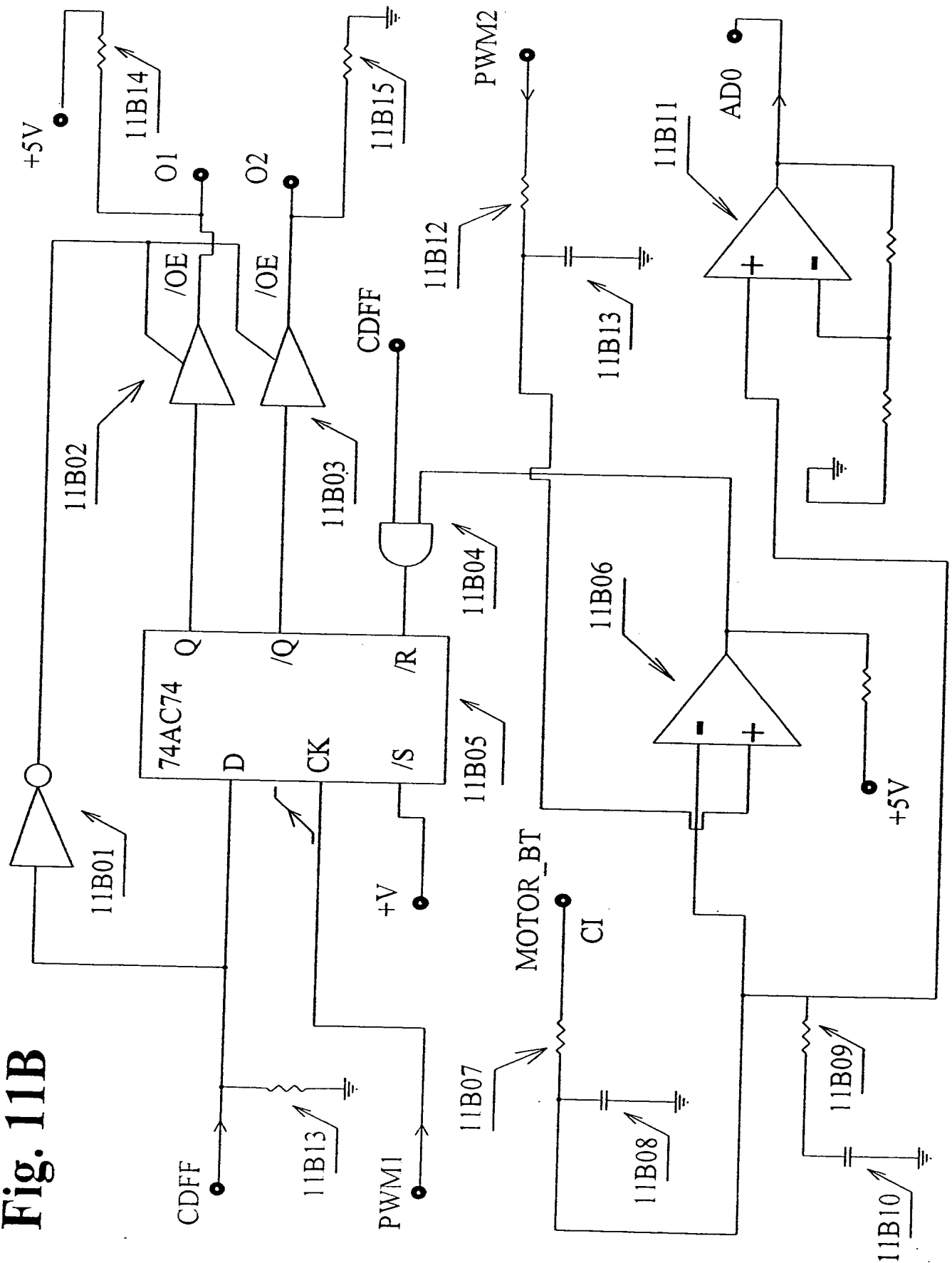


Fig. 12

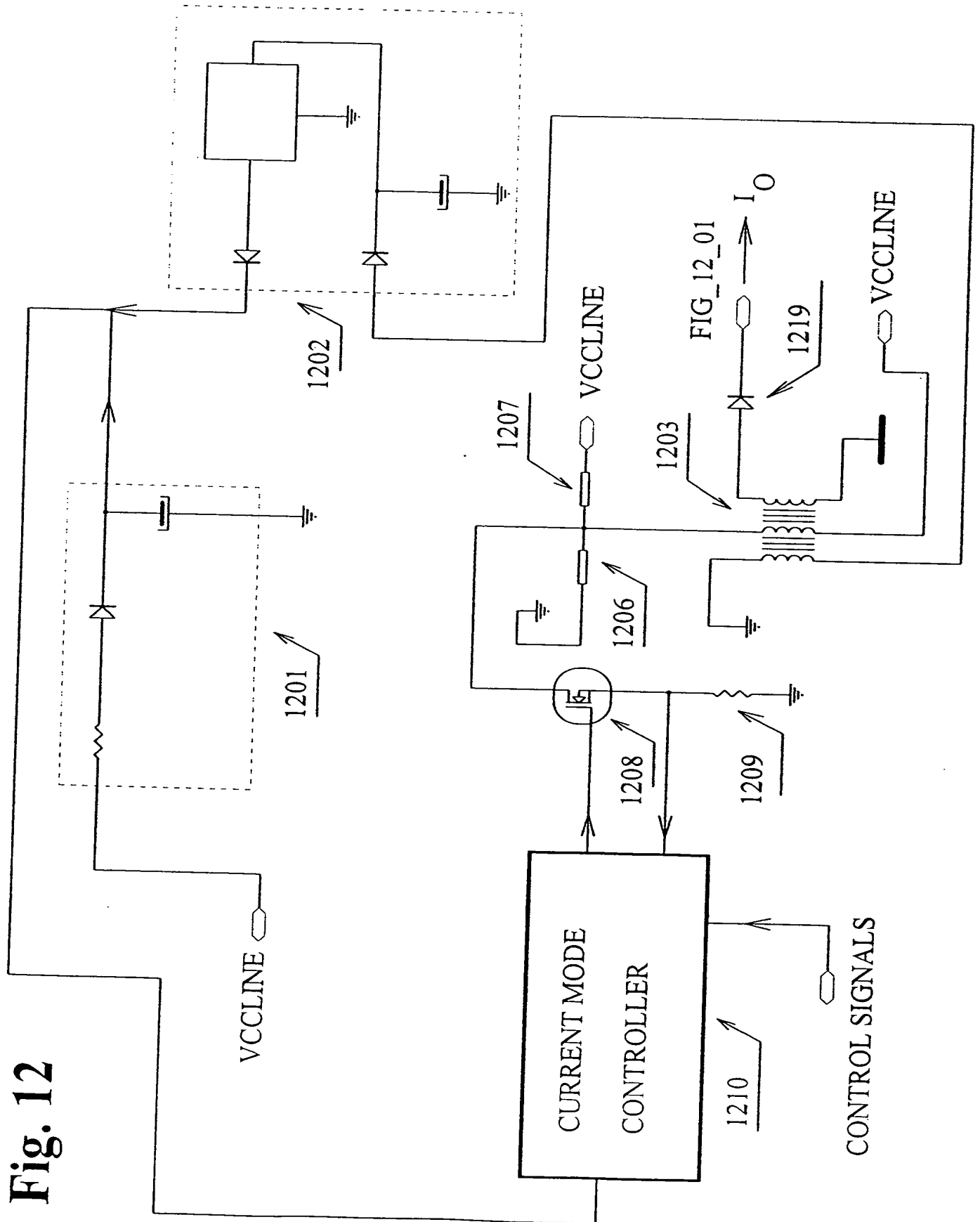


Fig. 12 (CONT'D)

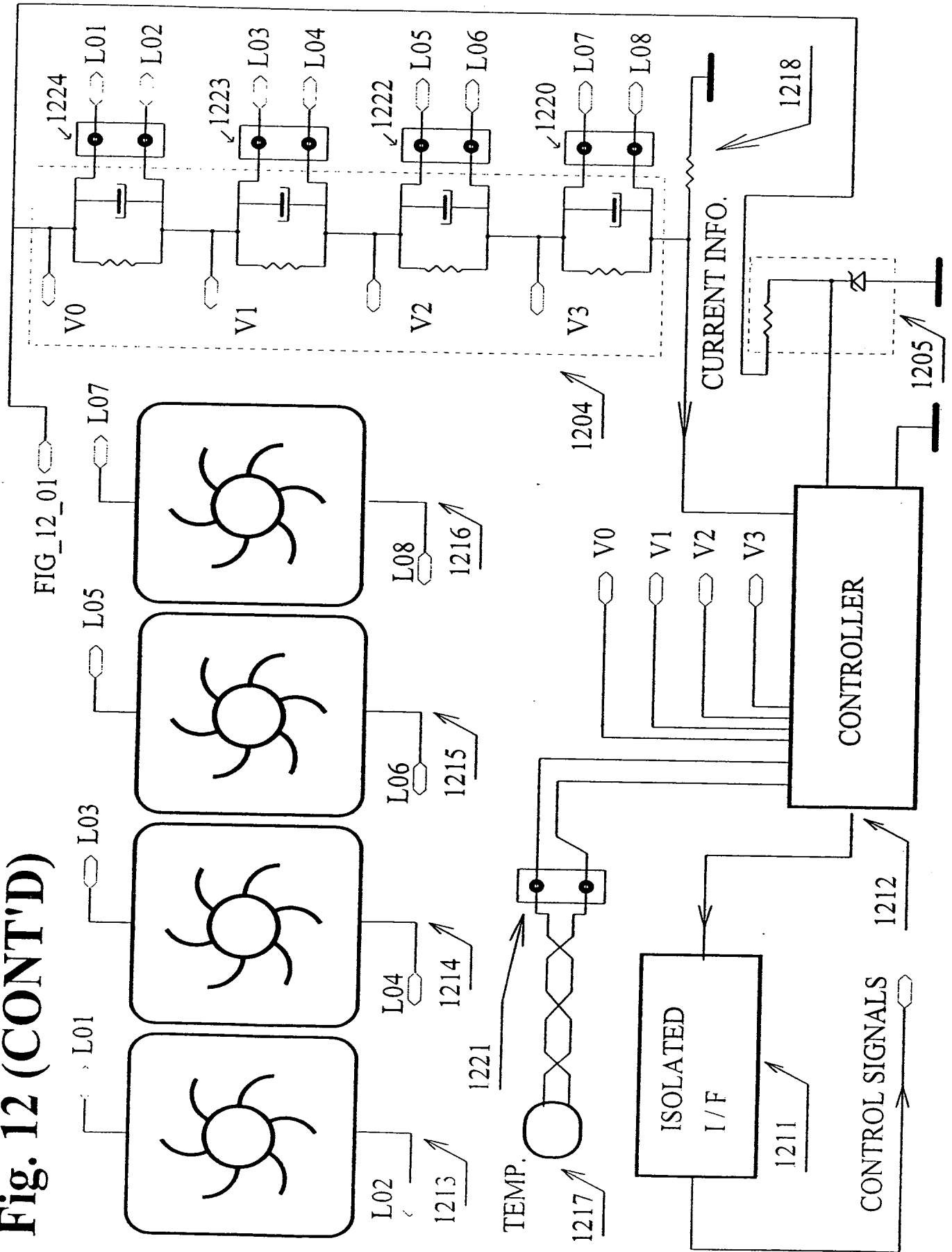


Fig. 13

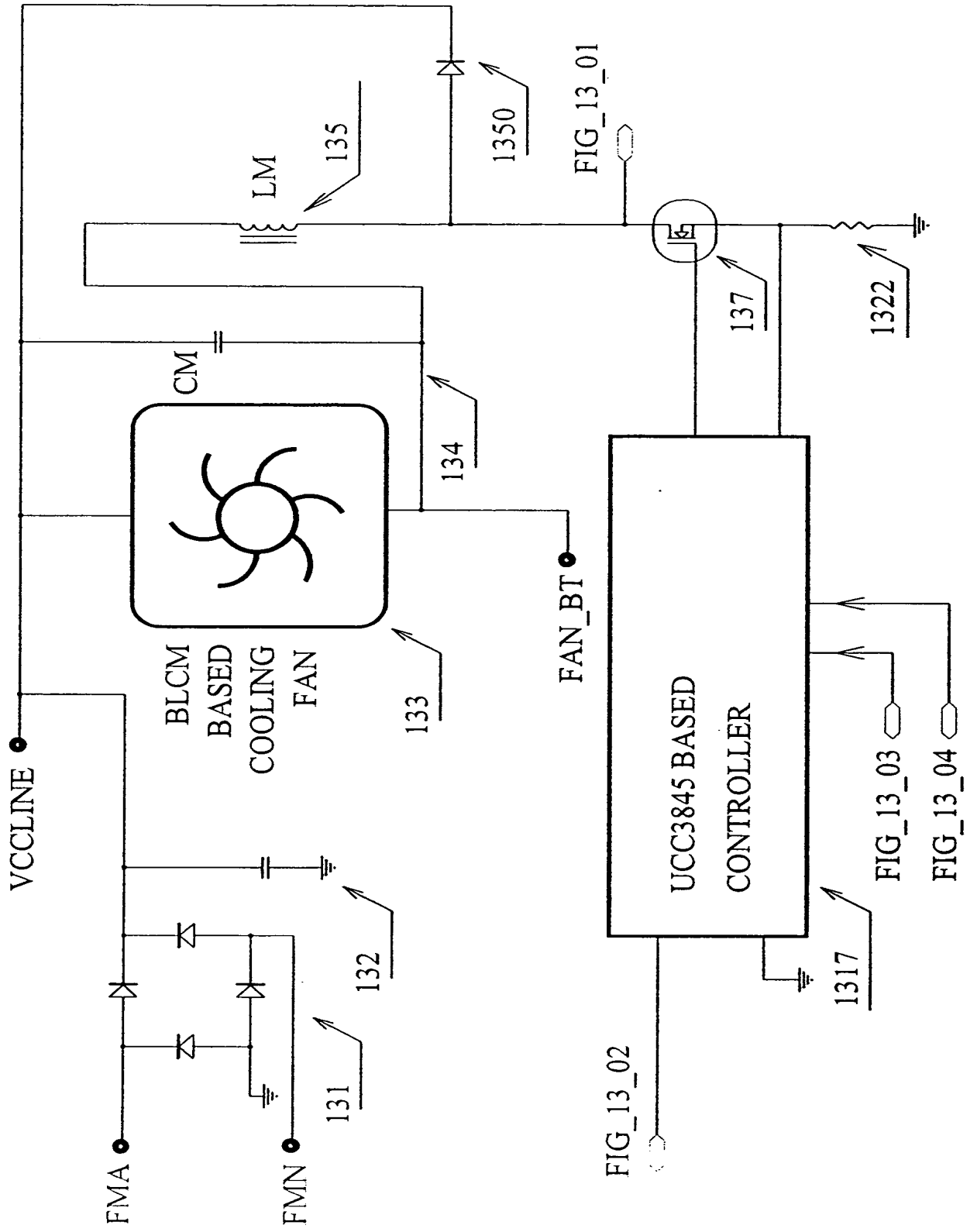
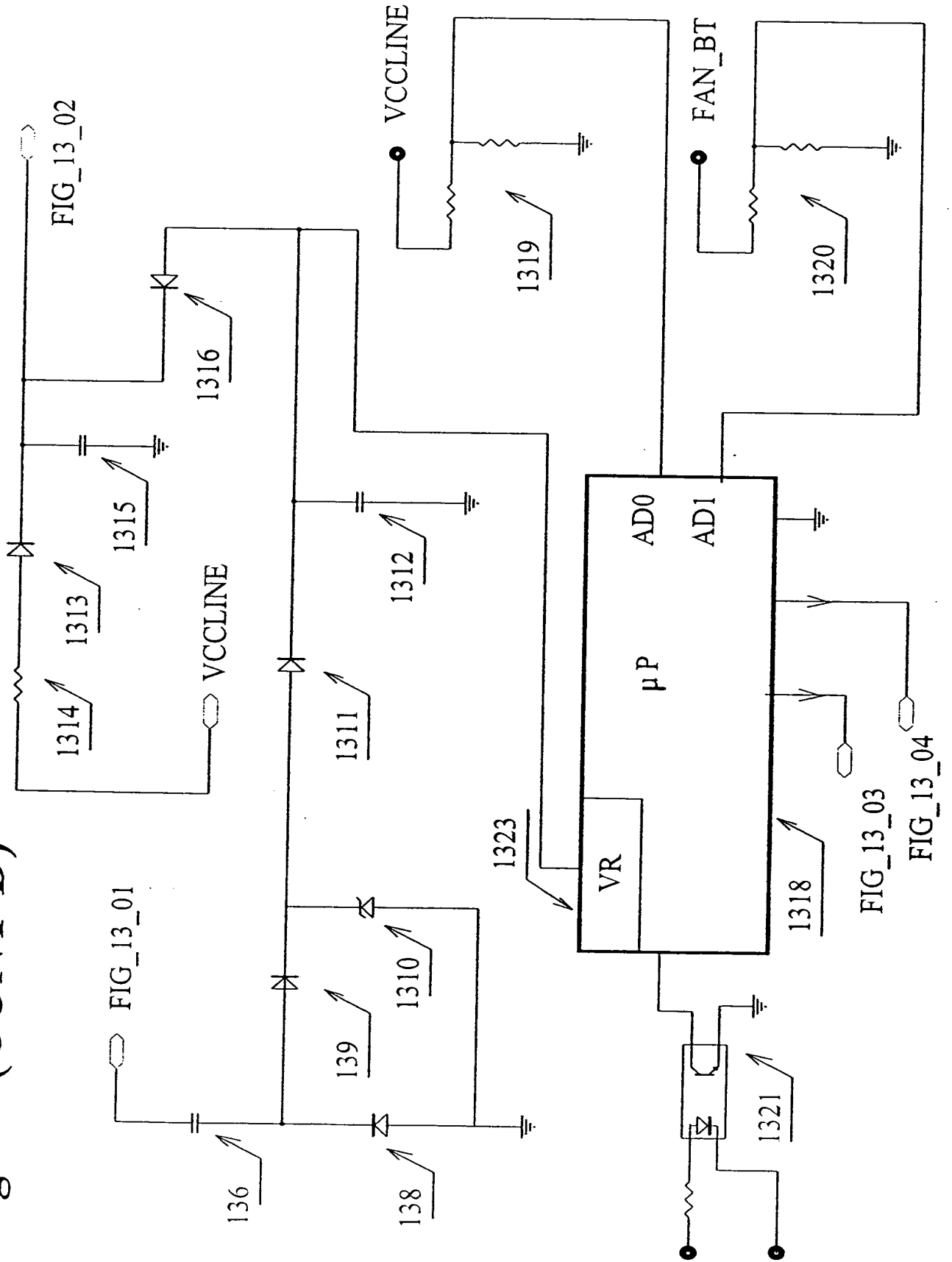
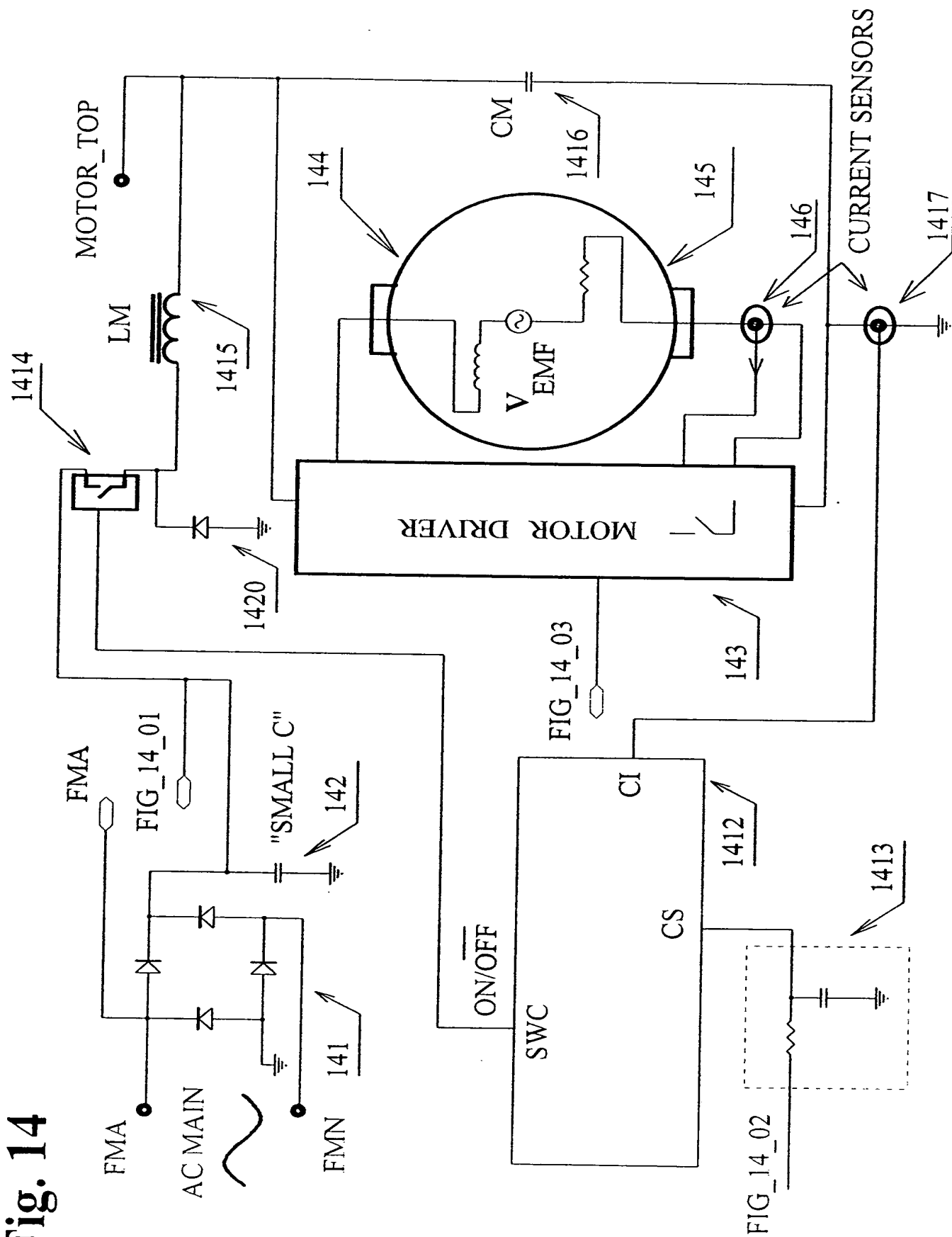




Fig. 13 (CONT'D)





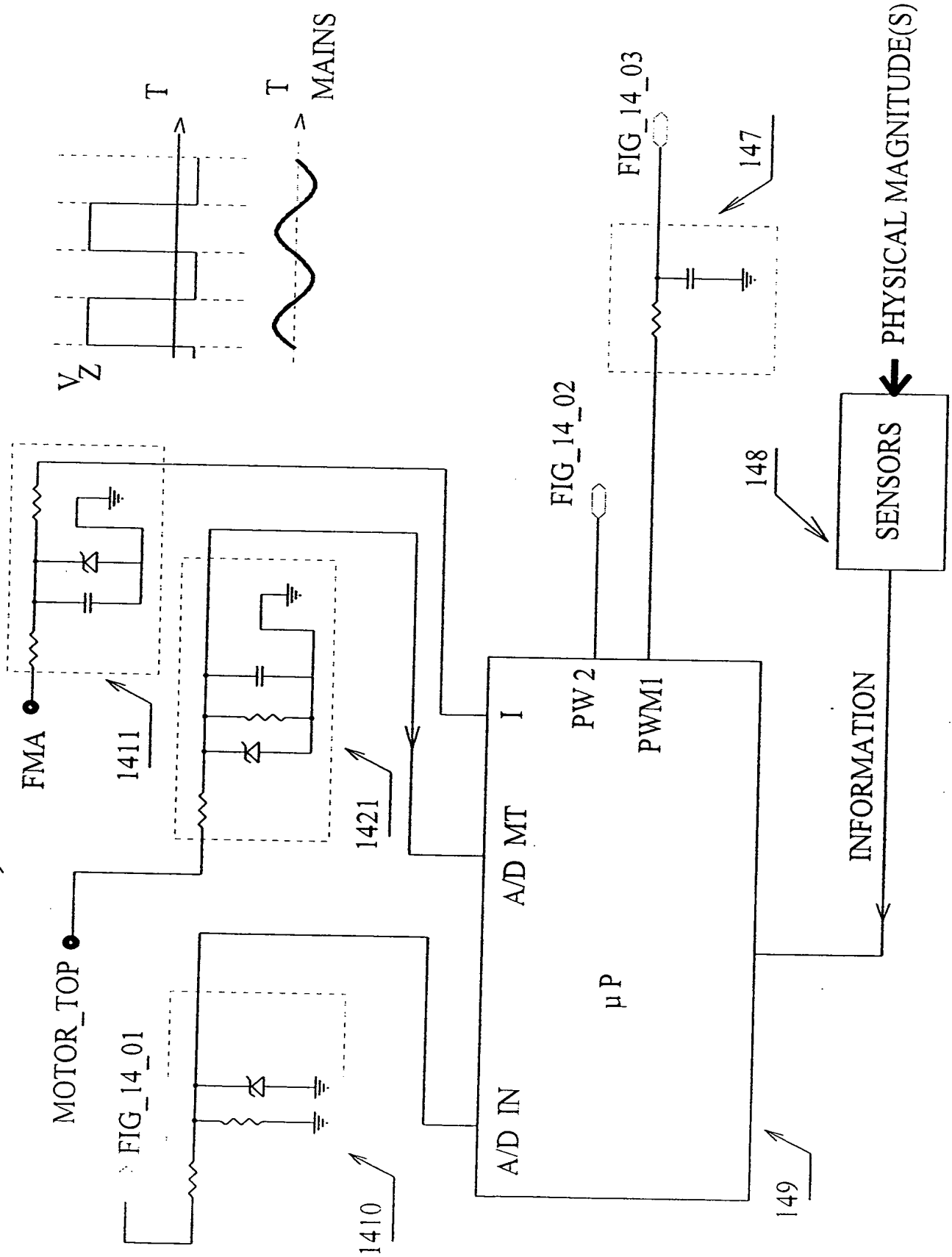
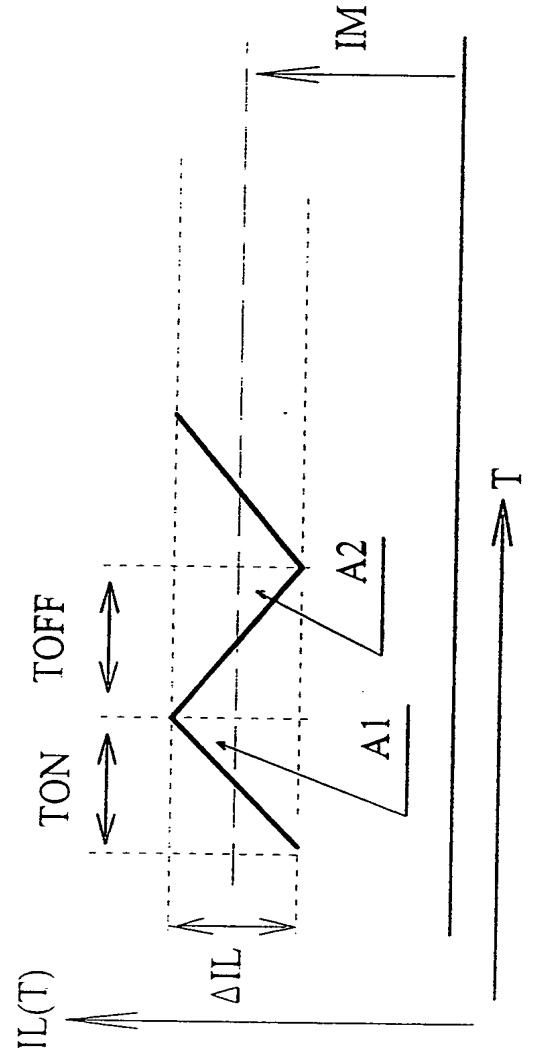
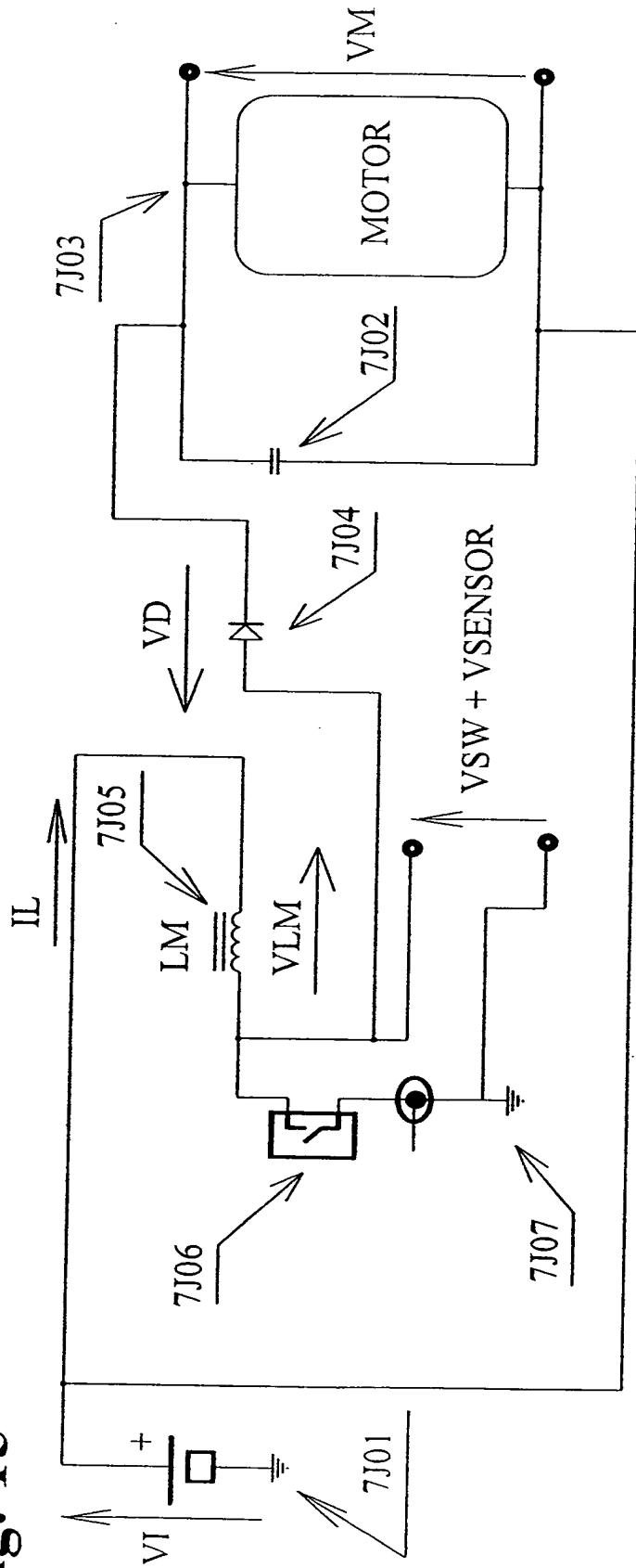


Fig. 15



$$(1501) V_M \cong I_M \cdot R_M + V_{emf}$$

$$(1502) V_{emf} = K_v \cdot \omega_M$$

$$(1503) V_{SW} + V_{SENSOR} \ll V_L$$

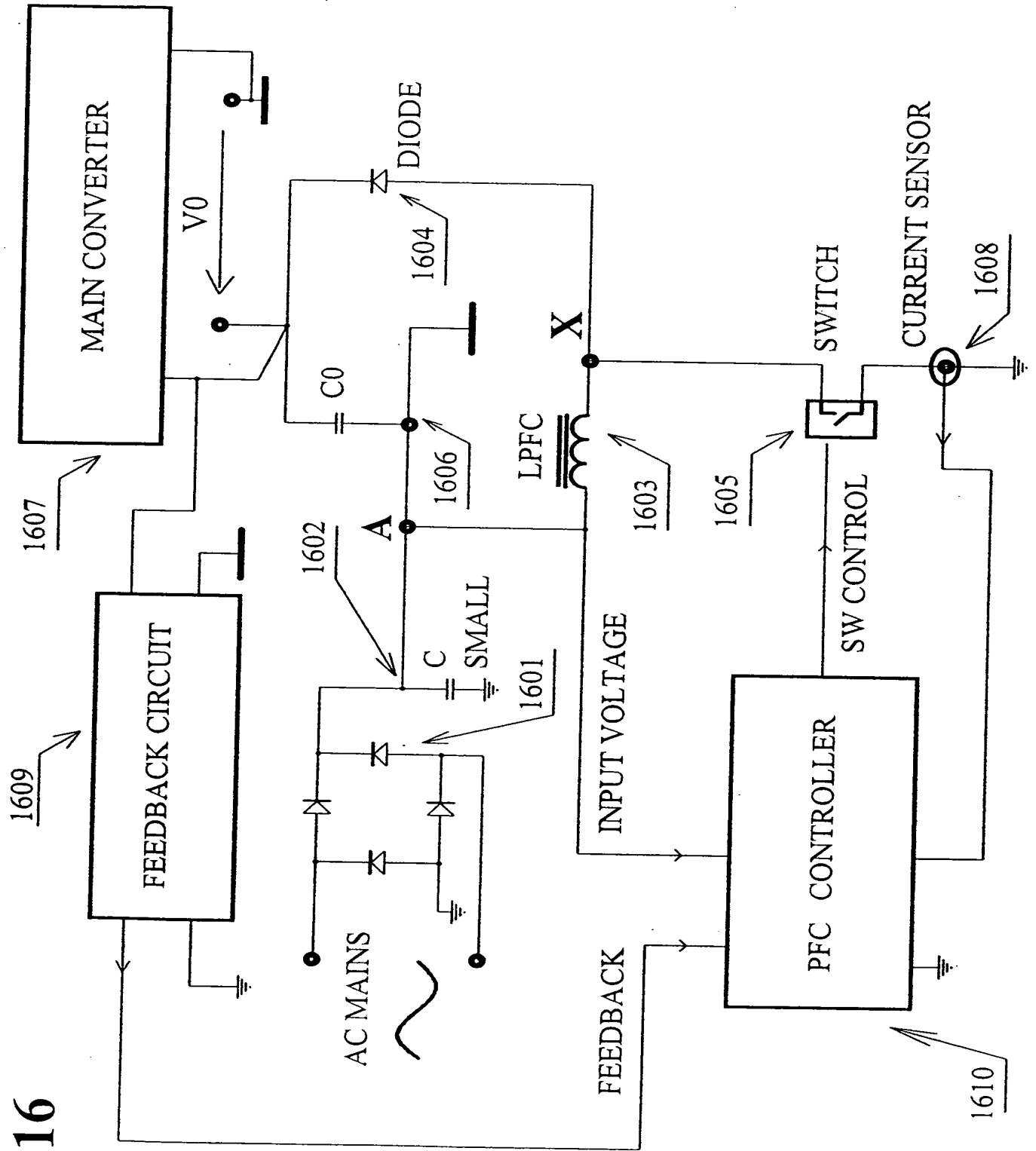
$$(1504) V_D \ll V_M$$

$$(1505) \Delta I_L = \frac{V_I}{L_M} T_{ON} = \frac{V_M}{L_M} T_{OFF}$$

$$(1506) \frac{T_{ON}}{T_{OFF}} = \frac{V_M}{V_I} \quad (\text{FOR CONTINUOUS CONDUCTION MODE})$$

**Fig. 15 (CONT'D)**

Fig. 16



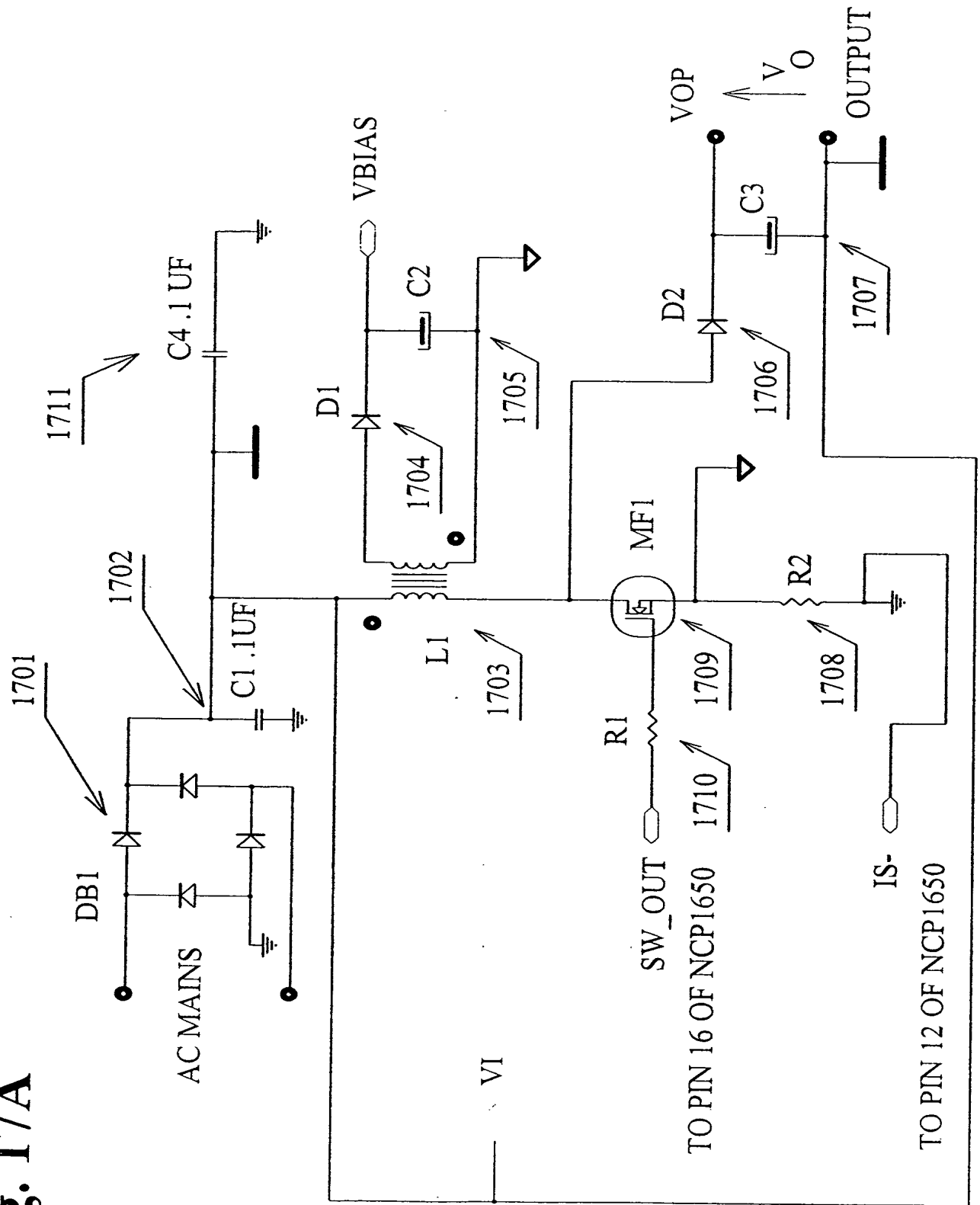


Fig. 17B

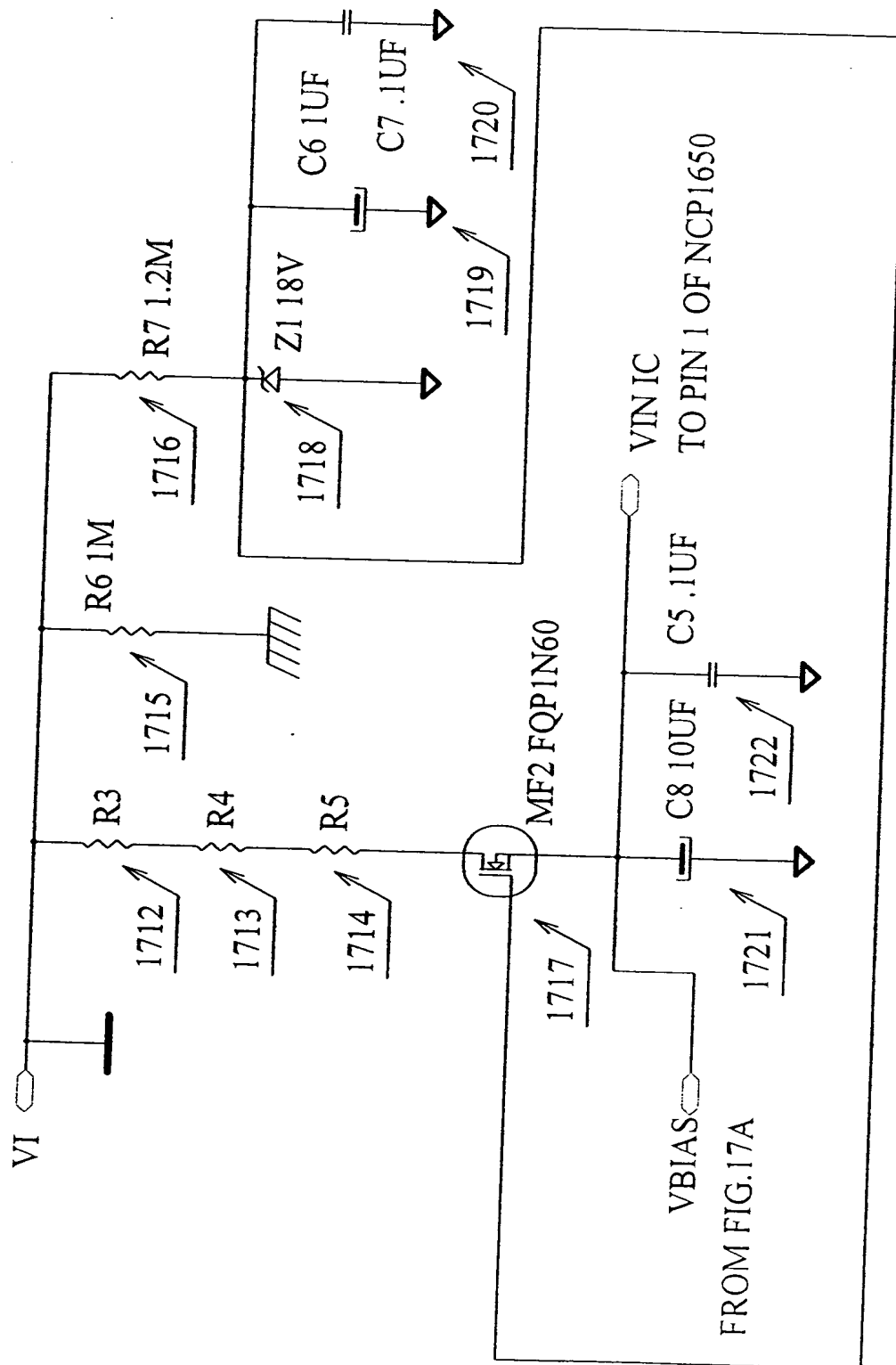




Fig. 17C

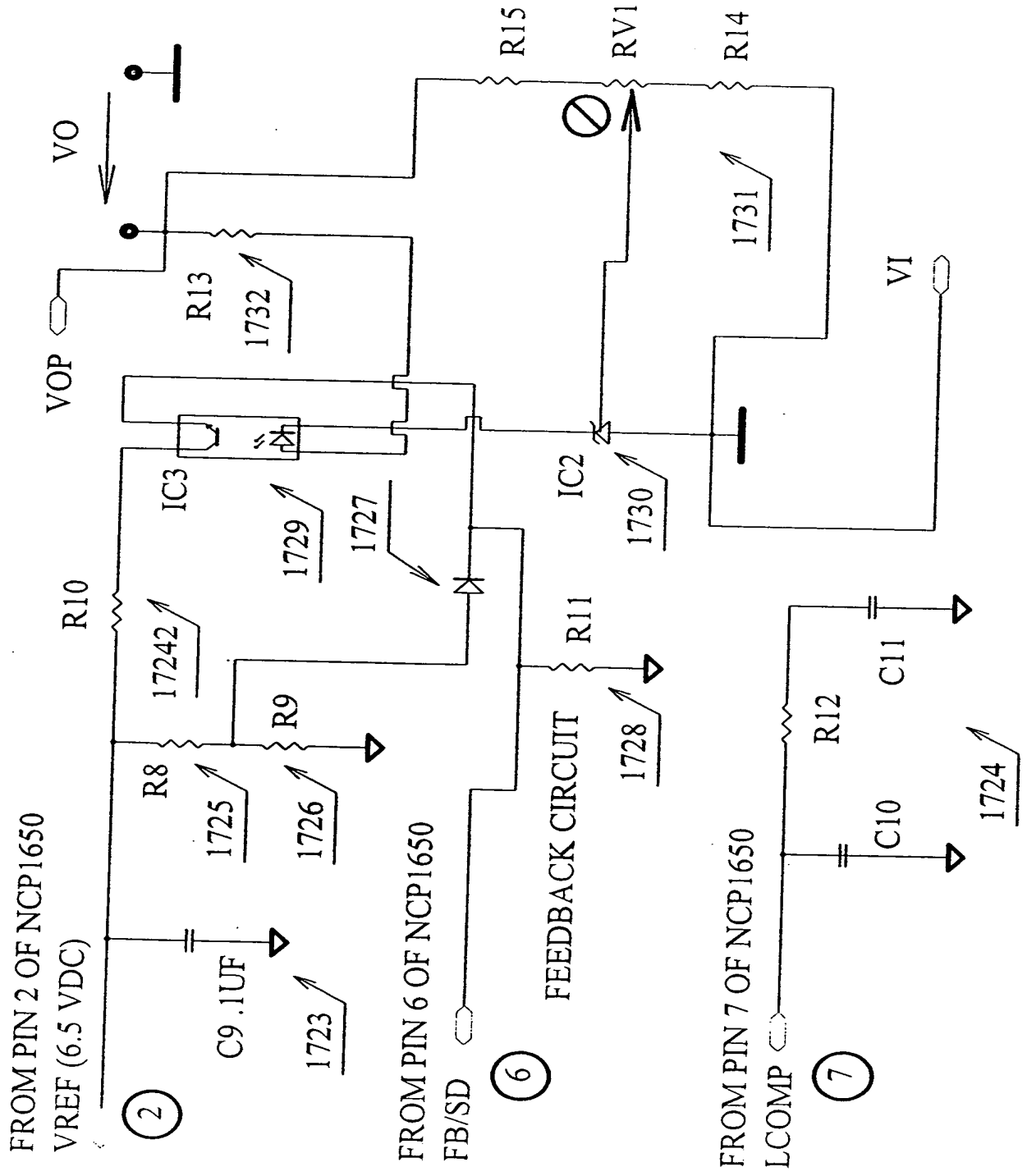


Fig. 17D

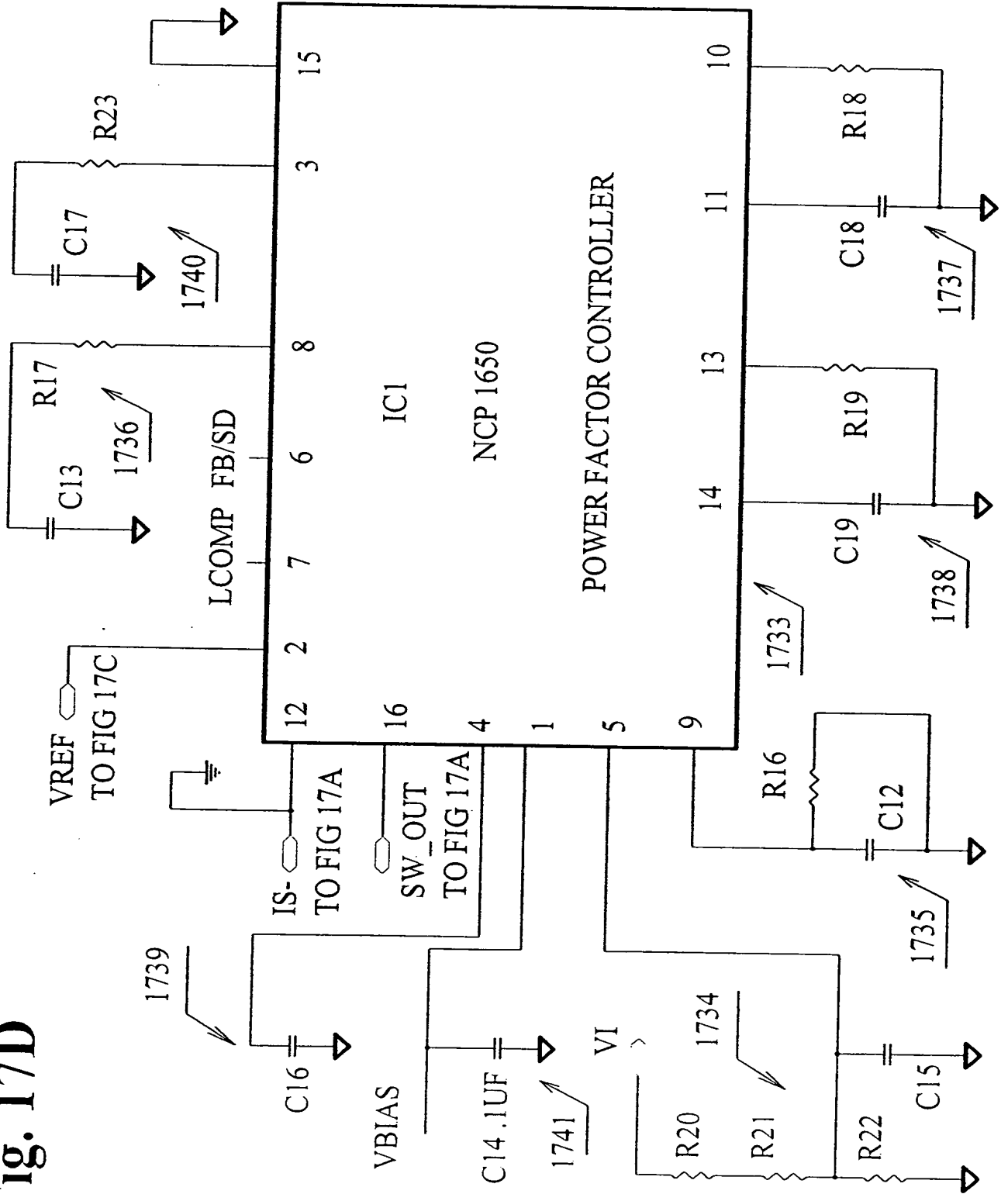


Fig. 17E

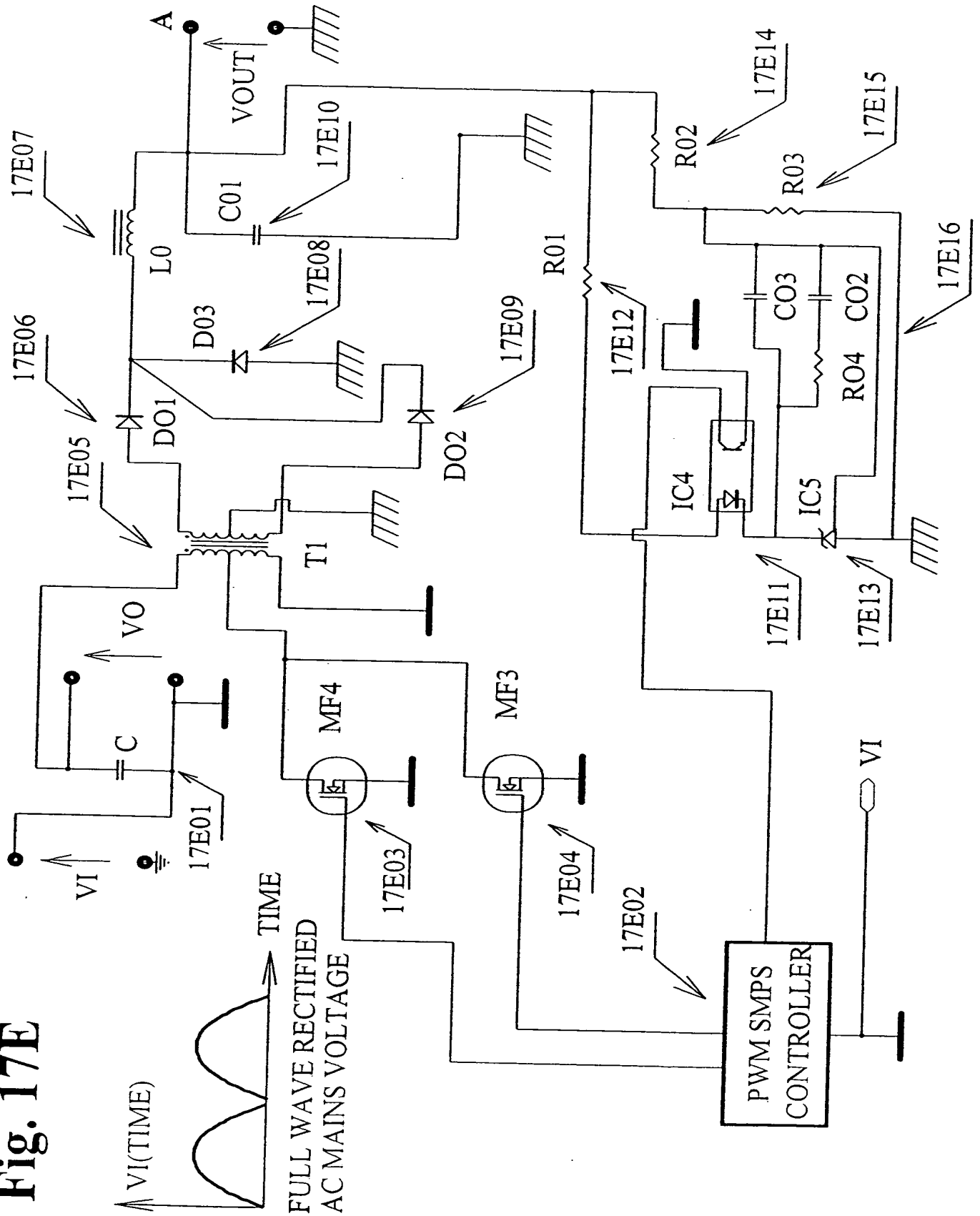


Fig. 17F

